# High-Temperature Differentiability of Lattice Gibbs States by Dobrushin Uniqueness Techniques 

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#### Abstract

We establish conditions for the differentiability, to any order, of the Gibbs states of classical lattice systems with arbitrary compact single-spin space and with interactions in the Dobrushin uniqueness region. The derivatives are expressed as series expansions and are shown to be continuous on the uniqueness region. We also provide a procedure for estimating the size of the derivatives. These results verify a conjecture of L . Gross and extend his results in "Absence of second-order phase transitions in the Dobrushin uniqueness region," Journal of Statistical Physics 25(1):57-72 (1981). The techniques of this paper are based on those employed by Gross.


KEY WORDS: Classical lattice spin systems; Dobrushin uniqueness theorem; differentiability of pressure.

## 1. INTRODUCTION

### 1.1. Discussion of Results

The purpose of this paper is to investigate the extent to which uniqueness of the Gibbs state of a lattice system implies differentiability properties of the pressure. In this section we discuss some of the earlier results in that direction and state our main theorem. In the next we establish background and notation.

In 1968, R. L. Dobrushin ${ }^{(1)}$ demonstrated the uniqueness of Gibbs states for lattice models at high temperature. Specifically, there is a Banach space $\mathscr{P}$ of interactions and a neighborhood $\mathscr{D}$ of the origin in this space, such that to each interaction in $\mathscr{D}$ there corresponds a unique Gibbs state.

[^0]Both the single-spin space and the set of interactions for which Dobrushin's theorem holds are quite general: the spin space is compact metrizable but otherwise arbitrary, translational invariance is not assumed, and the interactions involved are many bodied and have long range [see Eqs. (1.13) and (1.14): $\mathscr{P}=\mathscr{P}_{2}$ ]. B. Simon has shown ${ }^{(2)}$ that Dobrushin's theorem is, in a sense, quite strong: for any $\epsilon>0$, there are interactions which are within a $\mathscr{P}$ distance $\epsilon$ of $\mathscr{D}$ and which possess multiple Gibbs states.

The Dobrushin uniqueness region $\mathscr{D}$ is, in fact, an open neighborhood of the origin in $\mathscr{P}$, as shown by L. Gross. ${ }^{(3)}$ In the translationally invariant context, where the pressure $P(\phi)$ may be defined, this leads immediately to a differentiability result. Namely, the pressure is "Gateaux differentiable in $\mathscr{P}$ directions" at each interaction $\phi$ in $\mathscr{D}$. By this we mean that for each $\phi$ in $\mathscr{D}$ and $\psi$ in $\mathscr{P}$, the function $u \rightarrow P(\phi+u \psi): R^{1} \rightarrow R^{1}$ is differentiable at $u=0$, in which case we write

$$
\partial_{\psi} P(\phi)=\left.\frac{d}{d u} P(\phi+u \psi)\right|_{u=0}
$$

The Gateaux derivative is also called the "functional" or "directional" derivative. Thus we assert that the pressure is differentiable in parameters occurring linearly in the interactions. This follows from the openness of $\mathscr{D}$, the convexity of $P(\phi)$, and the fact that every Gibbs state corresponding to an interaction may be represented by a "tangent functional" to the pressure at that interaction. See Ref. 4, p. 96 for details.

The properties of convex functions lead, moreover, to the fact that the pressure is continuously Gateaux differentiable on $\mathscr{D}$, i.e., that the function $\phi \rightarrow \partial_{\psi} P(\phi)$ is, for fixed $\psi \in \mathscr{P}$, continuous on $\mathscr{D}$. If $\sigma_{\phi}$ is the unique Gibbs state corresponding to $\phi$ in $\mathscr{D}$, the derivative may be written

$$
\partial_{\psi} P(\phi)=\sigma_{\phi}\left(A_{\psi}\right)
$$

where $A_{\psi}$ is an observable (i.e., a continuous function on the space of spin configurations) which is linearly associated with $\psi$ [see (1.17)], and where $\sigma_{\phi}\left(A_{\psi}\right)$ is the expectation of $A_{\psi}$ with respect to the probability measure $\sigma_{\phi}$.

The main result of Gross in Ref. 3 is that the pressure is actually twice continuously Gateaux differentiable on $\mathscr{D}$, in $\mathscr{P}$ directions. This obviates "second-order" phase transitions. He achieved this by showing that there is a dense subspace, $C^{1}$, of observables such that the function $\phi \rightarrow \sigma_{\phi}(f)$ is once continuously Gateaux differentiable on $\mathscr{D}$, for each $f$ in $C^{1}$ (note: if $\psi \in \mathscr{P}$ then $A_{\psi} \in C^{1}$; see Section 2.5).

The main result of this paper (Theorem 5.1) extends that of Gross above as follows: We identify a decreasing sequence $\left[\mathscr{P}_{N}\right]$ of interaction spaces $\left(N \geqslant 2, \mathscr{P}=\mathscr{P}_{2}\right)$ and a decreasing sequence $\left[C^{N}\right], N \geqslant 1$ of dense subspaces of observables such that, for each $f \in C^{N}$, the function $\phi \rightarrow \sigma_{\phi}(f)$ on $\mathscr{D}_{n} \mathscr{P}_{N+1}$ is $N$-times continuously Gateaux differentiable (in $\mathscr{P}_{N+1}$
directions). The techniques used are based on those of Gross, who, in turn, extended the techniques used by Lanford ${ }^{(4)}$ and Vasershtein ${ }^{(5)}$ in their proofs of Dobrushin's uniqueness theorem.

We also provide series expansions for the derivatives (as in Ref. 3 for $N=1$ ) as well as a procedure for estimating their size. These expansions seem to bear no resemblance to the customary series involving truncated correlations. As pointed out in Ref. 3, they may, however, be more useful for computations. However, H. Künsch ${ }^{(6)}$ has recently shown that the first derivative of the Gibbs state is in fact equal to the usual series of covariances.

As a corollary to our main result, it follows that, in the translationally invariant context, the pressure is $N$-times continuously differentiable in $\mathscr{D}_{\cap} \mathscr{P}_{N}, N \geqslant 2$.

We note here that the intersection of all the $\mathscr{P}_{N}$ spaces is still quite large. It contains, for example, all finite-range interactions. For a sufficient condition for interactions to lie in $\mathscr{D}$, see (1.18).

There are a number of problems immediately related to our main result which remain undecided. Some of these ought to succumb to the methods we have used. Firstly, it remains to investigate whether the pressure is not $N$ times continuously differentiable on $\mathscr{D}_{n} \mathscr{P}_{N-1}$. Secondly, we have not been able to establish the equality between the derivatives and the corresponding series of truncated correlations for arbitrary $N$. Thirdly, in Ref. 7 Gross demonstrated that the averaged two-point truncated correlations decay in the same weighted summability sense as the potential, when the latter lies in a suitable open subset of $\mathscr{D}$. (Improved estimates have recently been obtained by H. Künsch ${ }^{(6)}$ and H. Föllmer. ${ }^{(8)}$ ) We conjecture that a similar result holds in $\mathscr{T}_{\cap} \mathscr{P}_{N}, N=3,4, \ldots$. (For an extension of the main results of Ref. 7 in the direction of continuum systems see Ref. 9, which also provides an extension of Dobrushin's theorem to this situation.) Finally, we have not identified the exact domain of real analyticity of the pressure.

A number of results on complex analyticity of the pressure are extant in the literature. Using Dobrushin uniqueness techniques, R. B. Israel ${ }^{(10)}$ established complex analyticity, at high temperature, in any finite number of directions. The real part of his space of (complex) interactions is contained in the intersection of our $\mathscr{P}_{N}$, but from the point of view of range and many-bodiedness is still quite general. Results on analyticity not using Dobrushin techniques usually exert more stringent restrictions, for example, on the cardinality of the single-spin space. G. Gallavotti and S. Miracle-Sole ${ }^{(11)}$ have demonstrated analyticity at high temperature (or low activity) for a wider class of potentials than ours (the space $\mathscr{P}_{1}$ of "supersummable" interactions), though their single-spin space is restricted
to two points. Their techniques do not seem to admit generalization to infinite cardinality. Links between high-temperature correlation functions and analyticity have been explored by Duneau, Iagolnitzer, and Souillard ${ }^{(12-15)}$ and Holley and Stroock. ${ }^{(16)}$

### 1.2. The Mathematical Setting

General references for this section are Refs. 17 and 18.
Let $L$ be a countably infinite set with some fixed enumeration $\left\{a_{i}\right\}$. Let $X$ be a compact metrizable space and associate with each $a \in L$ a copy $X_{a}$ of $X$. For any $\Lambda \subset L$, define $\Omega_{\Lambda}=X_{a \in \Lambda} X_{a}$ and $\Omega=\Omega_{L} . \Omega_{\Lambda}$ is the space of configurations inside $\Lambda$. We shall call a function in $C(\Omega)$ that depends upon only finitely many coordinates a (continuous) cylinder function. Since $\Omega$ is compact, the cylinder functions are dense in $C(\Omega)$.

In all that follows, the notation " $\Lambda \subset L$ " will be taken to refer to a finite subset of $\Lambda$ of $L$. Also, we shall write " $s_{p}$ " for the $\left(a_{p}\right)$ th coordinate of $s \in \Omega$, and often write " $j \in L$," " $\Lambda \cup j$," etc. instead of $a_{j} \in L, \Lambda_{\cup}\left\{a_{j}\right\}$, respectively. We shall sometimes speak of a cylinder function as being "based upon $p$ " if it is independent of all $j$ th coordinates with $j>p$.

Let $M=\left\{\mu_{j}(d x \mid s)\right\}_{j \in L, s \in \Omega}$ be a system of "conditional measures," i.e.,
(i) $\mu_{j}(\cdot \mid s)$ is a probability measure on $X_{j}$, for each $s \in \Omega$.
(ii) $\mu_{j}(\cdot \mid s)$ is independent of $s_{j}$.
(iii) For any continuous function $g$ on $X_{j}, \int_{X_{j}} \mu_{j}(d x \mid s) g(x)$ is in $C(\Omega)$. (The $\mu_{j}$ will arise as single-site Gibbs ensembles.) Following Lanford, define the operators $\zeta_{j}$ on $C(\Omega)$ by

$$
\begin{equation*}
\zeta_{j} f(s)=\int_{X_{j}} \mu_{j}(d x \mid s) f\left(x_{\vee} \hat{s}\right) \tag{1.1}
\end{equation*}
$$

where $\hat{s}=\left.s\right|_{L-j}$ and $x_{\vee} \hat{s}$ is the configuration obtained from $s$ by replacing its $j$ th component with $x$. That $\zeta_{j} f$ is a continuous function follows from (iii) above and (ii) shows that it is independent of $s_{j}$. It is a contraction (i.e., $\left|\zeta_{j} f\right|_{\infty} \leqslant|f|_{\infty}$, where $|\cdot|_{\infty}$ is the supremum norm $)$ since $\mu_{j}(\cdot \mid s)$ is a probability measure.

For $k \leqslant p<\infty$ define

$$
\begin{equation*}
T_{k, p} f=\zeta_{k} \cdot \zeta_{k+1} \cdots \xi_{p} f \tag{1.2}
\end{equation*}
$$

As a product of contractions, $T_{k, p}$ is a contraction itself. But note that the function $T_{k, p} f(s)$ is, in general, only independent of $s_{k}$. The function $\zeta_{p} f$, for example, is independent of $s_{p}$, but applying $\zeta_{p-1}$ to it introduces a dependence on $s_{p}$ by virtue of the dependence of $\mu_{p-1}(\cdot \mid s)$ on $s_{p}$.

Consider the sequence $\left\{T_{1, p} f\right\}_{p=1}^{\infty}$, for fixed $f \in C(\Omega)$. If $f$ is a cylinder function based on $q$, then it is clear from (1.1) that $\zeta_{j} f=f$ whenever $j>q$.

Thus the sequence $\left\{T_{1, p} f\right\}$ becomes stationary as soon as $p>q$ (in which case $T_{1, p} f=T_{1, q} f$ ) and we may define $T f=\lim _{p \rightarrow \infty} T_{1, p} f$ [where the limit is in the uniform, or $C(\Omega)$, norm]. Since the $T_{1, p}$ are uniformly bounded and the cylinder functions are dense in $C(\Omega)$, it follows that the limit $T f$ exists for all $f \in C(\Omega)$. The same arguments hold for $\left\{T_{k, p} f\right\}_{p=1}^{\infty}$, in which instance we write $T_{k, \infty} f=\operatorname{Lim}_{p \rightarrow \infty} T_{k, p} f$.

Define, for $k \in L$,

$$
\begin{equation*}
R_{k, j}=\frac{1}{2} \sup \left\{\left\|\mu_{j}(\cdot \mid s)-\mu_{j}(\cdot \mid t)\right\|: s=t \text { off } k\right\} \tag{1.3}
\end{equation*}
$$

where the norm is that of total variation. Let

$$
\begin{equation*}
\alpha_{1}=\sup _{j} \sum_{k} R_{k, j} \tag{1.4}
\end{equation*}
$$

We are now in a position to state the following:
Dobrushin's Uniqueness Theorem. If $\alpha_{1}<1$, there is at most one probability measure $\sigma$ on the configuration space $\Omega$ such that $\sigma\left(\zeta_{j} f\right)=\sigma(f)$ for all $j \in L$ and $f \in C(\Omega)$.

For a proof, see Corollary 3.3 of Ref. 7. Vasershtein's method of proof ${ }^{(5)}$ gives us a neat formula for constructing the Gibbs state, namely, if $\sigma$ is a measure as above,

$$
\begin{equation*}
\sigma(f)=\lim _{n \rightarrow \infty} T^{n} f, \quad f \in C(\Omega) \tag{1.5}
\end{equation*}
$$

That is, $T^{n} f(s)$ tends, uniformly in $s$, to the constant $\sigma(f)$.
Crucial to the method of proof is the identification of a dense subset $C^{1}$ of functions on which (1.5) is first established. This space is defined as follows:

For each $j \in L$ and $f \in C(\Omega)$, define

$$
\begin{gather*}
D_{j}(f)=\sup \{|f(s)-f(t)|: s=t \text { off } j\}  \tag{1.6}\\
|f|_{1}=\sum_{j} D_{j}(f)
\end{gather*}
$$

Then $C^{1}=\left\{f \in C(\Omega):|f|_{1}<\infty\right\}$. Every cylinder function is contained in $C^{1}$, so that $C^{1}$ is dense in $C(\Omega)$. The proof of Dobrushin's theorem we use relies on the fact that for $\alpha_{1}<1,\left|T^{n} f\right|_{1} \leqslant \alpha_{1}|f|_{1}$.

In statistical mechanics we define the system of conditional measures by means of an interaction. This is a continuous function $\phi$ on $\bigcup_{\Lambda \subset L} \Omega_{\Lambda}$ (again, the $\Lambda$ are finite) whose value on $\Omega_{\Lambda}$ represents the many-body interaction energy between the spins located in $\Lambda$. The many-body energy is denoted $\phi(s \mid \Lambda)$ (for a configuration $s$ in $\Omega$ ) and we require that $\phi(s \mid \varnothing)=0$.

Thus the energy of any configuration inside $\Gamma \subset L$ is given by $\bigcup_{\Gamma}(s)$ $=\sum_{\Lambda \subset \Gamma \phi}(s \mid \Lambda)$. Evidently the contribution of any single site $j$ in the lattice
to the total interaction energy of some configuration $s$ in $\Omega$ is given by

$$
\begin{equation*}
-k_{\phi, j}(s)=\sum_{\substack{\Lambda \subset L \\ j \in \Lambda}} \phi(s \mid \Lambda) \tag{1.7}
\end{equation*}
$$

(assuming the series converges). We require that

$$
\begin{equation*}
\|\phi\|_{1}=\sup _{j \in L} \sum_{\substack{\wedge \subset L \\ j \in \Lambda}} \sup _{\substack{ \\\hline \in \Omega}}|\phi(s \mid \Lambda)|<\infty \tag{1.8}
\end{equation*}
$$

so that $k_{\phi, j}(s)$ is finite and, by uniform convergence, is a continuous function on $\Omega$. Let $\nu$ be some bounded real Borel measure (the "a priori single-spin" measure) and define the single-spin Gibbs ensemble at $j$ (with "boundary conditions" $\hat{s}=\left.s\right|_{L-j}$ ) by

$$
\begin{equation*}
\mu_{j}^{\phi}(d x \mid s)=Z_{j}^{\phi}(s)^{-1} \exp \left[k_{\phi, j}\left(x_{\vee} \hat{s}\right)\right] \nu(d x) \tag{1.9}
\end{equation*}
$$

where $Z_{j}^{\phi}(s)$ is the normalization. It is easily checked that $M=\left\{\mu_{j}^{\phi}\right\}$ is a system of conditional measures. In this case we write $\zeta_{j}^{\phi}$ in place of $\zeta_{j}, T_{\phi, k, p}$ for $T_{k, p}$ and $\alpha_{1}(\phi)$ for $\alpha_{1}$.

We proceed now to define Gibbs states corresponding to $\phi$. Put

$$
\begin{equation*}
W_{\Lambda}^{\phi}(s)=\sum_{\substack{\Gamma \subset L \\ \Gamma_{n} \Lambda \neq \varnothing}} \phi(s \mid \Gamma) \tag{1.10}
\end{equation*}
$$

(we have $\left|W_{\Lambda}^{\phi}\right| \leqslant|\Lambda|\|\phi\|_{1}$, where $|\Lambda|$ is the cardinality of $\Lambda$ ). $W_{\Lambda}(s)$ is to be interpreted as the energy of the configuration $\left.s\right|_{\Lambda}$ inside $\Lambda$, plus the energy of interaction between $\left.s\right|_{\Lambda}$ and the "boundary" spins $\left.s\right|_{L-\Lambda}$ outside $\Lambda$. Write

$$
\begin{equation*}
\zeta_{\Lambda}^{\phi} f(s)=Z_{\Lambda}(s)^{-1} \int_{\Omega_{\Lambda}} \nu^{\Lambda}(d x) e^{-W q\left(x x^{\vee}\right)} f\left(x_{\vee} \hat{s}\right) \tag{1.11}
\end{equation*}
$$

where now $\hat{s}=\left.s\right|_{L=\Lambda}$ and $v^{\Lambda}=\otimes_{\Lambda} \nu$. A Gibbs state corresponding to $\phi$ with $\|\phi\|_{1}<\infty$ is any probability measure $\sigma$ on $\Omega$ satisfying

$$
\begin{equation*}
\sigma\left(\zeta_{\Lambda}^{\phi} f\right)=\sigma(f) \quad \text { for all } \quad \Lambda \subset L, \quad f \in C(\Omega) \tag{1.12}
\end{equation*}
$$

That is, the Gibbs ensemble $\zeta_{i}^{\phi}$ is just the conditional expectation corresponding to $\sigma$, given the configuration of spins outside $\Lambda$. If we think of the $\zeta_{\Lambda}$ as probability measures on $C\left(\Omega_{\Lambda}\right)$, then it is easily seen by a compactness argument that the set of weak limits of these measures as $\Lambda \uparrow L$ is nonempty and consists of Gibbs states. Dobrushin's theorem asserts that if $\alpha_{1}(\phi)<1$ there exists a unique Gibbs state.

Following Gross we now define the spaces $\mathscr{P}_{N}$ alluded to in Section 1.1. For any integer $N$ and interaction $\phi$, put

$$
\begin{equation*}
\|\phi\|_{N}=\sum_{\substack{\Lambda \subset L \\ j \in \Lambda}}|\Lambda|^{N-1} \sup _{s \in \Omega}|\phi(s \mid \Lambda)| \tag{1.13}
\end{equation*}
$$

and define

$$
\begin{equation*}
\mathscr{P}_{N}=\left\{\phi:\|\phi\|_{N}<\infty\right\} \quad \text { and } \quad \mathscr{D}=\left\{\phi \in P_{2}: \alpha_{1}(\phi)<1\right\} \tag{1.14}
\end{equation*}
$$

(we choose $\mathscr{P}_{2}$ rather than $\mathscr{P}_{1}$ because $\mathscr{D}$ is not open in $\mathscr{P}_{1}$ ). If $L=Z^{d}$, the corresponding spaces of translationally covariant interactions are denoted by $\hat{\mathscr{P}}_{N}$. Each $\mathscr{P}_{N}$ is a separable Banach space.

An aside: It is possible to define the pressure on $\hat{\mathscr{P}}_{0}$. However this space is quite pathological from a physical viewpoint. For example, M. E. Fisher constructed in Ref. 19 models whose interactions lie in $\hat{\mathscr{P}}_{0}$ and whose pressure is discontinuous as a function of density, implied by linear segments on the $P-\mu$ isotherms. This phenomenon has never been observed in the laboratory and it is known ${ }^{(20,21)}$ that such a lack of strict convexity cannot obtain in $\mathscr{P}_{1}$ (and therefore in $\mathscr{P}_{N}, N \geqslant 1$ ). In Fisher's example two physically distinct interactions share the same Gibbs state. Indeed, in Ref. 22 Israel found that there exists a dense set of interactions in $\hat{\mathscr{P}}_{0}$, each of which has uncountably many Gibbs states. We shall not dwell upon $\hat{\mathscr{F}}_{0}$ any further.

Let us now define the pressure on $\hat{\mathscr{P}}_{1}$ with $L=Z^{d}$. With $W_{i}^{\phi}$ as in (1.10), put for each $s \in \Omega$

$$
\begin{equation*}
P_{\Lambda}(\phi)(s)=\frac{1}{|\Lambda|} \log \int_{\Omega_{\Lambda}} \nu^{\Lambda}(d x) \exp \left[-W_{\Lambda}^{\phi}\left(x_{\vee} \hat{s}\right)\right] \tag{1.15}
\end{equation*}
$$

The "thermodynamic limit" of $P_{\Lambda}(\phi)(s)$ as $\Lambda$ approaches $Z^{d}$ through a sequence of sets (with suitably tame surfaces) exists uniformly in, and independent of, the boundary conditions $s$. This limit is the pressure $P(\phi)$. The $P_{A}$ and $P$ are convex, continuous functions on $\hat{\mathscr{P}}_{1}$ (and therefore on $\hat{\mathscr{P}}_{N}, N \geqslant 1$ ). In fact, they are Lip 1 functions:

$$
\begin{equation*}
\left|P(\phi)-P\left(\phi^{\prime}\right)\right| \leqslant\left\|\phi-\phi^{\prime}\right\|_{1} \leqslant\left\|\varphi-\varphi^{\prime}\right\|_{N}, \quad N \geqslant 1 \tag{1.16}
\end{equation*}
$$

In Section 1.1 we alluded to the fact that a unique Gibbs state $\sigma$ corresponding to the interaction $\phi$ is representable as a tangent functional to the pressure. By this we mean that, with 0 the origin of $Z^{d}$,

$$
\begin{equation*}
P(\phi+\psi) \geqslant P(\phi)+\sigma\left(A_{\psi}\right), \quad \text { where } \quad A_{\psi}(s)=-\sum_{\Lambda: 0 \in \Lambda}|\Lambda|^{-1} \psi(s \mid \Lambda) \tag{1.17}
\end{equation*}
$$

A sufficient condition for $\phi$ to be in $\mathscr{D}$ was given by B. Simon in Ref. 2 namely,

$$
\begin{equation*}
\left.\sup _{j} \sum_{\Lambda: j \in \Lambda}(|\Lambda|-1) \phi(\cdot \mid \Lambda)\right|_{\infty}<1 \tag{1.18}
\end{equation*}
$$

For example, if $X=S^{n-1}$, the unit sphere in $R^{n}$, and $\phi$ is a purely pair interaction, with $\phi(s \mid\{a, b\})=-J_{a, b} \mathbf{s}_{a} \mathbf{s}_{b}$ (so that we have the " $n$-vector"
model) and $\sum_{b}\left|J_{0, b}\right|<1$, there is a unique Gibbs state and the pressure is infinitely differentiable. In general, interactions in $\mathscr{P}_{1}$ satisfying (1.18) but having vanishing $M$-body interactions for all $M$ larger than some number will be in $\mathscr{D}_{\cap} \mathscr{P}_{N}$ for all $N$ and therefore possess infinitely differentiable Gibbs states.

We proceed now to informally differentiate the Vasershtein equation (1.5) for the Gibbs state expectation. We write

$$
\begin{gather*}
\partial_{\psi} T_{\phi} f=\left.\frac{d}{d u} T_{\phi+u \psi} f\right|_{u=0} \\
\partial_{\psi_{1, \psi}} T_{\phi} f=\left.\frac{d}{d u}\left(\partial_{\psi} T\right)_{\phi+u \psi_{1}} f\right|_{u=0} \tag{1.19}
\end{gather*}
$$

and so on. Since

$$
\begin{equation*}
T_{\phi+u \psi} f-T_{\phi}^{n} f=\sum_{k=1}^{n} T_{\phi+u \psi}^{n-k} \cdot\left(T_{\phi+u \psi}-T_{\phi}\right) T_{\phi}^{k-1} f \tag{1.20}
\end{equation*}
$$

we have

$$
\begin{equation*}
\partial_{\psi} \sigma_{\phi}(f)=\lim _{n \rightarrow \infty} \sum_{k=1}^{n} T_{\phi}^{n-k} \cdot \partial_{\psi} T_{\phi} \cdot T_{\phi}^{k-1} f \tag{1.21}
\end{equation*}
$$

Brazenly performing this limit and using (1.5) again,

$$
\begin{equation*}
\partial_{\psi} \sigma_{\phi}(f)=\sum_{k=1}^{\infty} \sigma_{\phi}\left(\partial_{\psi} T_{\phi} \cdot T_{\phi}^{k-1} f\right) \tag{1.22}
\end{equation*}
$$

This formula was rigorously established by Gross ${ }^{(3)}$ under the conditions that $\phi \in \mathscr{D}, \psi \in \mathscr{P}_{2}$ and $f \in C^{1}$. He also pointed out that it can be written in the form

$$
\begin{equation*}
\partial_{\psi} \sigma_{\phi}(f)=\sigma_{\phi}\left(\partial_{\psi} T_{\phi} \cdot\left(I-T_{\phi}\right)^{-1}[f]\right) \tag{1.23}
\end{equation*}
$$

Here $[f]$ is the equivalence class $\{f+c: c$ a constant function $\}$. The $C^{1}$ seminorm defined in (1.6) has as its kernel the constant functions. Thus $\tilde{C}^{1}=\left(C^{1} /\right.$ constants $)$ is a Banach space; since $I-T_{\phi}$ annihilates constants it may be interpreted as an operator on $\tilde{C}^{I}$, with inverse given by

$$
\begin{equation*}
S_{\phi}[f]=\left(I-T_{\phi}\right)^{-1}[f]=\sum_{k=1}^{\infty}\left[T_{\phi}^{k-1} f\right] \tag{1.24}
\end{equation*}
$$

Similarly, $\partial_{\psi} T_{\phi}$ acting on $C^{1}$ annihilates constants; Gross showed that $\partial_{\psi} T_{\phi}$ takes $C^{1}$ into $C(\Omega)$ and so may be interpreted as an operator from $\tilde{C}^{4}$ to $C(\Omega)$.

Space limitations prevent us from providing the heuristics for establishing higher derivatives [though it is clear how to proceed informally-see (5.2) below]. Heuristics are given in Ref. 23, Section 1.3. Here we note that we need to identify the spaces $\mathscr{P}_{N}$ and $C^{N}$ (of interactions and functions,
respectively) on which the informal expressions for the $N$ th derivative are well defined and converge. If the topologies of $C^{N}$ are defined by means of seminorms, as for $C^{1}$, then we at least want seminorms for which the operators $\zeta_{j}, T$, etc. are bounded. We follow this clue in the next section, where we define $C^{N}$ seminorms in terms of " $N$ th-order oscillations" by analogy to the definition of the $C^{1}$ seminorm in terms of "first-order" oscillations. In Section 3 we show that the operators $T_{\phi}$ are bounded on $C^{N}$ for $\phi$ in $\mathscr{D}_{n} \mathscr{P}_{N+1}$. In Section 4 we study the derivatives of the $\zeta_{j}^{\phi} f$ and establish their boundedness on $C^{N}$ and continuity in $\phi$. In the final section we state and prove the main theorem, giving estimates of the first two derivatives of the Gibbs state.

Space limitations also prevent us from giving detailed proofs in the first four sections, though we have tried to indicate the main ideas. This paper is a condensation of Ref. 23, where details may be found.

## 2. THE SPACES $C^{N}$ AND THE BOUNDEDNESS OF THE $\zeta_{j}^{\phi}$ ON $C^{N}$

### 2.1. Nth-Order Differences

For $\Lambda \subset L$ put

$$
\begin{equation*}
\Omega_{\Lambda}^{\prime}=\left\{(s, t) \in \Omega^{2}: s=t \text { off } \Lambda\right\} \tag{2.1}
\end{equation*}
$$

(the topology of $\Omega_{\Lambda}^{\prime}$ is given by its natural association to $\Omega_{\Lambda} \times \Omega_{\Lambda} \times \Omega_{L-\Lambda}$ ). For any $\Lambda \subset L$ and $(s, t) \in \Omega_{\Lambda}^{\prime}$, consider the set

$$
\begin{equation*}
\sum(s, t)=\left\{w \in \Omega: w_{i}=\text { either } s_{i} \text { or } t_{i}, i \in L\right\} \tag{2.2}
\end{equation*}
$$

Then $\Sigma(s, t)$ is the set of at most $2^{|\Lambda|}$ configurations in $\Omega$ which may be constructed from the pair ( $s, t$ ) by changing some components of $s$ into those of $t$. We may symbolize this process as follows: For $w \in \Sigma(s, t)$ and $\Gamma \subset \Lambda$, let $w_{\Gamma} \in \Omega$ be given by

$$
\left(w_{\Gamma}\right)_{i}=\left\{\begin{array}{lll}
t_{i} & \text { if } & i \in \Gamma \quad \text { and } \quad w_{i}=s_{i}  \tag{2.3}\\
s_{i} & \text { if } & i \in \Gamma \quad \text { and } \quad w_{i}=t_{i} . \\
w_{i} & \text { if } & i \notin \Gamma
\end{array}\right.
$$

Then $w_{\Gamma}$ is also in $\Sigma(s, t)$ and is obtained from $w$ by "switching" the appropriate components of $w$. Note that if $w \in \Sigma(s, t)$, then $w=s_{\Gamma}$ for some $\Gamma \subset \Lambda$. It is evident that if $(s, t) \in \Omega_{\Lambda}^{\prime}$, then for any $u \in \Sigma(s, t)$ we have $\left(u, u_{\Lambda}\right) \in \Omega_{\Lambda}^{\prime}$ and moreover that $\sum(s, t)=\Sigma\left(u, u_{\Lambda}\right)$.

Let $F: \Omega \rightarrow Y$, where $Y$ is an additive Abelian group (pertinent examples are $Y=$ real line or $Y=$ finite signed measures, on some $X_{j}$, indexed by $\Omega$, such as $\mu_{j}(d x \mid s)$ of Section 1). Given $\Lambda \subset L$, define the ( $|\Lambda|$ th-order)
difference of $F$ on $\Lambda$, denoted $F^{\Lambda}$, by

$$
\begin{equation*}
F^{\Lambda}: \Omega_{\Lambda}^{\prime} \rightarrow Y: F^{\Lambda}(s, t)=\sum_{\Gamma \subset \Lambda}(-1)^{|\Gamma|} F\left(s_{\Gamma}\right) \tag{2.4}
\end{equation*}
$$

where $s_{\Gamma}$ is to be interpreted with reference to $(s, t)$ as above. Note that $F^{\phi}(s)=F(s)$.

Differences up to second order are as follows: let $a, b \in L, u \in \Omega_{L \sim a}$, $v \in \Omega_{L-\{a, b\}}$. Then

$$
\begin{align*}
F^{\phi}: \Omega & \rightarrow Y: F^{\phi}(s)=F(s) \\
F^{\{a\}}: \Omega_{\{a\}}^{\prime} & \rightarrow Y: F^{\{a\}}\left(s_{a \vee} u, t_{a \vee} u\right)=F\left(s_{a \vee} u\right)-F\left(t_{a \vee} u\right)  \tag{2.5}\\
F^{\{a, b\}}: \Omega_{\{a, b\}}^{\prime} & \rightarrow Y: F^{\{a, b\}}\left(s_{a \vee} s_{b \vee} v, t_{a \vee} t_{b \vee} v\right) \\
& =F\left(s_{a \vee} s_{b \vee} v\right)-F\left(t_{a \vee} s_{b \vee} v\right)-F\left(s_{a \vee} t_{b \vee} v\right)+F\left(t_{a \vee} t_{b \vee} v\right)
\end{align*}
$$

Various properties of these differences appear in Section 2.3. We note here that the concept is really one of "differences of differences" and accordingly we may generalize (2.4) as follows.

Suppose that $\Upsilon \subset L$ and $G: \Omega_{\Upsilon}^{\prime} \rightarrow Y, Y$ an additive Abelian group. For any $\Lambda \subset L-\Upsilon$, define the difference of $G$ on $\Lambda$ as

$$
\begin{equation*}
G^{\Lambda}: \Omega_{\Lambda \cup \Upsilon}^{\prime} \rightarrow Y: G^{\Lambda}(s, t)=\sum_{\Gamma \subset \Lambda}(-1)^{|\Gamma|} G\left(s_{\Gamma}, s_{(\Gamma \cup \Upsilon)}\right) \tag{2.6}
\end{equation*}
$$

### 2.2. Definition of the Seminorms $D_{\Lambda},|\cdot|_{N}$

Let $\Lambda \subset L$ and $F \in C(\Omega)$. Put

$$
\begin{align*}
& D_{\Lambda}(F)=\sup _{\Omega_{\Lambda}^{\prime}}\left|F^{\Lambda}(\cdot)\right|  \tag{2.7}\\
& |F|_{N}=\sum_{\substack{\Lambda \subset L \\
|\Lambda|=N}} D_{\Lambda}(F) \tag{2.8}
\end{align*}
$$

We shall call $|\cdot|_{N}$ the $N$ th seminorm.
More generally, suppose that $G: \Omega_{\Upsilon}^{\prime} \rightarrow Y$ and $\Lambda \subset L-\Upsilon$. Put

$$
\begin{equation*}
D_{\Lambda}(G)=\sup _{\Omega_{\Lambda \cup \gamma}^{\prime}}\left|G^{\Lambda}(\cdot)\right| \tag{2.9}
\end{equation*}
$$

Of interest to us is when $G=F^{\Upsilon}, F \in C(\Omega)$, in which instance $D_{\Lambda}\left(F^{\Upsilon}\right)$ $=D_{\Lambda \cup \Upsilon}(F)$ (see Section 2.4).

### 2.3. Properties of $N$ th Order Differences

We will consider only functions $F: \Omega \rightarrow Y$, as in (2.4). Extensions to the situation of (2.6) are trivial.

Fix $\Lambda \subset L$ and $(s, t) \in \Omega_{\Lambda}^{\prime}$. We have the following:
(a) For $\Gamma, \Gamma^{\prime} \subset \Lambda$ and $w \in \sum(s, t)$,

$$
\begin{equation*}
\left(w_{\Gamma}\right)_{\Gamma^{\prime}}=w_{\Gamma \Delta \Gamma^{\prime}}, \quad \text { where } \quad \Gamma \Delta \Gamma^{\prime}=\left(\Gamma-\Gamma^{\prime}\right) \cup\left(\Gamma^{\prime}-\Gamma\right) \tag{2.10}
\end{equation*}
$$

(b) We have seen in Section 2.1 that to $w \in \Sigma(s, t)$ there corresponds a $\Gamma \subset \Lambda$ such that $w=s_{\Gamma}$. Also, $\left(w, w_{\Lambda}\right) \in \Omega_{\Lambda}^{\prime}$. We have, in that case

$$
\begin{equation*}
F^{\Lambda}\left(w, w_{\Lambda}\right)=(-1)^{|\mathbb{T}|} F^{\Lambda}(s, t) \tag{2.11}
\end{equation*}
$$

(c) Let $\Upsilon \subset L-\Lambda$. Then

$$
\begin{equation*}
F^{\Upsilon \cup \Lambda}=\left(F^{\Upsilon}\right)^{\Lambda} \tag{2.12}
\end{equation*}
$$

as in (2.6) with $G=F^{\gamma}$. This is a recursion formula for the differences. In particular, suppose $a \in \Lambda$. Let $x=s_{a}, y=t_{a}, \hat{s}=\left.s\right|_{L-a}$ and $\hat{t}=\left.t\right|_{L-a}$. Then

$$
\begin{equation*}
F^{\Lambda}(s, t)=F^{\Lambda}\left(x_{\vee} \hat{s}, y_{\vee} \hat{t}\right)=F^{\Lambda-a}\left(x_{\vee} \hat{s}, x_{\vee} \hat{t}\right)-F^{\Lambda-a}\left(y_{\vee} \hat{s}, y_{\vee} \hat{t}\right) \tag{2.13}
\end{equation*}
$$

(d) If $s_{i}=t_{i}$ for some $i \in \Lambda, F^{\Lambda}(s, t)=0$.
(e) If $F(s)$ is independent of $s_{j}, F^{\Lambda} \equiv 0$ whenever $j \in \Lambda$.

### 2.4. Remarks on the Seminorms $D_{\Lambda},|\cdot|_{N}$

(a) If $F \in C(\Omega)$, (2.4) shows that $D_{\Lambda}(F) \leqslant 2^{|\Lambda|}|F|_{\infty}<\infty$. This and the linearity of $F \rightarrow F^{\Lambda}$ show that the $D_{\Lambda}$ are indeed seminorms on $C(\Omega)$.
(b) Suppose $j \notin \Lambda, F \in C(\Omega)$ and there is a function $\xi$ on $\Omega_{\Lambda}^{\prime}$ such that $\xi(s, t)$ does not depend upon $s_{j}=t_{j}$ and such that it has the following property: for each $(s, t) \in \Omega_{\Lambda}^{\prime}$ with $\hat{s}=\left.s\right|_{L-j}$ and $\hat{t}=\left.t\right|_{L-j}$,

$$
\begin{equation*}
\inf _{x \in X_{j}} F^{\wedge}\left(x_{\vee} \hat{s}, x_{\vee} \hat{t}\right) \leqslant \xi(s, t) \leqslant \sup _{x \in X_{j}} F^{\wedge}\left(x_{\vee} \hat{s}, x_{\vee} \hat{t}\right) \tag{2.14}
\end{equation*}
$$

Then

$$
\begin{equation*}
\sup _{\Omega_{\Lambda}^{\prime}}\left|F^{\Lambda}-\xi\right| \leqslant D_{\Lambda \cup j}(F) \tag{2.15}
\end{equation*}
$$

For,

$$
\begin{align*}
\left|F^{\Lambda}(s, t)-\xi(s, t)\right| & \leqslant \sup _{x \in X_{j}} F^{\Lambda}\left(x_{\vee} \hat{s}, x_{\vee} \hat{t}\right)-\inf _{x \in X_{j}} F^{\Lambda}\left(x_{\vee} \hat{s}, x_{\vee} \hat{t}\right) \\
& \leqslant \sup _{x, y \in X_{j}}\left|F^{\wedge}\left(x_{\vee} \hat{s}, x_{\vee} \hat{t}\right)-F^{\Lambda}\left(y_{\vee} \hat{s}, y_{\vee} \hat{t}\right)\right| \\
& \leqslant D_{\Lambda \cup j}(F) \tag{2.16}
\end{align*}
$$

where we have used (2.13).
(c) If $F(s)$ is independent of $s_{j}$ and $j \in \Lambda$, Property 2.3(e) shows that $D_{\Lambda}(F)=0$. In consequence, if $F$ is a continuous cylinder function, $|F|_{M}$ $<\infty$ for all $M=1,2, \ldots$.
(d) Let $s, t \in \Omega$ and $F \in C(\Omega)$. If we change the coordinates of $s$ into those of $t$ one at a time, we see that $|F(s)-F(t)| \leqslant|F|_{1}$. Thus the subset of $C(\Omega)$ on which the "seminorm" $|\cdot|_{1}$ vanishes consists exactly of the constant functions.

### 2.5. Definition of the Spaces $C^{N}$; Their Connection with Spaces of Physical Interactions

For each natural number $N$ we define $C^{N}$ to be the topological vector space consisting of those $f \in C(\Omega)$ with $|f|_{M}<\infty, 1 \leqslant M \leqslant N$, and with topology defined by this collection of seminorms.

I am indebted to John Reid of U.C.I. for pointing out to me the following:

Lemma. If $f \in C(\Omega)$, there exists a sequence $\left\{f_{n}\right\}$ of cylinder functions converging to $f$ uniformly and such that $D_{\Lambda}\left(f_{n}\right) \leqslant D_{\Lambda}(f)$ for all $\Lambda \subset L$ and all $n$.

This may be seen as follows. Let $\left\{g_{n}\right\}$ be a sequence of cylinder functions tending to $f$ uniformly and let $\Lambda_{n}$ be finite subsets of $L$ such that $g_{n}$ depends only on coordinates in $\Lambda_{n}$ for all $n$. For $s \in \Omega$, let $s_{n}=s \mid \Lambda_{n}$ and let $t_{n} \in \Omega_{L-\Lambda_{n}}$ be any choice of configurations. Then $f_{n}(s)=f\left(s_{n} \vee t_{n}\right)$ are the required cylinder functions. It follows from this lemma that

$$
C^{N}=\left[f \in C(\Omega):|f|_{M}<\infty, 1 \leqslant M \leqslant N\right. \text {, and there exists a sequence }
$$

$\left\{f_{n}\right\}$ of cylinder functions such that $\left|f-f_{n}\right|_{M} \rightarrow 0$,

$$
\begin{equation*}
\left.1 \leqslant M \leqslant N \text { and }\left|f-f_{n}\right|_{\infty} \rightarrow 0\right] \tag{2.17}
\end{equation*}
$$

As we have seen in Section 1, the functions in $C(\Omega)$ that we expect to arise out of successive differentiations of the pressure $P(\phi)$ are of the following two kinds, namely,

$$
\begin{equation*}
A_{\phi}(s)=-\sum_{\Gamma: j \in \Gamma}|\Gamma|^{-1} \phi(s \mid \Gamma) \tag{2.18}
\end{equation*}
$$

and

$$
\begin{equation*}
k_{\phi}(s)=-\sum_{\Gamma: j \in \Gamma} \phi(s \mid \Gamma) \tag{2.19}
\end{equation*}
$$

for some $j \in L$. By a standard computation employing Property 2.3(e) it may be shown that

$$
\begin{equation*}
\left|k_{\phi}\right|_{N} \leqslant 2^{N} \sum_{\Gamma \in j}\left(\frac{|\Gamma|}{N}\right)|\phi(\cdot \mid \Gamma)|_{\infty} \leqslant \frac{2^{N}}{N!}\|\phi\|_{N+1} \tag{2.20}
\end{equation*}
$$

and similarly that

$$
\begin{equation*}
\left|\boldsymbol{A}_{\boldsymbol{\phi}}\right|_{N} \leqslant \frac{2^{N}}{N!}\|\boldsymbol{\phi}\|_{N} \tag{2.21}
\end{equation*}
$$

Thus we have that, for each nonnegative integer $N, \phi \rightarrow k_{\phi}: \mathscr{P}_{N+1} \rightarrow C^{N}$ and $\phi \rightarrow A_{\phi}: \mathscr{P}_{N} \rightarrow C^{N}$. Moreover, these maps are surjective for $N=0$. ${ }^{(18)}$
2.6. Definition of $R_{\Lambda, j}$ and $\alpha_{N}$

As in Section 1, define the probability measures

$$
\begin{equation*}
\mu_{j}^{\phi}(d x \mid s)=\nu_{j}(d x) \frac{\exp k_{\phi}\left(x_{\vee} \hat{s}\right)}{Z(s)}, \quad x \in X_{j} \tag{2.22}
\end{equation*}
$$

for each $j \in L$ and $s \in \Omega$. If $F(s)=\mu_{j}^{\phi}(d x \mid s)$, write

$$
\left(\mu_{j}^{\phi}\right)^{\Lambda}(d x \mid s, t)=F^{\Lambda}(s, t), \quad \Lambda \subset L
$$

Define

$$
\begin{equation*}
R_{\Lambda, j}(\phi)=\frac{1}{2} \sup \left\{\left\|\left(\mu_{j}^{\phi}\right)^{\Lambda}(d x \mid s, t)\right\|_{\text {total variation }}:(s, t) \in \Omega_{\Lambda}^{\prime}\right\} \tag{2.23}
\end{equation*}
$$

Note that $R_{\Lambda, j}=0$ if $j \in \Lambda$. Also, put

$$
\begin{equation*}
\alpha_{N}(\phi)=\sup _{j} \sum_{\substack{\Lambda \subset L \\|\Lambda|=N}} R_{\Lambda, j}(\phi), \quad N=1,2, \ldots \tag{2.24}
\end{equation*}
$$

It will be seen in Section 4.2 that the $\alpha_{N}(\cdot)$ are finite and in fact continuous on $\mathscr{P}_{N+1}$.

We next present the fundamental estimate needed to show that $T_{\phi}$ is bounded on $C^{N}$. This generalizes the basic inequality of Lanford, ${ }^{(4)}$ who found that $D_{a}\left(\zeta_{a} f\right)=0$ and

$$
\begin{equation*}
D_{a}\left(\zeta_{j} f\right) \leqslant D_{a}(f)+R_{a, j} D_{j}(f), \quad a \neq j \tag{2.25}
\end{equation*}
$$

### 2.7. Theorem Estimating $D_{\Lambda}\left(\zeta_{j}^{\phi} f\right)$

Let $f \in C(\Omega), j \in L$, and $\Lambda \subset L$. Then

$$
D_{\Lambda}\left(\zeta_{j}^{\dot{\phi}} f\right) \leqslant \begin{cases}0, & j \in \Lambda  \tag{2.26}\\ D_{\Lambda}(f)+\sum_{\substack{\Gamma \subset \Lambda \\ \Gamma \neq \emptyset}} R_{\Gamma, j}(\phi) D_{(\Lambda-\Gamma) \cup j}(f), & j \notin \Lambda\end{cases}
$$

(If $\Lambda=\emptyset$, we interpret the sum over $\Gamma$ in the right-hand side to be 0 .)
For the proof, the essential step is to establish, by induction on $|\Lambda|$, the following identity (where we suppress the symbols $j$ and $\phi$ ):

$$
\begin{align*}
2^{|\Lambda|}(\zeta f)^{\Lambda}(s, t)= & \sum_{\Gamma \subset \Lambda} \sum_{\Gamma^{\prime} \subset \Lambda}(-1)^{\left|\Gamma^{\prime}\right|} \int_{X_{j}} \mu^{\Gamma}\left[d x \mid s_{\Gamma^{\prime}},\left(s_{\Gamma^{\prime}}\right)_{\Gamma}\right] \\
& \times f^{\Lambda-\Gamma}\left(x_{\vee} \hat{s}_{\Gamma^{\prime}}, x_{\vee}\left(\hat{s}_{\Gamma^{\prime}}\right)_{\Lambda-\Gamma}\right), \quad(s, t) \in \Omega_{\Lambda}^{\prime} \text { and } j \notin \Lambda \tag{2.27}
\end{align*}
$$

Here $\mu^{\Gamma}$ is, as in Section 2.6, a finite signed measure on $X_{j}$. The notation $x_{\vee} \hat{s}_{\Gamma^{\prime}}$ for $\left(x_{\vee} \hat{s}_{\Gamma^{\prime}}\right.$ should cause no confusion as $x \in X_{j}$ and $j \notin \Lambda$. The estimate (2.26) is then arrived at in this way: for each $\Gamma \neq \varnothing$ appearing in (2.27), set

$$
\left.\begin{array}{rl}
\xi(s, t)= & \frac{1}{2}
\end{array} \quad \sup _{x} f^{\Lambda-\Gamma}\left[x_{\vee} \hat{s}_{\Gamma^{\prime}},\left(x_{\vee} \hat{s}_{\Gamma^{\prime}}\right)_{\Lambda-\Gamma}\right]\right) .
$$

Then we have

$$
\begin{align*}
&\left|\int \mu^{\Gamma}\left(d x \mid s_{\Gamma^{\prime}}, \cdot\right) f^{\Lambda-\Gamma}\left(x_{\vee} \hat{s}_{\Gamma^{\prime}}, \cdot\right)\right|=\left|\int \mu^{\Gamma}\left(d x \mid s_{\Gamma^{\prime}}, \cdot\right)\left\{f^{\Lambda-\Gamma}\left(x_{\vee} \hat{s}_{\Gamma^{\prime}}, \cdot\right)-\xi\right\}\right| \\
& \leqslant\left\|\mu^{\Gamma}\left(d x \mid s_{\Gamma^{\prime}} \cdot \cdot\right)\right\|_{\text {tot. var }} \\
& \frac{1}{2}\left[\sup _{x} f^{f^{\Lambda-\mathrm{r}}}\left(x_{\vee} \hat{s}_{\Gamma^{\prime}}, \cdot\right)-\inf _{x} f^{\Lambda-\Gamma}\left(x_{\vee} \hat{s}_{\Gamma}, \cdot\right)\right] \leqslant R_{\Gamma, j}(\phi) D_{(\Lambda-\Gamma) \cup j}(f) \tag{2.29}
\end{align*}
$$

where we have used the fact that $\mu^{\Gamma}$ has total mass zero, (2.23), and (2.12).
In case $\Gamma=\emptyset$, the corresponding term yields

$$
\begin{equation*}
\left|\int \mu\left(d x \mid s_{\Gamma^{\prime}}\right) f^{\Lambda}\left(x_{\vee} s_{\Gamma^{\prime}}, \cdot\right)\right| \leqslant \sup _{x}\left|f^{\Lambda}\left(x_{\vee} s_{\Gamma^{\prime}}, \cdot\right)\right| \leqslant D_{\Lambda}(f) \tag{2.30}
\end{equation*}
$$

Finally, we note that there are $2^{|\Lambda|}$ different $\Gamma^{\prime} \subset \Lambda$, each of which yields the same size estimate. When we take absolute values on both sides of (2.27) and a supremum over ( $s, t$ ), the factor $2^{|\Lambda|}$ therefore cancels and we will have proved the theorem.

## 3. THE BOUNDEDNESS OF $T_{\phi}$ ON $C^{N}$; VASERSHTEIN MATRICES

The purpose of this section is to demonstrate that $T_{\phi}$, as defined in Section 1 , is a bounded linear operator on $C^{N}, N=0,1,2, \ldots$, whenever the interaction $\phi$ is restricted to a suitable neighborhood $\mathscr{D}_{N}$ of the origin in $P_{N+1}$. In Section 5.3 we will show that $\phi \rightarrow T_{\phi} f: \mathscr{D}_{N} \rightarrow C^{N}$ is continuous. The proof of this rests on the arguments of Section 4. We first identify $\mathscr{D}_{N}$ and then state the main theorem.

### 3.1. The Dobrushin Uniqueness Regions

For $N$ a natural number, let

$$
\begin{equation*}
\mathscr{D}_{N}=\left[\phi \in P_{N+1}: \alpha_{1}(\phi)<1\right] \tag{3.1}
\end{equation*}
$$

We call $\mathscr{D}_{N}$ the $N$ th Dobrushin uniqueness region. We will see in Section 4.2 that, on $\mathscr{P}_{N+1}, \alpha_{M}(\cdot), 1 \leqslant M \leqslant N$ are finite (and in fact continuous). In this section we shall assume this as an added condition in the definition of $\mathscr{D}_{N}$ above.

### 3.2. Theorem Bounding the $T_{\phi, k, p}$

For $\phi \in \mathscr{D}_{N}, N=1,2, \ldots$, the operators $T_{\phi, k, p}(1 \leqslant k<\infty, k \leqslant p$ $\leqslant \infty$ ), already defined in $C(\Omega)$, are bounded linear operators on $C^{N}$. For $f \in C^{N}$ and $\varphi \in \mathscr{D}_{N}$, we have (when $k<p$ ),

$$
\begin{align*}
\left|T_{\varphi, k, p} f\right| \leqslant & \rho_{k, p}(\varphi)|f|+\left[1-\alpha_{1}(\varphi)\right]^{-1} \\
& \times\left(G \sum_{l=0}^{N-1}\left\{G+\left[1-\alpha_{1}(\varphi)\right]^{-1} J G\right\}^{l}\left[J|f|+E^{p}(f)\right]\right) \tag{3.2}
\end{align*}
$$

where $|f|$ is the $N \times 1$ column matrix $\left[|f|_{M}\right]$

$$
\rho_{k, p}(\varphi)=\left\{\begin{array}{llll}
\alpha_{1}(\varphi), & \text { if } \quad k=1 & \text { and } \quad p=\infty  \tag{3.3}\\
1, & \text { if } \quad k>1 \quad \text { or } \quad p<\infty
\end{array}\right.
$$

where the $N \times N$ matrices $G, J$ are defined by

$$
\begin{gather*}
G_{m, l}= \begin{cases}\alpha_{m-l+1}(\varphi), & 1 \leqslant l \leqslant m-1 \\
0, & l \geqslant m\end{cases}  \tag{3.4}\\
J_{m, l}=m \delta_{m, l} \quad(\text { Kronecker } \delta) \tag{3.5}
\end{gather*}
$$

and where $E^{p}(f)$ is the $N \times 1$ matrix whose $M$ th entry is

$$
E_{M}^{p}(f)=\left\{\begin{array}{lll}
0, & p=\infty  \tag{3.6}\\
{\left[1-\alpha_{1}(\varphi)\right] \sum_{\substack{\Gamma \not z_{p} \\
|\Gamma|=M-1}} D_{\Gamma \cup_{p}}(f),} & p<\infty
\end{array}\right.
$$

When $k=p$, we have

$$
\begin{equation*}
\left|T_{p, p} f\right|_{N}=\left|\zeta_{p} f\right|_{N} \leqslant|f|_{N}+\left[1-\alpha_{1}(\varphi)\right]^{-1} \sum_{j=1}^{N} \alpha_{N-j+1} E_{j}^{p}(f) \tag{3.7}
\end{equation*}
$$

### 3.3. Remarks on Theorem 3.2

(a) The estimate in (3.2) for $\left|T_{\varphi, k, p} f\right|_{N}$ involves the $N$ th seminorms of $f$ only in the first term of the right-hand side, the matrix $G$ being zero on and above its diagonal.
(b) The instance $N=1$ was proved by L. Vasershtein. ${ }^{(5)}$
(c) We present estimate (3.2) for $N=1,2$, and 3. Set

$$
\begin{equation*}
\gamma_{n}(\phi)=\frac{\alpha_{n}(\phi)}{1-\alpha_{1}(\phi)}, \quad n=1,2, \ldots \tag{3.8}
\end{equation*}
$$

Then, suppressing $\varphi$,

$$
\begin{align*}
\left|T_{k, p} f\right|_{1} \leqslant & \rho_{k, p}|f|_{1}  \tag{3.9a}\\
\left|T_{k, p} f\right|_{2} \leqslant & \rho_{k, p}|f|_{2}+\gamma_{2}\left[|f|_{1}+E_{1}^{p}(f)\right]  \tag{3.9b}\\
\left|T_{k, p} f\right|_{3} \leqslant & \rho_{k, p}|f|_{3}+2 \gamma_{2}|f|_{2}+\left[\gamma_{3}+\alpha_{2} \gamma_{2}\left(1+\frac{2}{1-\alpha_{1}}\right)\right]|f|_{1} \\
& +\left\{\gamma_{2} E_{2}^{p}+\left[\gamma_{2} \alpha_{2}\left(1+\frac{2}{1-\alpha_{1}}\right)+\gamma_{3}\right] E_{1}^{p}\right\} \tag{3.9c}
\end{align*}
$$

### 3.4. Definition of Vasershtein Matrices

Define

$$
\begin{gather*}
V_{N}=\{\Lambda \subset L,|\Lambda|=N\}, \quad N=0,1,2, \ldots  \tag{3.10}\\
U_{N}=\bigcup_{n=1}^{N} V_{n}, \quad N=1,2, \ldots
\end{gather*}
$$

and

$$
U_{0}=\{\phi\}=V_{0}
$$

For $\Lambda, \Gamma \subset L$, let

$$
\chi_{\Lambda, \Gamma}= \begin{cases}1 & \text { if } \Gamma \subset \Lambda  \tag{3.11}\\ 0 & \text { otherwise }\end{cases}
$$

and let

$$
\delta_{\Lambda, \Gamma}= \begin{cases}1 & \text { if } \Gamma=\Lambda  \tag{3.12}\\ 0 & \text { otherwise }\end{cases}
$$

In what follows we shall assume that $\phi$ is a fixed interaction (in $\mathscr{P}_{1}$, at least) and will not explicitly mention it in our formulas.

For fixed $N \geqslant 0$ and $\Lambda, \Gamma \in V_{N}$, put

$$
\stackrel{(k)}{A}_{\Lambda, \Gamma}= \begin{cases}\delta_{\Lambda, \Gamma}, & \text { if } k \notin \Gamma  \tag{3.13}\\ R_{\Lambda-(\Gamma-k), k} \chi_{\Lambda, \Gamma-k}, & \text { if } k \in \Gamma\end{cases}
$$

and for $\Lambda \in V_{N}, \Gamma \in \bigcup_{N-1}$, put

$$
\mathscr{A}_{A, \Gamma}= \begin{cases}0, & \text { if } k \notin \Gamma  \tag{3.14}\\ R_{A-(\Gamma-k), k} \chi_{A, r-k}, & \text { if } k \in \Gamma\end{cases}
$$

(k)
[of course, $\mathscr{A}_{\mathrm{A}, \Gamma}$ is defined by the right-hand side of (3.13) also]. Note that (k) if $\Lambda \in V_{1}, \mathscr{A}_{\Lambda, \Gamma} \equiv 0$.

The $A^{(k)}, \mathscr{A}^{(k)}$ are here entitled "Vasershtein matrices" after L. Vasershtein, who studied them in the instance $N=1$. ${ }^{(5)}$

### 3.5. Recasting Theorem 2.7

We may rewrite (2.26) in terms of Vasershtein matrices as follows: let $\Lambda \in V_{N}$. Then

$$
\begin{equation*}
D_{\Lambda}\left(\zeta_{k} f\right) \leqslant \sum_{\Gamma \in V_{N}} \stackrel{(k)}{A}_{A, \Gamma} D_{\Gamma}(f)+\sum_{\Gamma \in U_{N-1}} \stackrel{(k)}{A}_{A, \Gamma} D_{\Gamma}(f), \quad N \geqslant 1 \tag{3.15}
\end{equation*}
$$

To see this, consider (2.26) (with $j \rightarrow k$ ). Note that

$$
\sum_{\substack{\Gamma \subset \Lambda \\ \Gamma \neq \phi}} R_{\Gamma, k} D_{(\Lambda-\Gamma) \cup k}=\sum_{\substack{\Gamma^{\prime} \subset \Lambda \\ \Gamma^{\prime} \neq \Lambda}} R_{\Lambda-\Gamma^{\prime}, k} D_{\Gamma^{\prime} \cup k}=\sum_{\substack{\Gamma: k \in \Gamma \\ \Gamma-k \subset \Lambda \\|\Gamma| \leqslant N}} R_{\Lambda-(\Gamma-k), k} D_{\Gamma}
$$

where we have successively set $\Gamma^{\prime}=\Lambda-\Gamma$ and $\Gamma=\Gamma^{\prime} \cup k$. Thus, employing (3.10) and (3.11), (2.26) translates to

$$
D_{\Lambda}\left(\xi_{k} f\right) \leqslant \begin{cases}0, & k \in \Lambda  \tag{3.16}\\ D_{\Lambda}(f)+\sum_{\substack{\Gamma \in U_{N} \\ k \in \Gamma}} R_{\Lambda-(\Gamma-k), k} \chi_{\Lambda, \Gamma-k} D_{\Gamma}(f), & k \notin \Lambda\end{cases}
$$

Now since $U_{N}$ is the disjoint union of $V_{N}$ and $U_{N-1}$, we see from the definitions (3.13) and (3.14) that (3.15) holds.

### 3.6. Products of the Matrices

Consider the following sum of nonnegative terms; for $\Lambda, \Gamma \in V_{N}$, $k=1,2, \ldots$, and $n=0,1,2, \ldots$ :

Doing the sum in the order $\Lambda_{1}, \Lambda_{2}, \ldots, \Lambda_{n}$, we see that the sum is actually
a finite one of at most $(N+1)^{n}$ terms ( $A_{\Lambda, \Lambda_{1}}$, for example, stands a chance of being nonzero only if $\Lambda \nexists k$ and either $\Lambda_{1}=\Lambda$ or $\Lambda_{1}=(\Lambda-j)_{\cup} k$ for some $j \in \Lambda$ ).
 over the $\Lambda_{j}$ from right to left ( $j$ decreasing) for those $j$ with $k+j \notin \Gamma$, we have

$$
B_{\Lambda, \Gamma}^{k, k+n}= \begin{cases}\delta_{\Lambda, \Gamma}, & \Gamma_{\cap}[k, k+n]=\varnothing  \tag{3.18}\\ B_{\Lambda, \Gamma}^{k, \max \left\{\Gamma_{n}[k, k+n]\right\}}, & \Gamma_{\cap}[k, k+n] \neq \varnothing\end{cases}
$$

where $[k, k+n]=\{k, k+1, \ldots, k+n\}$ and $\max \Lambda=\max \{j: j \in \Lambda\}$.
Now fix $k, \Lambda, \Gamma$ and allow $n$ to increase indefinitely. As soon as $n>\max \Gamma$, the sequence $B_{\Lambda, \Gamma}^{k, k+n}$ becomes constant and therefore has a limit
$B_{\Lambda, \Gamma}^{k, \infty}:$

$$
\begin{align*}
& B_{\Lambda, \Gamma}^{k, \infty}=\lim _{n \rightarrow \infty} B_{\Lambda, \Gamma}^{k, n}= \begin{cases}\delta_{\Lambda, \Gamma}, & \max \Gamma<k \\
B_{\Lambda, \Gamma}^{k, \max \Gamma}, & \max \Gamma \geqslant k\end{cases}  \tag{3.19}\\
& B_{\Lambda, \Gamma}^{k, \infty}=B_{\Lambda, \Gamma}^{k, j} \quad \text { for any } j \geqslant \max \Gamma \tag{3.20}
\end{align*}
$$

Certain summability estimates for these matrices were studied by Vasershtein and Gross ${ }^{(7)}$ when $N=1$. We will need similar estimates for $N \geqslant 1$. The next lemma enables us to reduce the estimations for $N>1$ to those of Ref. 7.

### 3.7. Lemma

(a) Let $\Lambda$ and $\Gamma$ be in $V_{N}$ for some $N \geqslant 1$ and let $\pi_{\Lambda}, \pi_{\Gamma}$ be the sets of ordered arrangements of $\Lambda, \Gamma$, respectively. We write the components of $b \in \pi_{\Lambda}$ as $b_{i}, 1 \leqslant i \leqslant N$. Then we have

$$
\begin{equation*}
B_{\Lambda, \Gamma}^{k, p} \leqslant \frac{1}{N!} \sum_{b \in \pi_{\Lambda}} \sum_{c \in \pi_{\Gamma}} \prod_{i=1}^{N} B_{b_{i}, c_{i}}^{k, p}=\sum_{b \in \pi_{\Lambda}} \prod_{i=1}^{N} B_{b_{i}, b_{i}}^{k, p_{i}}=\sum_{c \in \pi_{\Gamma}} \prod_{i=1}^{N} B_{\mathscr{B}_{i}, c_{i}}^{k, p} \tag{3.21}
\end{equation*}
$$

where $\mathscr{B}$ and $\mathscr{C}$ are any fixed elements of $\pi_{\Lambda}, \pi_{\Gamma}$, respectively.
(b) If $\max \Lambda \leqslant p<\max \Gamma, B_{\Lambda, \Gamma}^{k, p}=0$.

The proof of part (a) rests on induction in $p$. Part (b) is a corollary to part (a) and the corresponding property for $N=1$.

### 3.8. Lemma: Summability of the Matrices

(a) Let $N \geqslant 1, k \in[1, \infty)$ and $p \in[k, \infty]$. If $\alpha_{1}<1$, then for all $\Gamma \in V_{N}$,

$$
\begin{gather*}
\sum_{\Lambda \in V_{N}} B_{\Lambda, \Gamma}^{1, \infty} \leqslant \alpha_{1}  \tag{3.22}\\
\sum_{\Lambda \in V_{N}} B_{\Lambda, \Gamma}^{k, p} \leqslant 1 \tag{3.23}
\end{gather*}
$$

and

$$
\begin{equation*}
\sum_{k=1}^{p-1} \sum_{\substack{\Lambda \in V_{N-1} \\ k \notin \Lambda}} B_{\Lambda \cup k, \Gamma}^{k+1, p} \leqslant \frac{N}{1-\alpha_{1}} \tag{3.24}
\end{equation*}
$$

(b) Let $N \geqslant 2$ and $j \in[1, N-1]$. For each $k \in L$ and each $\Gamma \in V_{j-1}$ with $k \notin \Gamma$, we have

$$
\begin{equation*}
\sum_{\Lambda \in V_{N}} \stackrel{(k)}{\mathscr{A}}_{\Lambda, \Gamma_{\lrcorner} k} \leqslant \alpha_{N-j+1} \tag{3.25}
\end{equation*}
$$

The proof of (3.22) is along the same lines as that in Gross [Ref. 7, Eq. (3.11)]. (3.23) follows by the same argument and (3.24) relies on Lemma 3.7 above and on equation (3.12) of Ref. 7 for its proof. Part (b) is a direct consequence of the definition (3.14) of $\mathscr{A}$.

The next lemma iterates the basic inequality (3.15) a finite number of times.

### 3.9. Lemma

For $k \in[1, \infty), p \in[k, \infty), N \geqslant 1, \Lambda \in V_{N}$ and $f \in C(\Omega)$, we have

$$
\begin{align*}
D_{\Lambda}\left(T_{k, p} f\right) \leqslant & \sum_{\Gamma \in V_{N}} B_{\Lambda, \Gamma}^{k, p} D_{\Gamma}(f) \\
& +\sum_{n=k-1}^{p-1} \sum_{\Gamma \in V_{N}} B_{\Lambda, \Gamma}^{k, n} \sum_{\substack{r \nexists(n+1) \\
T_{\cup}(n+1) \in U_{N-1}}}{ }^{(n+1)} A_{\Gamma, \Upsilon_{\cup}(n+1)} D_{\Upsilon_{\cup(n+1)}\left(T_{n+2, p} f\right)} \tag{3.26}
\end{align*}
$$

where we make the conventions that $B_{\Lambda, \Gamma}^{k, k-1}=\delta_{\Lambda, \Gamma}$ and $T_{p+1, p} f=f$. In case $N=1$, the second sum is considered empty and we have

$$
\begin{equation*}
D_{i}\left(T_{k, p} f\right) \leqslant \sum_{j=1}^{\infty} B_{i, j}^{k, p} D_{j}(f) \tag{3.27}
\end{equation*}
$$

In order to extend this result to the case $p=\infty$, as well as to estimate $\left|T_{\varphi, k, p} f\right|_{N}$ as in (3.2), we need a technical lemma (for $N \geqslant 2$ ).

### 3.10. Lemma

Let $k \in[1, \infty), p \in[k, \infty], n$ a natural number, $f \in C(\Omega)$ and $\phi \in \mathscr{D}_{1}$. Define

$$
\begin{equation*}
F_{k, p ; n}(f)=\left(1-\alpha_{1}\right) \sum_{m=k}^{p} \sum_{\substack{\Lambda \in V_{n-1} \\ m \notin \Lambda}} D_{\Lambda_{\cup} m}\left(T_{m+1, p} f\right) \tag{3.28}
\end{equation*}
$$

where, as usual, $T_{p+1, p} f=f(p<\infty)$.
Then for $p<\infty$ we have

$$
F_{k, p ; n}(f) \leqslant \begin{cases}n|f|_{n}+\left(1+\frac{n}{1-\alpha_{1}}\right) \sum_{l=1}^{n-1} \alpha_{n-l+1} F_{k+1, p ; l}(f) &  \tag{3.29}\\ \quad+E_{n}^{p}(f), & \text { if } p>k \\ E_{n}^{p}(f) & \text { if } p=k\end{cases}
$$

[where $E_{n}^{p}$ is defined as in (3.6)]. The sum above is zero when $n=1$.

We may express the estimate for $F$ in matrix form. To this end, let $F$, $|f|$, and $E^{p}$ be $n \times 1$ column matrices whose $m$ th entries are $F_{k, p ; m},|f|_{m}$, and $E_{m}^{p}$ respectively. Let $G$ and $J$ be the $n \times n$ matrices defined in (3.4) and (3.5) with $N=n$. Then if $k<p<\infty$ we have for $j \in[1, n]$

$$
\begin{equation*}
F_{j} \leqslant \sum_{k=0}^{j-1}\left\{\left[\left(1+\frac{1}{1-\alpha_{1}} J\right) G\right]^{k}\left(J|f|+E^{p}\right)\right\}_{j} \tag{3.30}
\end{equation*}
$$

The proof of this lemma involves a careful application of Lemmas 3.8 and 3.9 to the summand in (3.28). We then get (3.30) by noting that $F_{k+1, p, l}(f) \leqslant F_{k, p, l}(f)$ and that if two matrices are both zero on and above their diagonals, then so is their product.

### 3.11. Proof of Theorem 3.2

Our task is to show that the conclusions of Lemma 3.9 and 3.10 continue to hold when $p=\infty$ and then to sum (3.26) over $\Lambda \in V_{M}$, $1 \leqslant M \leqslant N$. To this end, let

$$
\begin{equation*}
R_{\Lambda}^{k, p}(f)=\text { right-hand side of }(3.26) \tag{3.31}
\end{equation*}
$$

Since this is a sum of nonnegative (though possibly infinite) terms, it is well defined for $p=\infty$. We will first show that

$$
\begin{align*}
D_{\Lambda}\left(T_{k} f\right) & =\lim _{p \rightarrow \infty} D_{\Lambda}\left(T_{k, p} f\right) \leqslant \lim _{p \rightarrow \infty} R_{\Lambda}^{k, p}(f) \\
& =R_{\Lambda}^{k, \infty}(f)<\infty \tag{3.32}
\end{align*}
$$

The first equality follows from the fact that $D_{\Lambda}(\cdot)$ is a continuous seminorm on $C(\Omega)$ [cf. Remark 2.4(a)]. Thus we are required to show that, under our hypotheses $\phi \in D_{N}, f \in C^{N}$,

$$
\begin{equation*}
\lim _{p \rightarrow \infty} R_{\Lambda}^{k, p}(f)=R_{\Lambda}^{k, \infty}(f)<\infty \tag{3.33}
\end{equation*}
$$

We do this by induction on $N$ as follows:
(i) We show that (3.33) holds for $N=1$ and then make the induction hypothesis that it holds for $N \leqslant M-1$.
(ii) It will follow that Lemma 3.10 holds for $p=\infty, n \leqslant m-1$.
(iii) This will yield a bound for $F_{k_{p} ; M-1}, p \leqslant \infty$, with which we will establish (3.33) when $|\Lambda|=M$.
(i) Let $N=1$. Then by (3.27), if $p<\infty$ and $i \in L$,

$$
\begin{equation*}
R_{i}^{k, p}(f)=\sum_{j=1}^{\infty} B_{i, j}^{k, p} D_{j}(f) \tag{3.34}
\end{equation*}
$$

Now suppose $p>i$. By Lemma 3.7(b) and (3.20),

$$
\begin{equation*}
R_{i}^{k, p}(f)=\sum_{j=1}^{p} B_{i, j}^{k_{k}, p} D_{j}(f)=\sum_{j=1}^{p} B_{i, j}^{k, \infty} D_{j}(f), \quad(i<p<\infty) \tag{3.35}
\end{equation*}
$$

Hence

$$
\begin{equation*}
\lim _{p \rightarrow \infty} R_{i}^{k, p}(f)=\sum_{j=1}^{\infty} B_{i, j}^{k, \infty} D_{j}(f)=R_{k}^{k, \infty}(f) \tag{3.36}
\end{equation*}
$$

Finally, Lemma 3.8 shows us that

$$
\begin{equation*}
R_{i}^{k, \infty}(f) \leqslant \sum_{j} R_{j}^{k, \infty}(f) \leqslant \rho_{k, \infty}(\dot{\phi})|f|_{1}<\infty \tag{3.37}
\end{equation*}
$$

where $\rho_{k, \infty}(\phi)$ is defined in (3.3).
Thus (3.33) holds for $N=1$. Assume that, for some $M \geqslant 1$, it holds for all $N \leqslant M-1, \Lambda \in V_{N}\left(f \in C^{N}\right.$ and $\left.\phi \in \mathscr{D}_{N}\right)$.

Let now $f$ be in $C^{M}$ and $\phi \in \mathscr{D}_{M}$. Then a priori $f \in C^{N}, \phi \in \mathscr{D}_{N}$ for each $N \leqslant M$.
(ii) By the above induction hypothesis, (3.26) holds with $p=\infty$ and $|\Lambda|=j \leqslant M-1$. An examination of the proof of Lemma 3.10 reveals that, in that case, the statement of Lemma 3.10 continues to be true with $p=\infty$ (and $E^{\infty}=0$ ) for $n \leqslant M-1$. Thus, we have that, for $1 \leqslant n \leqslant M-1$,

$$
\begin{equation*}
F_{k, \infty ; n}(f) \leqslant \sum_{l=1}^{n} K_{n, l}|f|_{l} \tag{3.38}
\end{equation*}
$$

with

$$
\begin{equation*}
K_{n, l}=\sum_{m=0}^{M-1}\left\{\left[\left(I+\frac{1}{1-\alpha_{1}} J\right) G\right]^{m} J\right\}_{n, l} \tag{3.39}
\end{equation*}
$$

where $J, G$ are as in (3.5). It is permissible to extend this sum over $m$ to $M-1$ (rather than $n-1$ ) since the summands are zero for $m \geqslant n-1$. Since $\phi \in \mathscr{D}_{M}$, all entries are finite and

$$
\begin{equation*}
F_{k, p ; n}(f)<\infty \quad \text { for } \quad f \in C^{M}, \quad \phi \in \mathscr{D}_{M}, \quad n \leqslant M-1, \quad \text { and } \quad p \leqslant \infty \tag{3.40}
\end{equation*}
$$

(iii) Fix $\Lambda \in V_{M}$ and put, for any $h \in C(\Omega)$,
i.e., the second term of $R_{\Lambda}^{k, p}(h)$ (we have adjusted the index " $n$ " a bit). As usual, $B_{\Lambda, \Gamma}^{k, k-1}=\delta_{\Lambda, \Gamma}$ and $T_{p+1, p} f=f$ for $p<\infty$.

Now suppose that $p>\max \Lambda$. Then by Lemma 3.7(b) and (3.20) we have

$$
\begin{equation*}
R_{\Lambda}^{k, p}(h)=\sum_{\substack{\Gamma \in V_{M} \\ \max \Gamma \leqslant p}} B_{\Lambda, \Gamma}^{k, \infty} D_{\Gamma}(h)+P_{\Lambda}^{k, p}(h) \tag{3.42}
\end{equation*}
$$

Thus, to prove (3.33) it suffices to show that

$$
\begin{equation*}
\lim _{p \rightarrow \infty} P_{\Lambda}^{k, p}(f)=P_{\Lambda}^{k, \infty}(f)<\infty \quad(|\Lambda|=M) \tag{3.43}
\end{equation*}
$$

Consider $P_{\Lambda}^{k, p}(h)$. From (3.41), (3.23), and (3.25) we have, for $k \leqslant p \leqslant \infty$, that

$$
\begin{align*}
P_{\Lambda}^{k, p}(h) & \leqslant \sum_{\Lambda^{\prime} \in V_{M}} P_{\Lambda}^{k, p}(h) \leqslant \sum_{j=1}^{M-1} \sum_{n=k}^{p} \alpha_{M-j+1} \sum_{\Upsilon_{\cup} \in V_{j}} D_{\Upsilon_{\cup n}}\left(T_{n+1, p} h\right) \\
& \leqslant \frac{1}{1-\alpha_{1}} \sum_{j=1}^{M-1} \alpha_{M-j+1} F_{k, p ; j}(h)<\infty \quad \text { if } h \in C^{M} \text { and } k \leqslant p \leqslant \infty \tag{3.44}
\end{align*}
$$

as follows from (3.40) above.
Suppose now that $g$ is a cylinder function based on $q$. Since $P_{\Lambda}^{k, p}(h)$ is finite for $h \in C^{M}, P_{\Lambda}^{k, p}(\cdot)$ is a seminorm for each $p<\infty$, so that if $q<p<\infty$,

$$
\begin{equation*}
\left|P_{\Lambda}^{k, p}(f)-P_{\Lambda}^{k, \infty}(f)\right| \leqslant P_{\Lambda}^{k, p}(f-g)+P_{\Lambda}^{k, \infty}(f-g) \tag{3.45}
\end{equation*}
$$

Here we have used $P_{\Lambda}^{k, p}(g)=P_{\Lambda}^{k, \infty}(g)$ for $p>q$.
Now it follows from (3.44) and (3.38) (and its analog with $p<\infty$ ) that $P^{k, p}(\cdot): C^{M} \rightarrow R^{1}$ is continuous at 0 for each $p \leqslant \infty$, under our hypothesis that $\phi \in \mathscr{D}_{M}$. Moreover, the bounds on $P_{\Lambda}^{k, p}(h)$ may be chosen uniformly in $p$, since $E_{j}^{p}(h) \rightarrow 0$ as $p \rightarrow \infty$ for $j \leqslant M, h \in C^{M}$. Hence we may make the left-hand side of (3.45) as small as desired by first choosing a cylinder function $g$ close to $f$ (in the $|\cdot|_{n}$ seminorms, $1 \leqslant n \leqslant M$ ) and then letting $p$ go to $\infty$. We have therefore established (3.43) for $\Lambda \in V_{M}$ and therefore also (3.33).

It remains to estimate $\left|T_{k, p} f\right|_{N}$. As in (3.44), we have from (3.26) (extended to $p \leqslant \infty$ ) that

$$
\begin{align*}
\left|T_{k, p} f\right|_{N} & =\sum_{\Lambda \in V_{N}} D_{\Lambda}\left(T_{k, p} f\right) \\
& \leqslant \sum_{\Gamma} \sum_{\Lambda} B_{\Lambda, \Gamma}^{k, p} D_{\Gamma}(f)+\frac{1}{1-\alpha_{1}} \sum_{j=1}^{N-1} \alpha_{N-j+1} F_{k, p ; j}(f) \\
& \leqslant \rho_{k, p}|f|_{N}+\frac{1}{1-\alpha_{1}}(G F)_{N} \tag{3.46}
\end{align*}
$$

for $1 \leqslant k \leqslant p \leqslant \infty$. We have used (3.22), (3.23), and (3.28). Now applying (3.30) of Lemma 3.10 (and letting the sum over $k$ extend to $N-1$ there [see remarks after (3.39)], we conclude that (3.2) holds and its right-hand side is finite. As for (3.7), simply estimate (3.15) as above [see Theorem 4.4(a)(ii)].

### 3.12. Remarks

It follows, as in the proof above, that in fact

$$
\begin{equation*}
\lim _{p \rightarrow \infty}\left|T_{k, p} f\right|_{N}=\left|T_{k} f\right|_{N}, \quad f \in C^{N}, \quad \phi \in \mathscr{D}_{N} \tag{3.47}
\end{equation*}
$$

since by the estimates of Theorem 3.2, $\left|T_{k, p} \cdot\right|$ is a seminorm on $C^{N}$ for each $p \leqslant \infty$, when $\phi \in D_{N}$.

The $N=1$ estimate

$$
\begin{equation*}
\left|T_{\phi} f\right|_{1} \leqslant \alpha_{1}(\phi)|f|_{1}, \quad \phi \in \mathscr{D}_{1} \tag{3.48}
\end{equation*}
$$

may be used to prove Dobrushin's theorem and Vasershtein's formula (1.5). See Ref. 7, Corollary 3.3 or Ref. 23, pp. 61 and 62.

## 4. DERIVATIVES OF $\phi \rightarrow \zeta_{j}^{\phi} f$

### 4.1. Existence of Derivatives of $\phi \rightarrow \zeta_{j}^{\phi} f: \mathscr{P}_{1} \rightarrow C(\Omega)$; Ursell Functions

In the following, all interactions will be in $\mathscr{P}_{1}$ and $j$ is a fixed point of $L$. Given an interaction $\psi$, write

$$
\begin{equation*}
k_{\psi}(\cdot)=-\sum_{\Lambda \in j} \psi(\cdot \mid \Lambda) \tag{4.1}
\end{equation*}
$$

As in Section 2.5, $k_{\psi} \in C(\Omega)$.
Let $g=k_{\phi}, h \in C(\Omega)$ and $s \in \Omega_{L-j}$. Put

$$
Z_{g}(s)=\int_{X_{j}} \nu_{j}(d x) e^{g\left(x_{\vee} s\right)}
$$

and

$$
\begin{equation*}
\langle h\rangle_{g}(s)=Z_{g}^{-1}(s) \int_{X_{j}} v_{j}(d x) e^{g\left(x_{\vee} s\right)} h\left(x_{\vee} s\right)\left(\equiv \zeta_{j}^{\phi} h(s)\right) \tag{4.2}
\end{equation*}
$$

Now suppose the function $g$ in (4.2) depends also on some parameter $v \in I, I \subset R^{1}$ an open interval. We claim that if $v \rightarrow g_{v}: I \rightarrow C(\Omega)$ is differentiable at $v_{0} \in I$, then so is $v \rightarrow\langle h\rangle_{g_{0}}: I \rightarrow C(\Omega)$, with derivatives given by

$$
\begin{equation*}
\left.\frac{d}{d v}\langle h\rangle_{g_{v}}\right|_{v=v_{0}}=\left\langle h\left(g_{v_{0}}^{\prime}-\left\langle g_{v_{0}}^{\prime}\right\rangle_{g_{v_{0}}}\right\rangle_{v_{v_{0}}}\right. \tag{4.3}
\end{equation*}
$$

where $g_{v_{0}}^{\prime}=\left.\left(d g_{v} / d v\right)\right|_{v=v_{0}}$. This may be seen by means of the usual dominated convergence arguments. More generally we may suppose that $v$ lies in some open ball of $R^{n}$; the partial derivatives of $v \rightarrow\langle h\rangle_{g_{v}}$ are then found by successive differentiations of the type (4.3). Finally, with suitable modifications to (4.3), we may allow $h$ to depend upon $v$ also.

Our concern is with Gateaux derivatives of $\phi \rightarrow \zeta_{j}^{\phi} f$, so that we now specialize to functions of the form

$$
\begin{equation*}
v \rightarrow g_{\mathbf{v}}=g+\mathbf{v} \cdot \mathbf{k}=g+\sum_{i=1}^{n} v_{i} k_{i} \tag{4.4}
\end{equation*}
$$

where $\mathbf{v}=\left(v_{1}, \ldots, v_{n}\right) \in R^{n}$ and $\mathbf{k}=\left(k_{1}, \ldots, k_{n}\right) \in(C(\Omega))^{n}$. (The $k_{i}$ will arise as $k_{\psi_{i}}$ [see (4.1)] or as $A_{\psi_{i}}$ (2.18).) Note that $g_{v} \in C(\Omega)$ for $\mathbf{v} \in R^{n}$ and by the above remarks, $\mathbf{v} \rightarrow\langle h\rangle_{g_{v}}$ is $C^{\infty}$ differentiable.

We introduce the notation

$$
\begin{equation*}
\left(\prod_{i=1}^{m} \partial_{i}\right)\langle h\rangle_{g}=\left.\left(\frac{\partial^{m}}{\partial v_{1} \cdots \partial v_{m}}\langle h\rangle_{g_{v}}\right)\right|_{v=0} \tag{4.5}
\end{equation*}
$$

when $1 \leqslant m \leqslant n$. It is clear that the order of differentiation is immaterial and that

$$
\begin{equation*}
\partial_{1}\langle h\rangle_{g}=\left\langle h k_{1}\right\rangle_{g}-\langle h\rangle_{g}\left\langle k_{1}\right\rangle_{g} \tag{4.6}
\end{equation*}
$$

We may characterize the derivatives (4.5) as follows.
For $f_{i} \in C(\Omega), 1 \leqslant i \leqslant m$, define the $m$ th-order Ursell function [with respect to $g \in C(\Omega), j \in L]$ by

$$
\begin{align*}
& u_{m}^{g}\left(f_{1}, \ldots, f_{m}\right)(s)=u_{m}^{g}\left(\left\{f_{i}\right\}_{1}^{m}\right)(s) \\
&=\sum_{Q_{m}}(-1)^{\left|Q_{m}\right|-1}\left(\left|Q_{m}\right|-1\right)!\prod_{P \in Q_{m}}\left\langle f_{P}\right\rangle_{g}(s) \\
& \quad\left(s \in \Omega_{L-j}\right) \tag{4.7}
\end{align*}
$$

where $Q_{m}$ runs over all partitions of the set $[1, m]$ and $f_{P}=\prod_{i \in P} f_{i}$ (see, e.g., Ref. 24). The significance of Ursell functions is that

$$
\begin{equation*}
\prod_{i=1}^{n} \partial_{i}\langle h\rangle_{g}=u_{n+1}^{g}\left(h, k_{1}, \ldots, k_{n}\right) \tag{4.8}
\end{equation*}
$$

This may be verified by induction on $n$, using (4.6) [see (4.10) below]. Note that $u_{m}^{g}\left(\left\{f_{i}\right\}\right)(\cdot) \in C(\Omega)$.

For later purposes we need to generalize somewhat the notion of Ursell functions. Note from (4.2) that the right-hand side of (4.1) is still well defined when $g \in C\left(X_{j} \times M\right), f_{i} \in C\left(X_{j} \times M_{i}\right), 1 \leqslant i \leqslant n$, where $M, M_{i}$ are topological spaces (of course, the argument " $s$ " has to be suitably altered). In particular, our $M_{i}$ will be of the form $\Omega_{\Lambda}^{\prime} \times\left(\times_{i=1}^{n} \Omega_{\Lambda_{i}}^{\prime}\right)$ or some suitable subset.)

We mention some properties of Ursell functions.
Remarks 4.1.1. (a) If $m \geqslant 2$ and some $f_{l}$ is independent of the $j$ th coordinate, $u_{m}^{g}\left(\left\{f_{i}\right\}\right) \equiv 0$. This follows from the representation (4.8): if $k_{1}\left(x_{\vee} s\right)$ is independent of $x, \partial_{1}\langle h\rangle_{g} \equiv 0$ for all $g$.

It is clear that $\left\{f_{i}\right\}_{i=1}^{n} \rightarrow u_{n}^{g}\left(\left\{f_{i}\right\}\right):(C(\Omega))^{n} \rightarrow C(\Omega)$ is multilinear. This and the above remark allow us to, for example, replace any $f_{i}$ in the argument by $f_{i}-\left\langle f_{i}\right\rangle_{g}$ without affecting the value of $u_{m}^{g}$.
(b) Letting $Q_{m-1}$ denote partitions of [1,m-1] and putting $C_{Q_{m}}$ $=(-1)^{\left|Q_{m}\right|-1}\left(\left|Q_{m}\right|-1\right)!$, we have

$$
\begin{equation*}
u_{m}^{g}\left(\left\{f_{i}\right\}_{i}^{m}\right)=\sum_{Q_{m-1}} C_{Q_{m-1}} \sum_{P \in Q_{m-1}}\left\langle f_{P}\left(f_{m}-\left\langle f_{m}\right\rangle\right)\right\rangle_{g} \prod_{\substack{S \in Q_{m-1} \\ S \neq P}}\left\langle f_{s}\right\rangle_{g} \tag{4.9}
\end{equation*}
$$

This may be seen by differentiation of $v \rightarrow u_{m-1}^{g+v f_{m}}\left(\left\{f_{i}\right\}_{1}^{m-1}\right)$, or combinatorically by generating the $Q_{m}$ from the $Q_{m-1}$, by adding the element $m$ in $\left|Q_{m-1}\right|+1$ ways.

The remarks in (a) also follow from (4.9).
(c) Moving back to the general situation in which

$$
v \rightarrow g_{v}, \quad v \rightarrow f_{i, v}, \quad 1 \leqslant i \leqslant m
$$

are differentiable from an open set $I \subset R^{1}$ into $C(\Omega)$, we have that

$$
\begin{equation*}
\frac{d}{d v} u_{m}^{g_{v}}\left(\left\{f_{i, v}\right\}_{1}^{m}\right)=u_{m+1}^{g_{v}}\left(\frac{d g_{v}}{d v},\left\{f_{i, v}\right\}\right)+\sum_{i=1}^{m} u_{m}^{g_{v}}\left(\frac{d f_{i, v}}{d v},\left\{f_{j, v}\right\}_{j \neq i}\right) \tag{4.10}
\end{equation*}
$$

This is an expression of Leibnitz' product rule on the symbols $u_{m}^{g_{0}}()$, $f_{1, v}, \ldots, f_{m, v}$.

### 4.2. Relative Hamiltonian Spaces

We will find it most convenient here to work with the so-called relative Hamiltonian norms on our interactions rather than the usual $\mathscr{P}_{n}$ norms. Let

$$
\begin{equation*}
\Omega_{F}=\bigcup\left\{\Omega_{\Lambda}^{\prime}, \Lambda \text { finite }\right\} \tag{4.11}
\end{equation*}
$$

Then we define $\mathscr{H}_{1}$ to be the space of all continuous real-valued functions $H(\cdot, \cdot)$ on $\Omega_{F}$ satisfying
(i) $H(s, t)=-H(t, s)$
(ii) $H(s, t)=H(s, u)+H(u, t)$ whenever $(s, t) \in \Omega_{\Lambda}^{\prime}$ and $(s, u),(u, t)$ $\in \Omega_{\Lambda}^{\prime}$, for some $\Lambda \subset L$
(iii) $|H|_{1}=\sup _{a \in L}(\sup \{|H(s, t)|: s=t$ off $a\})<\infty$
$\mathscr{H}_{1}$ is the first relative Hamiltonian space, so named because an
interaction $\phi \in \mathscr{P}_{1}$ gives rise to an element of $\mathscr{H}_{1}$ by

$$
\begin{equation*}
H_{\phi}(s, t)=\sum_{\Lambda \subset L}[\phi(s \mid \Lambda)-\phi(t \mid \Lambda)] \tag{4.13}
\end{equation*}
$$

Note that $\mathscr{H}_{1}$ equipped with the norm $|\cdot|_{1}$ is a Banach space and that the canonical map (4.13) takes $\mathscr{P}_{1}$ into $\mathscr{H}_{1}$ continuously-indeed $\left|H_{\varphi}\right|_{1}$ $\leqslant 2\|\varphi\|_{1}$. As is to be expected, relative Hamiltonians are more closely related to their Gibbs states than are interactions ${ }^{(26,27)}$.

Next, define for $H \in \mathscr{H}_{1}, j \in L$ and $\Lambda \subset L-j$

$$
\begin{equation*}
\lambda^{H}(j, \Lambda)=\sup \left[\left|\sum_{\Gamma \subset \Lambda \cup j}(-1)^{|\Gamma|} H\left(s_{\Gamma}, t\right)\right|:(s, t) \in \Omega_{\Lambda \cup j}^{\prime}\right] \tag{4.14}
\end{equation*}
$$

For instance, if $\Lambda=\{i\} \neq\{j\}, s=s_{i \vee} s_{j \vee} \hat{s}$ and $t=t_{i \vee} t_{j \vee} \hat{s}$,

$$
\begin{align*}
& \lambda^{H}(j,\{i\})=\sup \left\{\mid H\left(s_{i \vee} s_{j \vee} \hat{s}, t\right)-H\left(t_{i \vee} s_{j \vee} \hat{s}, t\right)\right. \\
&\left.-H\left(s_{i \vee} t_{j \vee} \hat{s}, t\right) \mid:(s, t) \in \Omega_{\{i, j\}}^{\prime}\right\} \tag{4.15}
\end{align*}
$$

If $\Lambda=\varnothing, \lambda^{H}(j, \varnothing)=\sup \{|H(s, t)|: s=t$ off $j\} \leqslant|H|_{1}$. Define the $n$th relative Hamiltonian norm by

$$
\begin{equation*}
|H|_{n}=\sup _{j} \sum_{\substack{\Lambda \subset L-j \\|\Lambda|=n-1}} \lambda^{H}(j, \Lambda), \quad n=1,2, \ldots \tag{4.16}
\end{equation*}
$$

and the Banach space $\mathscr{H}_{n}$ by

$$
\begin{equation*}
\mathscr{H}_{n}=\left\{H \in \mathscr{H}_{1}:|H|_{m}<\infty, 1 \leqslant m \leqslant n\right\} \tag{4.17}
\end{equation*}
$$

with norm, say,

$$
\|H\|_{n}=\sum_{m=1}^{n}|H|_{n}
$$

If $H=H_{\phi}$ we will write $\lambda^{\phi}$ for $\lambda^{H_{\phi}} . \lambda^{\phi}(i, j)$ measures the rate of decay of the potential: putting (4.13) and (4.14) together one sees that

$$
\begin{equation*}
\lambda^{\phi}(j, \Lambda) \leqslant 2^{|\Lambda|+1} \sup _{s}\left|\sum_{A \supset j \cup \Lambda} \phi(s \mid \Lambda)\right| \tag{4.18}
\end{equation*}
$$

The right-hand side measures the strength of interaction between "spins" in $j \cup \Lambda$. If, for example, $\phi$ has finite range $R$, then $\lambda^{\phi}(j, \Lambda)=0$ whenever the distance between $j$ and $\Lambda$ is greater than $R$. From (4.18) we may derive

$$
\begin{equation*}
\left|H_{\phi}\right|_{n}=\sup _{j} \sum_{\substack{\Lambda: j \neq \Lambda \\|\Lambda|=n-1}} \lambda^{\phi}(j, \Lambda) \leqslant 2^{n} \sup _{j} \sum_{A: j \in A}\binom{|A|-1}{n-1}|\phi(\cdot \mid A)|_{\infty} \tag{4.19}
\end{equation*}
$$

so that the canonical map (4.13) takes $P_{n}$ to $\mathscr{H}_{n}$ continuously.
The estimates we shall come across in the sequel involve expressions of
the form $D_{j \cup \Lambda}\left(k_{\psi}\right), k_{\psi}$ as in (4.1). The relative Hamiltonian norms are particularly well suited to these since (we are now fixing $j$ as in Section 4.1)

$$
\begin{equation*}
D_{j \cup \Lambda}\left(k_{\psi}\right)=\lambda^{\psi}(j, \Lambda), \quad j \notin \Lambda \tag{4.20}
\end{equation*}
$$

and in particular

$$
\begin{equation*}
D_{j}\left(k_{\psi}\right) \leqslant\left|H_{\psi}\right|_{1} \tag{4.21}
\end{equation*}
$$

To see this, note that

$$
\begin{equation*}
D_{j \cup \Lambda}\left(k_{\psi}\right)=\sup _{(s, t) \in \Omega_{A \cup j}^{\prime}}\left|\sum_{A: j \in A} \psi^{j \cup \Lambda}(s, t \mid A)\right|=\sup \left|\sum_{A \subset L} \psi^{j \cup \Lambda}(s, t \mid A)\right| \tag{4.22}
\end{equation*}
$$

by Property 2.3(e). But

$$
\begin{align*}
\sum_{A \subset L} \psi^{j \cup \Lambda}(s, t \mid A) & =\sum_{A \subset L} \sum_{\Gamma \subset j \cup \Lambda}(-1)^{|\Gamma|} \psi\left(s_{\Gamma} \mid A\right) \\
& =\sum_{A \subset L} \sum_{\Gamma \subset j \cup A}(-1)^{|\Gamma|}\left[\psi\left(s_{\Gamma} \mid A\right)-\psi(t \mid A)\right] \\
& =\sum_{\Gamma \subset j \cup \Lambda}(-1)^{|\Gamma|} H_{\psi}\left(s_{\Gamma}, t\right) \tag{4.23}
\end{align*}
$$

since $\sum_{\Gamma}(-1)^{|\Gamma|}=0$. Finally, use (4.14).
We are now in a position to state the two main results of this section.

### 4.3. Proposition on $\alpha_{N}(\phi)$

For $N=1,2, \ldots, \alpha_{N}$, as defined in Section 2.6, is a continuous real-valued function on $\mathscr{P}_{N+1}$. (Hence $\mathscr{D}_{N}$ as defined in 3.1 is an open neighborhood of the origin in $P_{N+1}$.)

The $\alpha_{N}$ are in fact "locally Lipschitz": e.g., for $N=1,2$ we have for $\phi, \phi^{\prime} \in P_{N+1}, H=H_{\phi}$ and $H^{\prime}=H_{\phi^{\prime}}$,

$$
\begin{array}{r}
\left|\alpha_{1}(\phi)-\alpha_{1}\left(\phi^{\prime}\right)\right| \leqslant \frac{1}{2}\left|H-H^{\prime}\right|_{2}+\frac{1}{2}\left|H-H^{\prime}\right|_{1}\left(|H|_{2}+\left|H^{\prime}\right|_{2}\right) \\
\left|\alpha_{2}(\phi)-\alpha_{2}\left(\phi^{\prime}\right)\right| \leqslant\left|H-H^{\prime}\right|_{3}+\frac{1}{2}\left|H-H^{\prime}\right|_{2}\left(|H|_{2}+\left|H^{\prime}\right|_{2}\right) \\
+\left|H-H^{\prime}\right|_{1}\left(\frac{1}{2}|H|_{3}+\frac{4}{3}|H|_{2}^{2}+\frac{4}{3}|H|_{2}\left|H^{\prime}\right|_{2}\right. \\
\left.+\frac{4}{3}\left|H^{\prime}\right|_{2}^{2}+\frac{1}{2}\left|H^{\prime}\right|_{3}\right) \tag{4.24b}
\end{array}
$$

### 4.4. Theorem (Continuity of $\phi \rightarrow \zeta_{j}^{\phi} f$ and Its Derivatives)

Fix $j \in L$
(a) Let $N=0,1,2, \ldots$. If $f \in C^{N}$ and $\phi \in \mathscr{P}_{N+1}$,
(i) $\zeta_{j}^{\phi} f \in C^{N}\left(C^{0}=C(\Omega)\right)$.
(ii)

$$
\begin{equation*}
\left|\zeta_{f}^{\phi} f\right|_{N} \leqslant|f|_{N}+\sum_{m=1}^{N} \alpha_{m}(\phi) \sum_{\Gamma \in V_{N-m}, j \notin \Gamma} D_{\Gamma \in j}(f) \tag{4.25}
\end{equation*}
$$

(where the sum is zero for $N=0$ ).
(iii) $\phi \rightarrow \zeta_{j}^{\phi} f: P_{N+1} \rightarrow C^{N}$ is continuous.
(b) Let $n$ be a natural number, $\psi_{i} \in \mathscr{P}_{1}$ for $1 \leqslant i \leqslant n, \phi \in \mathscr{P}_{1}$ and $f \in C(\Omega)$. Then
(i) The function $\left(u_{1}, \ldots, u_{n}\right) \rightarrow \zeta_{j}^{\phi+\sum u_{i} \psi_{i} f: R^{n} \rightarrow C(\Omega) \text { possesses the }}$ $n$th derivative

$$
\begin{align*}
\partial_{\psi_{1}, \ldots, \psi_{n}} \zeta_{j}^{\phi} f & =\left.\frac{\partial^{n}}{\partial u_{1} \ldots \partial u_{n}} \zeta_{j}^{\phi+\sum u_{i} \psi_{i} f}\right|_{u_{1}=\cdots u_{n}=0} \\
& =u_{n+1}^{g}\left(f, k_{1}, \ldots, k_{n}\right) \tag{4.26}
\end{align*}
$$

where $g=k_{\phi}, k_{1}=k_{\psi_{1}}$ as in (4.1). Moreover, $\phi \rightarrow \partial_{\psi_{1}, \ldots, \psi_{n}} \zeta_{j}^{\phi} f: \mathscr{P}_{1} \rightarrow C(\Omega)$ is continuous for fixed $f \in C(\Omega)$.
(ii) If in addition $\phi, \psi_{1} \in \mathscr{P}_{N+1}(N=0,1, \ldots)$ and $f \in C^{N}$, $\partial_{\psi_{1}, \ldots, \psi_{n}} \zeta_{j}^{\phi} f$ is in $C^{N}$. Moreover, $\phi \rightarrow \partial_{\psi_{1}}, \ldots, \phi_{n} \zeta_{j}^{\phi} f$ is continuous from $\mathscr{P}_{N+1}$ into $C^{N}$, for fixed $f \in C^{N}, \psi_{i} \in \mathscr{P}_{N+1}$.

Estimates of the derivatives are as follows: for $M=0,1, \ldots$,

$$
\begin{equation*}
\left|\partial_{\psi_{\mathrm{k}}, \ldots, \psi_{n}} \zeta_{j}^{\phi} f\right|_{M} \leqslant \sum_{m=1}^{M+1} C_{M, m}\left(\phi,\left\{\psi_{i}\right\}\right) \sum_{\substack{\Lambda \in V_{m-1} \\ j \notin \Lambda}} D_{j \cup \Lambda}(f) \tag{4.27n}
\end{equation*}
$$

where each $C_{M, m}\left(\phi,\left\{\psi_{i}\right\}\right)$ is a polynomial in $\left|H_{\phi}\right|_{l},\left|H_{\psi_{i}}\right|_{l}$ for $1 \leqslant l \leqslant M+1$ (and $1 \leqslant i \leqslant n$ ).

Note that the above estimate is summable over $j$ if $f \in C^{M+1}$.
In concluding the statement of the lemma, we give estimates of those derivatives of $\zeta_{j}^{\phi} f$ needed for establishing the second derivative of the Gibbs state. Let $H^{1}=\left|H_{\psi_{1}}\right|$ etc. Then

$$
\begin{align*}
\left|\partial_{\psi} \zeta_{j}^{\phi} f\right|_{\infty} & \leqslant D_{j}(f) \min \left(\|\psi\|_{1},\left|H_{\psi}\right|_{1}\right)  \tag{4.28}\\
\left|\partial_{\psi_{1}, \psi_{2}} \zeta_{j}^{\phi} f\right|_{\infty} & \leqslant D_{j}(f)\left|H^{1}\right|_{1}\left|H^{2}\right|_{1}  \tag{4.29}\\
\left|\partial_{\psi} \zeta_{j}^{\phi} f\right|_{1} & \leqslant D_{j}(f)\left(\left|H_{\psi}\right|_{2}+\left|H_{\psi}\right|_{1}\left|H_{\psi}\right|_{2}\right)+\sum_{\substack{l \\
l \neq j}} D_{j, l}(f)\left|H_{\psi}\right|_{1} \tag{4.30}
\end{align*}
$$

### 4.5. Estimating $\left|u_{n}\left(\left\{f_{i}\right\}\right)\right|$

As we have seen in Section 4.1, we may write

$$
\begin{equation*}
u_{n}^{g}\left(\left\{f_{i}\right\}_{1}^{n}\right)=\sum_{Q_{n}}^{\prime}(-1)^{\left|Q_{n}\right|}\left(\left|Q_{n}\right|-1\right)!\prod_{S \in Q_{n}}\left\langle\prod_{i \in S}\left(f_{i}-\left\langle f_{i}\right\rangle_{g}\right)\right\rangle_{g} \tag{4.31}
\end{equation*}
$$

where the prime denotes a sum over partitions without a singleton. Since $\sup _{x \in X_{j}}\left|f_{i}\left(x_{\vee} s\right)-\left\langle f_{i}\right\rangle_{g}(s)\right| \leqslant D_{j}\left(f_{i}\right)$, we see that

$$
\begin{equation*}
\left|u_{n}^{g}\left(\left\{f_{i}\right\}_{1}^{n}\right)\right| \leqslant\left[\sum_{Q_{n}}^{\prime}\left(\left|Q_{n}\right|-1\right)!\right] \prod_{i=1}^{n} D_{j}\left(f_{i}\right)=t_{n} \prod_{i=1}^{n} D_{j}\left(f_{i}\right) \tag{4.32}
\end{equation*}
$$

By means of the inclusion-exclusion principle one can derive a formula for $t_{n}$ (Ref. 23, Section 4.11), namely, that $t_{1}=0, t_{2}=1$ and if $n \geqslant 3$,

$$
\begin{align*}
t_{n} & =\sum_{Q_{n}}^{\prime}\left(\left|Q_{n}\right|-1!\right) \\
& =\sum_{r=1}^{[n / 2]} \sum_{k=0}^{r-1} \sum_{l=k}^{r-1} k!\binom{n}{k}\binom{r-1}{l}\binom{l}{k}(r-l)^{n-k-1}(-1)^{l} \tag{4.33}
\end{align*}
$$

(4.32) is the fundamental estimate of this section: we will see that all higher-order differences may be expressed in terms of it.

We note here that, in the case $n=2$, a better estimate may be obtained by means of Schwartz' inequality (as in Ref. 3, Lemma 2), namely,

$$
\begin{equation*}
\left|u_{2}^{g}\left(f_{1}, f_{2}\right)\right| \leqslant \min \left[\left|f_{1}\right|_{\infty}, D_{j}\left(f_{1}\right)\right] \cdot D_{j}\left(f_{2}\right) \tag{4.34}
\end{equation*}
$$

We remark that the estimates (4.32) are themselves a consequence of

$$
\begin{equation*}
\left|u_{n}\right| \leqslant t_{n} \prod_{i=1}^{n} \sup _{x, x^{\prime} \in X_{j}}\left|f_{i}^{[j]}\left(x_{v} s, x_{v}^{\prime} s\right)\right| \tag{4.35}
\end{equation*}
$$

with $s \in \Omega_{L-j}$. Also, the estimates, suitably modified, continue to hold for the situation (mentioned in Section 4.1) in which, for example, $f_{i} \in C(X \times$ $M_{i}$ ).

### 4.6. A Representation for Higher-Order Differences of Ursell Functions

We consider the functions $u_{m+1}(\cdot)$, corresponding to the $m$ th derivative, $m \geqslant 1$. Let $\Lambda \subset L,|\Lambda| \geqslant 1$. We may suppose that $j \notin \Lambda$, since otherwise $\left[u_{m+1}^{g}(\cdot)\right]^{\Lambda} \equiv 0$. Let $(s, t) \in \Omega_{\Lambda}^{\prime}$ and with respect to this pair, put

$$
\left\{\begin{array}{l}
g_{\Gamma}(x)=g\left(x_{\vee} \hat{s}_{\mathrm{r}}\right)  \tag{4.36}\\
k_{i, \mathrm{\Gamma}}(x)=k_{i}\left(x_{\vee} \hat{\Gamma}_{\Gamma}\right), \quad \Gamma \subset \Lambda, \quad 1 \leqslant i \leqslant m+1, \quad x \in X_{j}
\end{array}\right.
$$

Let $v=\left\{v_{a}\right\}_{a \in \Lambda}, 0 \leqslant v_{a} \leqslant 1$ for each $a \in \Lambda$. Put

$$
\begin{equation*}
K\left(\Gamma, \Gamma^{\prime}\right)=\prod_{a \in \Gamma^{\prime}}\left(1-v_{a}\right) \prod_{b \in \Gamma-\Gamma^{\prime}} v_{b}, \quad \Gamma^{\prime} \subset \Gamma \subset \Lambda \tag{4.37}
\end{equation*}
$$

where the empty product is assumed to be unity. Finally, put

$$
\begin{equation*}
g_{v}=\sum_{\Gamma \subset \Lambda} K(\Lambda, \Gamma) g_{\Gamma} \tag{4.38}
\end{equation*}
$$

and similarly for the $k_{i}$.
We note the following properties;
(i)

$$
\begin{equation*}
\sum_{\Gamma^{\prime} \subset \Gamma} K\left(\Gamma, \Gamma^{\prime}\right)=1 \quad \text { for all } \quad \Gamma \subset \Lambda \tag{4.39}
\end{equation*}
$$

(ii) $K\left(\Gamma, \Gamma^{\prime}\right)= \begin{cases}\left(1-v_{c}\right) K\left(\Gamma-c, \Gamma^{\prime}-c\right), & \text { if } c \in \Gamma^{\prime} \\ v_{c} K\left(\Gamma-c, \Gamma^{\prime}\right), & \text { if } c \in \Gamma-\Gamma^{\prime}\end{cases}$
(iii) If $v$ is such that $v_{a}=0$ for all $a \in \Gamma^{\prime}$ and $v_{b}=1$ for all $b \in \Gamma-$ $\Gamma^{\prime}$, then

$$
K(\Lambda, \Gamma)= \begin{cases}1 & \text { if } \Gamma=\Gamma^{\prime}  \tag{4.41}\\ 0 & \text { otherwise }\end{cases}
$$

Hence
(iv)

$$
g_{v}=g_{\Gamma} \quad \text { if } \quad v_{a}= \begin{cases}0, & a \in \Gamma  \tag{4.42}\\ 1 & \text { otherwise }\end{cases}
$$

Of these, (ii)-(iv) are straightforward consequences of the definitions (4.37) and (4.38). (i) may be proved by induction on $\Gamma \subset \Lambda$.

Now put

$$
\begin{equation*}
F(v)=u_{m+1}^{g_{s}}\left(\left\{k_{i, v}\right\}_{i=1}^{m+1}\right)\left(s, s^{\prime}\right) \tag{4.43}
\end{equation*}
$$

As mentioned in Section 4.1, this makes sense as a function on $C\left(\Omega_{\Lambda}^{\prime}\right)$ and is differentiable in $v$. Introduce the notation

$$
\begin{equation*}
\partial_{\Gamma}=\prod_{a \in \Gamma} \frac{\partial}{\partial v_{a}}, \quad \Gamma \subset \Lambda \tag{4.44}
\end{equation*}
$$

The order of integration or differentiation will be immaterial in what follows. We claim that

$$
\begin{equation*}
\left[u_{m+1}^{g}\left(\left\{k_{i}\right\}_{1}^{m+1}\right)\right]^{\Lambda}\left(s, s^{\prime}\right)=\int_{[0,1]^{|\Lambda|}} \partial_{\Lambda} F(v) d v \tag{4.45}
\end{equation*}
$$

(Since the right-hand side involves derivatives of Ursell functions [cf. (4.10)], it is a linear combination of Ursell functions $u_{n+m}, n=1$, $2, \ldots,|\Lambda|+1$. We have thus reduced the problem of estimating the left-hand side to that of the estimates of the previous section.) To see why
(4.45) is true, note that from Section 2.1, (4.42) and (4.43),

LHS (4.45)

$$
\begin{aligned}
& =\sum_{\Gamma \subset \Lambda}(-1)^{|\Gamma|} u_{m+1}^{g_{\Gamma}}\left(\left\{k_{i, \Gamma}\right\}_{1}^{m+1}\right) \\
& =\sum_{\Gamma \subset \Lambda}(-1)^{|\Gamma|} F\left(v_{a}=0 \text { if } a \in \Gamma, 1 \text { otherwise }\right) \\
& =\sum_{\Gamma \subset \Lambda-b}(-1)^{|\Gamma|}\left\{F\left(v_{a}=0 \text { if } a \in \Gamma, v_{a}=1 \text { if } a \in(\Lambda-b)-\Gamma ; v_{b}=1\right)\right. \\
& \left.\quad \quad-F\left(v_{a}=0 \text { if } a \in \Gamma, v_{a}=1 \text { if } a \in(\Lambda-b)-\Gamma ; v_{b}=0\right)\right\}
\end{aligned}
$$

for some $b \in \Lambda$. But by the fundamental theorem of the calculus, this equals

$$
\begin{gather*}
\sum_{\Gamma \subset \Lambda-b}(-1)^{|\Gamma|} \int_{0}^{1} d v_{b} \frac{\partial}{\partial v_{b}} F\left(v_{a}=0 \text { if } a \in \Gamma, v_{a}=1 \text { if } a \in(\Lambda-b)-\Gamma ;\right. \\
\left.v_{b} \text { variable }\right) \tag{4.46}
\end{gather*}
$$

Proceeding by attrition, we arrive at (4.45).
Let us now evaluate the first few derivatives of $F(v)$. If $a \in \Lambda$ we have from (4.10) that

$$
\begin{equation*}
\partial_{a} F(v)=u_{m+2}\left(\partial_{a} g,\left\{k_{i}\right\}_{1}^{m+1}\right)+\sum_{j=1}^{m+1} u_{m+1}\left(\partial_{a} k_{j},\left\{k_{i}\right\}_{i \neq j}\right) \tag{4.47}
\end{equation*}
$$

where we are omitting mention of some indices. If $b \in \Lambda, b \neq a$, we have

$$
\begin{align*}
\partial_{a, b} F(v)= & u_{m+3}\left(\partial_{a} g, \partial_{b} t,\left\{k_{i}\right\}\right)+u_{m+2}\left(\partial_{a, b} g,\left\{k_{i}\right\}\right) \\
& +\sum_{j=1}^{m+1} u_{m+2}\left(\partial_{a} g, \partial b k_{j},\left\{k_{i}\right\}_{i \neq j}\right) \\
& +\sum_{j} u_{m+2}\left(\partial_{b} g, \partial_{a} k_{j},\left\{k_{i}\right\}_{i \neq j}\right) \\
& +\sum_{j} u_{m+1}\left(\partial_{a, b} k_{j},\left\{k_{i}\right\}_{i \neq j_{1}}\right) \\
& +\sum_{j_{1}} \sum_{j_{2} \neq j_{1}} u_{m+1}\left(\partial_{a} k_{j_{1}}, \partial_{b} k_{j_{2}},\left\{k_{i}\right\}_{i \neq j_{1}, i \neq j_{2}}\right) \tag{4.48}
\end{align*}
$$

In order to write a formula for $\partial_{\Lambda} F(v)$ for general $\Lambda$, one evidentily needs some more notation. This will be discussed in Section 4.10 of this paper. In
this section we will concentrate on the existence and continuity of the first two derivatives of the Gibbs state and only indicate a means of proving the full force of Proposition 4.3 and Theorem 4.4. For details see Ref. 23, Section 4.10. With this goal then, it is clear that we will need at least the following estimates of boundedness:

First derivative Second derivative

$$
\begin{array}{rlll}
\partial_{\psi} \zeta_{j}^{\phi}=u_{2}: & C^{1} \rightarrow C^{0} & & C^{2} \rightarrow C^{1}  \tag{4.49}\\
\partial_{\psi_{1}, \psi_{2}} \zeta_{j}^{\phi}=u_{3}: & - & & C^{2} \rightarrow C^{0}
\end{array}
$$

For the continuity of $\phi \rightarrow \zeta_{j}^{\phi} f$, which in our method of proof entails the taking of one derivative, we will need also an estimate of $\left|u_{2}\right|_{\infty},\left|u_{2}\right|_{1}$, and $\left|u_{2}\right|_{2}$. As we shall see, these estimates will also yield the continuity of $\alpha_{1}$ and $\alpha_{2}$ on the appropriate spaces. Thus, what we are looking for are estimates of

$$
\begin{equation*}
\left|u_{2}\right|_{\infty},\left|u_{3}\right|_{\infty},\left|u_{2}\right|_{1}, \text { and }\left|u_{2}\right|_{2} \tag{4.50}
\end{equation*}
$$

It is clear from (4.47) and (4.48) that estimates of $\left|u_{2}\right|_{\infty},\left|u_{3}\right|_{\infty}$, and $\left|u_{4}\right|_{\infty}$ will suffice. In general, for the $n$th derivative, we will need estimates for $\left|u_{l}\right|_{\infty}$, where $l=2, \ldots, n+2$.

### 4.7. Lemma

Ursell functions below are as in (4.7) ( $g$ and $j$ fixed). Let $f, k, k_{1}, k_{2}$, and $k_{3}$ be in $C(\Omega)$ and let $i, j$, and $l$ be distinct points of $L$. Then we have $\left(C^{0}=C(\Omega)\right)$ :
(a) $C^{0}$ estimates:

$$
\begin{gather*}
\left|u_{2}(f, k)\right|_{\infty} \leqslant D_{j}(k) \min \left[|f|_{\infty}, D_{j}(f)\right]  \tag{4.51}\\
\left|u_{3}\left(f, k_{1}, k_{2}\right)\right|_{\infty} \leqslant D_{j}(f) D_{j}\left(k_{1}\right) D_{j}\left(k_{2}\right)  \tag{4.52}\\
\left|u_{4}\left(f, k_{1}, k_{2}, k_{3}\right)\right|_{\infty} \leqslant 4 D_{j}(f) D_{j}\left(k_{1}\right) D_{j}\left(k_{2}\right) D_{j}\left(k_{3}\right) \tag{4.53}
\end{gather*}
$$

(b) $C^{1}$ estimates:

$$
\begin{align*}
& D_{l}\left(u_{2}(f, k)\right) \leqslant D_{j}(f) D_{j, l}(k)+D_{j}(f) D_{j}(k) D_{j, l}(g)+D_{j, l}(f) D_{j}(k) \\
& D_{l}\left(u_{3}\left(f, k_{1}, k_{2}\right)\right) \leqslant D_{j}(f) {\left[D_{j}\left(k_{1}\right) D_{j, l}\left(k_{2}\right)+D_{j, l}\left(k_{1}\right) D_{j}\left(k_{2}\right)\right.}  \tag{4.54}\\
&\left.+4 D_{j}\left(k_{1}\right) D_{j}\left(k_{2}\right) D_{j, l}(g)\right]+D_{j, l}(f) D_{j}\left(k_{1}\right) D_{j}\left(k_{2}\right) \tag{4.55}
\end{align*}
$$

(c) $C^{2}$ estimate:

$$
\begin{aligned}
D_{i, l}\left(u_{2}(f, k)\right) \leqslant D_{j}(f)[ & D_{j, i, l}(k)+\left(D_{j, l}(k) D_{j, i}(g)\right. \\
& \left.\left.+D_{j, i}(k) D_{j, l}(g)\right)+D_{j}(k) D_{j, i, l}(g)\right]
\end{aligned}
$$

+ same expression with $k$ and $f$ interchanged

$$
\begin{equation*}
+4 D_{j}(f) D_{j}(k) D_{j, i}(g) D_{j, l}(g) \tag{4.56}
\end{equation*}
$$

Moreover, suppose that $g=k_{\phi}, k=k_{\psi}, k_{i}=k_{\psi_{i}}$ as in (4.1). Put $H^{i}$ $=H_{\psi_{i}}$ as in (4.13). Then we have
( $\left.a^{\prime}\right) \quad C^{0}$ estimates:

$$
\begin{align*}
\left|u_{2}(f, k)\right|_{\infty} & \leqslant \min \left\{D_{j}(f)\|\psi\|_{1},\left.D_{j}(f)\left|H_{\psi \mid},|f|_{\infty}\right| H_{\psi}\right|_{1}\right\}  \tag{4.57}\\
\left|u_{3}\left(f, k_{1}, k_{2}\right)\right|_{\infty} & \leqslant D_{j}(f)\left|H^{1}\right|_{1}\left|H^{2}\right|_{1}  \tag{4.58}\\
\left|u_{4}\left(f, k_{1}, k_{2}, k_{3}\right)\right|_{\infty} & \leqslant 4 D_{j}(f)\left|H^{1}\right|_{1}\left|H^{2}\right|_{1}\left|H^{3}\right|_{1} \tag{4.59}
\end{align*}
$$

(b') $C^{1}$ estimates:

$$
\begin{equation*}
\left|u_{2}(f, k)\right|_{1} \leqslant D_{j}(f)\left(\left|H_{\psi}\right|_{2}+\left|H_{\psi}\right|_{1} \mid H_{\phi \mid 2}\right)+\sum_{\substack{l \\ l \neq j}} D_{j, l}(f) \cdot\left|H_{\psi}\right|_{1} \tag{4.60}
\end{equation*}
$$

$$
\left|u_{3}\left(f, k_{1}, \dot{j}_{2}\right)\right|_{1} \leqslant D_{j}(f)\left(\left|H^{1}\right|_{1}\left|H^{2}\right|_{2}+\left|H^{1}\right|_{2}\left|H^{2}\right|_{1}+4\left|H^{1}\right|_{1}\left|H^{2}\right|_{1}\left|H_{\phi}\right|_{2}\right)
$$

$$
\begin{equation*}
+\sum_{\substack{l \\ l \neq j}} D_{j, l}(f) \cdot\left|H^{1}\right|_{1}\left|H^{2}\right|_{1} \tag{4.61}
\end{equation*}
$$

(c') $C^{2}$ estimate:

$$
\begin{align*}
\left|u_{2}(f, k)\right|_{2} \leqslant & D_{j}(f)\left(\left|H_{\psi}\right|_{3}+\left|H_{\psi}\right|_{2}\left|H_{\phi}\right|_{2}+2\left|H_{\psi}\right|_{1}\left|H_{\phi}\right|_{2}^{2}+\left|H_{\psi}\right|_{1}\left|H_{\phi}\right|_{3}\right) \\
& +\left|H_{\psi}\right|_{1}\left[\sum_{\substack{i \\
i \neq j}} D_{j, i}(f) \cdot\left|H_{\phi}\right|_{2}+\sum_{\substack{\{i, l\} \in V_{2} \\
j \notin\{i, l\}}} D_{j, i, l}(f)\right] \\
& +\left|H_{\psi}\right|_{2} \sum_{\substack{i \\
i \neq j}} D_{j, i}(f) \tag{4.62}
\end{align*}
$$

This concludes the statement of the lemma. [In deriving the $C^{1}$ and $C^{2}$ estimates, we have only used (4.51) in the form $\left|u_{2}(f, k)\right|_{\infty} \leqslant D_{j}(k) D_{j}(f)$.]

Note that each of the estimates (4.57)-(4.62) is in fact summable over $j \in L$, given that $f, \phi, \psi$ etc. are in appropriate spaces.

Proof. (a) The $C^{0}$ estimates follow directly from (4.32) and (4.34) of Section 4.5, since $t_{2}=t_{3}=1$ and $t_{4}=4$.
(b) For $l \neq j$, let $s, t \in \Omega_{\Lambda-j}$, with $s=t$ off $l$ and consider the specialization of (4.45), namely,

$$
\begin{equation*}
\left[u_{2}(h, k)\right]^{l}=\int_{0}^{1} d v \frac{d}{d v} F(v), \quad v \in R^{1} \tag{4.63}
\end{equation*}
$$

where $F(v)=u_{2}^{g}\left(f_{v}, k_{v}\right)$ as in (4.43) and

$$
\begin{equation*}
g_{v}=v g\left(x_{\vee} s\right)+(1-v) g\left(x_{\vee} t\right)=g_{l}(x)+v\left(g(x)-g_{l}(x)\right) \tag{4.64}
\end{equation*}
$$

and where $g_{l}(x)=g\left(x_{\vee} t\right) ; g(x)=g\left(x_{\vee} s\right)$ as in (4.36). Similarly, $k_{v}=k_{l}+$ $v\left(k-k_{l}\right)$, etc.

Thus, by (4.10),

$$
\begin{align*}
\frac{d F}{d v}(v) & =u_{2}\left(f_{v}, \frac{d k_{v}}{d v}\right)+u_{3}\left(f_{v}, k_{v}, \frac{d g_{v}}{d v}\right)+u_{2}\left(\frac{d f_{v}}{d v}, k_{v}\right) \\
& =u_{2}\left(f_{v}, k-k_{l}\right)+u_{3}\left(f_{v}, k_{v}, g-g_{l}\right)+u_{2}\left(f-f_{l}, k_{v}\right) \tag{4.65}
\end{align*}
$$

But the Ursell function is multilinear and $0 \leqslant v \leqslant 1$, so that

$$
\begin{align*}
\left|\frac{d F}{d v}\right| \leqslant & {\left[v\left|u_{2}\left(f, k-k_{l}\right)\right|+(1-v)\left|u_{2}\left(f_{l}, k-k_{l}\right)\right|\right] } \\
& +\left[v\left|u_{2}\left(f-f_{l}, k\right)\right|+(1-v)\left|u_{2}\left(f-f_{l}, k_{l}\right)\right|\right] \\
& +\left[v^{2}\left|u_{3}\left(f, k, g-g_{l}\right)\right|+v(1-v)\left|u_{3}\left(f, k_{l}, g-g_{l}\right)\right|\right] \\
& +\left[(1-v) v\left|u_{3}\left(f_{l}, k, g-g_{l}\right)\right|+(1-v)^{2}\left|u_{3}\left(f_{l}, k_{l}, g-g_{l}\right)\right|\right] \tag{4.66}
\end{align*}
$$

Now consider, for example,

$$
\begin{align*}
u_{2}\left(f_{l}, k-k_{l}\right) & \equiv u_{2}^{g_{0}(s, t)}\left(f\left(x_{\vee} t\right), k\left(x_{\vee} s\right)-k\left(x_{\vee} t\right)\right) \\
& =u_{2}^{g_{0}(s, t)}\left(f\left(x_{\vee} t\right), k^{l}\left(x_{\vee} s, x_{\vee} t\right)\right) \tag{4.67}
\end{align*}
$$

where we are using the generalized sense of Ursell functions. Since $\sup _{x}\left(\left(k^{\prime}\right)^{j}\right) \leqslant D_{j, l}(k)$ and $\sup _{x, y}\left|f\left(x_{\vee} t\right)-f\left(y_{\vee} t\right)\right| \leqslant D_{j}(f)$, we have from (4.35) that

$$
\begin{equation*}
\left|u_{2}\left(f_{l}, k-k_{l}\right)\right| \leqslant D_{j}(f) D_{j, l}(k) \tag{4.68}
\end{equation*}
$$

as in Section 4.5. Thus we see that each bracketed term in (4.66) has the same estimates for the Ursell functions in it. Indeed, from part (a) of this lemma we have

$$
\begin{equation*}
\left|\frac{d F}{d v}\right| \leqslant D_{j}(f) D_{j, l}(k)+D_{j, I}(f) D_{j}(k)+D_{j}(f) D_{j}(k) D_{j, l}(g) \tag{4.69}
\end{equation*}
$$

Note that the coefficients in $v$ sum to unity in each case. This situation
obtains for general $\Lambda$ and $m$, and is a consequence of multilinearity and (4.39).

Integrating (4.69) over $v$ we arrive at (4.54).
Next we prove (4.55). The above argument is modified by putting

$$
\begin{equation*}
F(v)=u_{3_{v}^{v}}^{\mathcal{v}_{v}}\left(f_{v}, k_{1, v}, k_{2, v}\right) \tag{4.70}
\end{equation*}
$$

so that

$$
\begin{equation*}
\left[u_{3}\left(f, k_{1}, k_{2}\right)\right]^{l}=\int_{0}^{1} d v \frac{d F}{d v} \tag{4.71}
\end{equation*}
$$

and now

$$
\begin{align*}
\frac{d F}{d v}= & u_{3}\left(f_{v}, k_{1}-k_{1, l}, k_{2, v}\right)+u_{3}\left(f_{v}, k_{1, v}, k_{2}-k_{2, l}\right) \\
& +u_{4}\left(f_{v}, k_{1, v}, k_{2, v}, g-g_{l}\right)+u_{3}\left(f-f_{i}, k_{1, v}, k_{2, v}\right) \tag{4.72}
\end{align*}
$$

By a straightforward computation, we may simply drop the $v$ 's and use part (a) to arrive at (4.55).
(c) $C^{2}$ estimate:

We now have the variables $v=\left(v_{i}, v_{l}\right)$ so that $F(v)=u_{2}^{g_{v}}\left(f_{v}, k_{v}\right)$, where, suppressing the unchanged configurations in $\Omega_{\{i, l)} c$,

$$
\begin{gather*}
k=k\left(x_{i}, x_{l}\right), \quad k_{i}=k\left(x_{i}^{\prime}, x_{l}\right) \\
k_{l}=k\left(x_{i}, x_{l}^{\prime}\right), \quad \text { and } k_{i l}=k\left(x_{i}^{\prime}, x_{l}^{\prime}\right)  \tag{4.73}\\
k_{v}=v_{i} v_{l} k+\left(1-v_{i}\right) v_{l} k_{i}+v_{i}\left(1-v_{l}\right) k_{l}+\left(1-v_{i}\right)\left(1-v_{l}\right) k_{i l} \tag{4.74}
\end{gather*}
$$

Now if we write

$$
\begin{align*}
k_{l}^{i} & =k_{l}-k_{i l} \\
k_{i}^{l} & =k_{i}-k_{i l} \tag{4.75}
\end{align*}
$$

and

$$
k^{i l}=k^{\{i, l\}}=k-k_{i}-k_{l}+k_{i l}
$$

then we have

$$
\begin{align*}
\partial_{i} k_{v} & =v_{l}\left(k-k_{i}\right)+\left(1-v_{l}\right)\left(k_{l}-k_{i, l}\right)=v_{l} k^{i}+\left(1-v_{l}\right) k_{l}^{i} \\
& =\sum_{\Gamma \subset\{l\}} K(\{l\}, \Gamma) k_{\Gamma}^{i} \quad[\operatorname{recall}(4.37)]  \tag{4.76}\\
\partial_{l} k_{v} & =v_{i} k^{l}+\left(1-v_{i}\right) k_{i}^{l}
\end{align*}
$$

and

$$
\partial_{i l} k_{v}=k^{i l}
$$

Thus, using (4.48) we have

$$
\begin{align*}
\partial_{i l} F(v)= & {\left[u_{3}\left(\partial_{i} f_{v}, k_{v}, \partial_{l} g_{v}\right)+u_{3}\left(\partial_{l} f_{v}, k_{v}, \partial_{i} g_{v}\right)\right] } \\
& +\left[u_{3}\left(f_{v}, \partial_{i} k_{v}, \partial_{l} g_{v}\right)+u_{3}\left(f_{v}, \partial_{l} k_{v}, \partial_{i} g_{v}\right)\right] \\
& +\left[u_{3}\left(f_{v}, k_{v}, \partial_{i l} g_{v}\right)\right] \\
& +\left[u_{4}\left(f_{v}, k_{v}, \partial_{i} g_{v}, \partial_{l} g_{v}\right)\right] \\
& +\left[u_{2}\left(f_{v}, \partial_{i l} k_{v}\right)\right]+\left[u_{2}\left(\partial_{i l} f_{v}, k_{v}\right)\right] \\
& +\left[u_{2}\left(\partial_{i} f_{v}, \partial_{l} k_{v}\right)+u_{2}\left(\partial_{l} f_{v}, \partial_{i} k_{v}\right)\right] \tag{4.77}
\end{align*}
$$

Now using (4.73) and (4.75) and using the ideas expressed in the proof of the first $C^{1}$ estimate above, we may see that, for example,

$$
\begin{align*}
& \mid u_{3}\left(f_{v}, \partial_{l} k_{v}, \partial_{i} g_{v}\right) \\
& =\mid u_{3}\left(\sum_{\Gamma_{1} \subset\{i, l\}} K\left(\{i, l\}, \Gamma_{1}\right) f_{\Gamma_{1}}, \sum_{\Gamma_{2} \subset\{i\}} K\left(\{i\}, \Gamma_{2}\right) k_{\Gamma_{2}}^{i},\right. \\
& \left.\quad \sum_{\Gamma_{3} \subset\{l\}} k\left(\{l\}, \Gamma_{3}\right) g_{\Gamma_{3}}^{i}\right) \mid \\
& \leqslant \\
& \quad \sum_{\Gamma_{1} \subset\{i, l\}} K\left(\{i, l\}, \Gamma_{1}\right) \sum_{\Gamma_{2} \subset\{i\}} K\left(\{i\}, \Gamma_{2}\right) \sum_{\Gamma_{3} \subset\{l\}} K\left(\{l\}, \Gamma_{3}\right)  \tag{4.78}\\
& \\
& \quad \times\left|u_{3}\left(f_{\Gamma_{1}}, k_{\Gamma_{2}}^{l}, g_{\Gamma_{3}}^{i}\right)\right|
\end{align*}
$$

since $u_{3}(\cdot)$ is multilinear and each $K(\cdot, \cdot)$ is nonnegative. (We have reverted to Section 4.6-notation to give a sneak preview of why we can, in general, drop the $v$ 's.) As we have seen,

$$
\begin{equation*}
\left|u_{3}\left(f_{\Gamma_{\mathrm{I}}}, k_{\Gamma_{2}}^{l}, g_{\Gamma_{3}}^{i}\right)\right| \leqslant D_{j}(f) D_{j}\left(k^{l}\right) D_{j}\left(g^{i}\right)=D_{j}(f) D_{j, l}(k) D_{j, k}(g) \tag{4.79}
\end{equation*}
$$

By (4.39) applied to (4.78), then,

$$
\begin{equation*}
\left|u_{3}\left(f_{v}, \partial_{l} k_{v}, \partial_{i} g_{v}\right)\right| \leqslant D_{j}(f) D_{j, l}(k) D_{j, i}(g) \tag{4.80}
\end{equation*}
$$

and proceeding in this way on (4.77), we have (4.56).
We now turn to the estimates $\left(a^{\prime}\right)$, $\left(b^{\prime}\right)$, and ( $\left.c^{\prime}\right)$. Note firstly that $D_{\Lambda}\left(u_{m}\right) \equiv 0$ whenever $j \in \Lambda$. By (4.20), if $j \notin \Lambda, D_{j \cup \Lambda}\left(k_{\psi}\right)=\lambda^{\psi}(j, \Lambda)$ and thus, by (4.19),

$$
\begin{equation*}
\sum_{\substack{\Lambda \in V_{n} \\ j \notin \Lambda}} D_{j \cup \Lambda}\left(k_{\psi}\right) \leqslant\left|H_{\psi}\right|_{n+1} \tag{4.81}
\end{equation*}
$$

Apply this to part (a) with $n=0$ to get ( $a^{\prime}$ ), and to part (b) with $n=0,1$ to get ( $b^{\prime}$ ). In part (c) a little care with counting is well rewarded (by a factor
of 2): for example,

$$
\begin{equation*}
\sum_{\substack{\{i, l\} \in V_{2} \\ j \notin\{i, l\}}}\left(D_{j, i}(k) D_{j, l}(g)+D_{j, l}(k) D_{j, i}(g)\right) \leqslant\left(\sum_{i} D_{j, i}(k)\right)\left(\sum_{l} D_{j, l}(g)\right) \tag{4.82}
\end{equation*}
$$

since the sum in the left-hand side is over unordered pairs of distinct elements.

### 4.8. Partial Proof of Proposition 4.3

The left-hand sides of (4.24a) and (4.24b) are undefined unless at least one of $\alpha_{n}(\phi), \alpha_{n}\left(\phi^{\prime}\right)$ is finite ( $n=1,2$ respectively). We first demonstrate (4.24a) under this assumption, for otherwise arbitrary $\phi, \phi^{\prime}$ in $\mathscr{P}_{1}$; setting $\phi^{\prime}=0$ shows then that, in fact, $\alpha_{n}(\phi)$ is finite whenever $\phi \in \mathscr{P}_{1,2}$. The continuity is then obvious, similarly for (4.24b).

So suppose that one of $\alpha_{n}(\phi), \alpha_{n}\left(\phi^{\prime}\right)$ is finite (and $\phi, \phi^{\prime} \in \mathscr{P}_{1}$ ). From Section 2.6 we have

$$
\begin{align*}
&\left|\alpha_{n}\left(\phi^{\prime}\right)-\alpha_{n}(\phi)\right|=\frac{1}{2}\left|\sup _{j} \sum_{\Lambda \in V_{n}} R_{\Lambda, j}\left(\phi^{\prime}\right)-\sup _{j} \sum_{\Lambda \in V_{n}} R_{\Lambda, j}(\phi)\right| \\
& \leqslant \frac{1}{2} \sup _{j} \sum_{\Lambda_{\Lambda}} \sup _{(s, t) \in \Omega_{\Lambda}^{\prime}}\left\|\left[\mu_{j}^{\phi^{\prime}}\right]^{\Lambda}(s, t)-\left[\mu_{j}^{\phi}\right]^{\Lambda}(s, t)\right\| \\
& \left.=\frac{1}{2} \sup _{j} \sum_{\sum_{j}^{\Lambda}} \sup _{(s, t)} \sup _{h \in C\left(X_{j}\right)} \right\rvert\,\left[( \mu _ { j } ^ { \phi ^ { \prime } } - \mu _ { j } ^ { \phi } ) \left(\left.h\right|_{\infty}=1\right.\right.  \tag{4.83}\\
& \hline
\end{align*}
$$

(since $h$ does not depend on $\Omega_{\{j\} c}$, we can bring it inside the square brackets). Now

$$
\begin{equation*}
\left(\mu_{j}^{\phi^{\prime}}-\mu_{j}^{\phi}\right)(h)=\int_{0}^{1} d u \frac{d}{d u} \mu_{j}^{\phi+u \psi}(h)=\int_{0}^{1} d u u_{2}(h, k) \tag{4.84}
\end{equation*}
$$

where

$$
\begin{equation*}
\psi=\phi^{\prime}-\phi, \quad g=k_{\phi}, \quad k=k_{\phi^{\prime}-\phi} \tag{4.85}
\end{equation*}
$$

and

$$
f=g+u k=k_{u \phi^{\prime}+(1-u) \phi}
$$

Hence

$$
\begin{equation*}
\left|\alpha_{n}\left(\phi^{\prime}\right)-\alpha_{n}(\phi)\right| \leqslant \frac{1}{2} \sup _{j} \sum_{\substack{\Lambda \in V_{n} \\ j \notin \Lambda}} \sup _{h} \int_{0}^{1} d u D_{\Lambda}(u f(h, k)) \tag{4.86}
\end{equation*}
$$

(where it is understood that $u_{2}$ is with respect to $\left.\zeta_{j}^{u \phi^{\prime}+(1-u) \phi}\right)$.

We now specialize to the instances $n=1,2$. For $n=1$ we have

$$
\begin{align*}
& \sum_{\substack{l \\
l \neq j}} D_{l}\left(u_{2}^{f}(h, k)\right)=\left|u_{2}^{f}(h, k)\right|_{1} \\
& \left.\quad \leqslant\left(\min |h|_{\infty}, D_{j}(h)\right)\left|H_{\phi^{\prime}-\phi}\right|_{2}+D_{j}(h)\left|H_{\phi^{\prime}-\phi}\right|_{1} \mid H_{u \phi^{\prime}+(1-u) \phi \mid 2}\right) \\
& \quad \leqslant\left|H^{\prime}-H\right|_{2}+2\left|H^{\prime}-H\right|_{1}\left(u\left|H^{\prime}\right|_{2}+(1-u)|H|_{2}\right)
\end{align*}
$$

where we have used Lemma $4.7\left(b^{\prime}\right)$ with $D_{j}(h) \leqslant 2|h|_{\infty},|h|_{\infty}=1, D_{j, l}(h)$ $=0$ (since $h \in C\left(X_{j}\right)$ ), and with $H_{\phi}=H, H_{\phi^{\prime}}=H^{\prime}$. By the monotone convergence theorem applied to (4.86), (4.87) yields (4.24a).

For $n=2$, the relevant sum in (4.86) is obtained from Lemma 4.7( $\mathrm{c}^{\prime}$ ) and (4.85), to yield (4.24b).

### 4.9. Partial Proof of Theorem 4.4

(a) Continuity and Boundedness of $\zeta_{j}^{\phi} f$. We will demonstrate that $\left|\zeta_{j}^{\phi} f\right|_{N}<\infty$ for $f \in C^{N}$, then prove continuity of $\phi \rightarrow \zeta_{j}^{\phi} f: \mathscr{P}_{N+1} \rightarrow C^{N}$.

For $N=0$, we know that $\zeta_{j}^{\varphi}$ is a contraction on $C^{0}(=C(\Omega))$ if $\varphi \in \mathscr{P}_{1}$. Also, $\varphi \rightarrow \zeta_{j}^{\varphi} f: \mathscr{P}_{1} \rightarrow C^{0}$ is continuous by usual dominated convergence arguments applied to

$$
\begin{equation*}
\zeta_{j}^{\varphi} f(s)=Z_{\varphi}(s)^{-1} \int_{X_{j}} v_{j}(d x) f\left(x_{\vee} s\right) e^{k_{\varphi}\left(x_{\vee} s\right)} \tag{4.88}
\end{equation*}
$$

using the facts that $\varphi \rightarrow k_{\varphi}: \mathscr{P}_{1} \rightarrow C(\Omega)$ is continuous, and

$$
\begin{equation*}
\left|e^{k_{\varphi}}-e^{k_{\varphi}}\right| \leqslant e^{\left|k_{\varphi}\right|_{\infty}}\left|k_{\varphi}-k_{\varphi^{\prime}}\right|_{\infty} e^{\left|k_{\varphi}-k_{\varphi}\right|_{\infty}} \tag{4.89}
\end{equation*}
$$

Thus part (a) of the theorem is proved for $N=0$.
Suppose $N=1$. We have from (2.26) that

$$
\begin{equation*}
\left|\zeta_{j} f\right|_{1} \leqslant \sum_{\substack{i \\ i \neq j}} D_{i}(f)+\sum_{\substack{i \\ i \neq j}} R_{i, j} D_{j}(f) \leqslant|f|_{1}+\alpha_{1} D_{j}(f) \tag{4.90}
\end{equation*}
$$

proving (4.25) for $N=1$. So suppose $N \geqslant 2$. Now we have

$$
\begin{equation*}
\left|\zeta_{j} f\right|_{N} \leqslant|f|_{N}+\sum_{m=1}^{N} \sum_{\substack{\Lambda \in V_{N} \\ j \notin \Lambda}} \sum_{\Gamma \in V_{m}} R_{\Gamma, j} D_{(\Lambda-\Gamma) \cup j}(f) \tag{4.91}
\end{equation*}
$$

which may be rewritten as

$$
\begin{equation*}
\left|\zeta_{j} f\right|_{N} \leqslant|f|_{N}+\sum_{m=1}^{N} \sum_{\substack{\Gamma \in V_{m} \\ j \notin \Gamma}} R_{\Gamma_{j, j}} \sum_{\substack{\Gamma^{\prime} \in V_{N-m} \\ \Gamma^{\prime} \cap \Gamma=\varnothing \\ j \notin \Gamma^{\prime}}} D_{\Gamma^{\prime} \cup j}(f) \tag{4.92}
\end{equation*}
$$

If we drop the requirement $\Gamma \cap \Gamma^{\prime}=\varnothing$ and use the definition of $\alpha_{N}$ we get (4.25).

Thus we have $\zeta_{j}^{\phi} f \in C^{N}$ and proceed to the $\phi$ continuity. Recalling (2.27),

$$
\begin{align*}
& 2^{|\Lambda|}\left[\zeta_{j}^{\phi} f\right]^{\Lambda}(s, t) \\
& \quad=\sum_{\Gamma, \Gamma^{\prime} \subset \Lambda}(-1)^{\left|\Gamma^{\Gamma^{\prime}}\right|} \int_{X_{j}}\left[\mu_{j}^{\phi}\right]^{\Gamma}\left(d x \mid s_{\Gamma^{\prime}},\left(s_{\Gamma^{\prime}}\right)_{\Gamma}\right) \cdot f^{\Lambda-\Gamma}\left(x_{v} \hat{S}_{\Gamma^{\prime}}, x_{v}\left(\hat{s}_{\Gamma^{\prime}}\right)_{\Lambda-\Gamma}\right) \tag{4.93}
\end{align*}
$$

with $(s, t) \in \Omega_{A}^{\prime}$ and $j \notin \Lambda$. Using the definition (2.4) of the $N$ th-order difference, we write this as

$$
\begin{equation*}
2^{|\Lambda|}\left[\zeta_{j}^{\phi} f\right]^{\Lambda}(s, t)=\sum_{\Gamma, \Gamma^{\prime} \subset \Lambda}(-1)^{\left|\Gamma^{\prime}\right|} \sum_{\Upsilon \subset \Gamma}(-1)^{|\Upsilon|}\left(f_{\Gamma^{\prime}}^{A-\Gamma}\right)_{\phi, \Upsilon, \Gamma, \Gamma^{\prime}} \tag{4.94}
\end{equation*}
$$

where

$$
\begin{gather*}
f_{\Gamma^{\prime}}^{\Lambda-\Gamma}(x)=f^{\Lambda-\Gamma}\left(x_{v} \hat{s}_{\Gamma^{\prime}}, x_{v}\left(\hat{s}_{\Gamma^{\prime}}\right)_{\Lambda-\Gamma}\right)  \tag{4.95}\\
\langle\cdot\rangle_{\phi, \Upsilon, \Gamma, \Gamma^{\prime}}=\int_{X_{j}} \mu_{j}^{\phi}\left(d x \mid\left(s_{\Gamma^{\prime}}\right)_{\Upsilon}\right) \tag{4.96}
\end{gather*}
$$

In (4.96) it is to be understood that the symbol $\left(s_{\Gamma}\right)_{\Upsilon}$ refers to the $|\Gamma|$ th-order difference symbol of $s_{\Gamma^{\prime}}$ on the pair $\left(s_{\Gamma^{\prime}},\left(s_{\Gamma^{\prime}}\right)_{\Gamma}\right)$, which in turn refers to the pair ( $s, t$ ). This is why we retain the subscript $\Gamma$ in the left-hand side of (4.96).

Now select any one triple $\Gamma, \Gamma^{\prime}, \Gamma$. We will, whenever convenient, suppress some indices. Consider $u \rightarrow\left\langle f_{\Gamma^{\prime}}^{\Lambda-\Gamma}\right\rangle_{\phi+u \psi, \Upsilon, \Gamma, \Gamma^{\prime}}$ with a view towards differentiating (4.94). To this end, put

$$
\begin{equation*}
k_{\Gamma^{\prime}}=k_{\psi}\left(x_{v} s_{\Gamma^{\prime}}\right) \tag{4.97}
\end{equation*}
$$

and

$$
k_{\Gamma^{\prime} ; \mathrm{T}}=k_{\psi}\left(x_{v}\left(s_{\Gamma^{\prime}}\right)_{\Upsilon}\right) \quad\left(k_{\phi}=\left(x_{v} s\right)=k\right)
$$

where, again, the switching is with reference to $\left(s_{\Gamma^{\prime}},\left(s_{\Gamma^{\prime}}\right)_{\Gamma}\right)$.
Then by (4.3),

$$
\begin{align*}
\frac{d}{d u}\left\langle f_{\Gamma^{\prime}}^{A-\Gamma}\right\rangle_{\phi+u \psi, \Upsilon, \Gamma, \Gamma^{\prime}}= & \int_{X_{j}} \mu_{j}^{\phi+u \psi}\left(d x \mid\left(s_{\Gamma^{\prime}}\right)_{\Upsilon}\right) \cdot f_{\Gamma^{\prime}}^{A-\Gamma} \\
& \cdot\left(k_{\Gamma^{\prime}, \Upsilon}-\left\langle k_{\Gamma^{\prime}, \Upsilon}\right\rangle_{\phi+u \psi, \Upsilon, \Gamma, \Gamma^{\prime}}\right) \\
= & u_{2}^{\phi+u \psi}\left[k_{\Gamma^{\prime}}, f_{\Gamma^{\Gamma^{-}}}^{\Lambda-\Gamma}\left(s_{\Gamma^{\prime}},\left(s_{\Gamma^{\prime}}\right)_{\Lambda-\Gamma}\right)\right]\left(\left(s_{\Gamma^{\prime}}\right)_{\Upsilon}\right) \tag{4.98}
\end{align*}
$$

where we hope the notation is clear. It emphasizes that the argument $f_{\Gamma^{\prime}}^{\Lambda-\Gamma}$ is independent of $\Upsilon$, because our intention is to differentiate (4.94) and
write the resulting sum over $\Upsilon \subset \Gamma$ there as a $|\Gamma|$ th-order difference. From (4.94), (4.96), and (4.98) we have

$$
\begin{align*}
2^{|\Lambda|} & {\left[\frac{d}{d u} \zeta_{j}^{\phi+u \psi} f\right]^{\Lambda}(s, t) } \\
& =\sum_{\Gamma, \Gamma^{\prime} \subset \Lambda}(-1)^{\left|\Gamma^{\prime}\right|} \sum_{\Upsilon \in \Gamma}(-1)^{|\Upsilon|} u_{2, \Gamma, \Gamma, \Gamma^{\prime}}^{\phi+u \psi}\left(k_{\Gamma^{\prime}}, f_{\Gamma^{\Gamma^{\prime}}}^{\Lambda-\Gamma}\left(s_{\Gamma^{\prime}},\left(s_{\Gamma^{\prime}}\right)_{\Lambda-\Gamma}\right) \cdot\left(\left(s_{\Gamma^{\prime}}\right)_{\Upsilon}\right)\right. \\
& =\sum_{\Gamma, \Gamma^{\prime} \subset \Lambda}(-1)^{\left|\Gamma^{\prime}\right|}\left[\left[u_{2}^{\phi+u \psi}\left(k_{\Gamma^{\prime}}, f_{\Gamma^{\prime}}^{\Lambda-\Gamma}\left(s_{\Gamma^{\prime}},\left(s_{\Gamma^{\prime}}\right)_{\Lambda-\Gamma}\right)\right]\right]^{\Gamma} \cdot\left(s_{\Gamma^{\prime}},\left(s_{\Gamma^{\prime}}\right)_{\Gamma}\right)\right. \tag{4.99}
\end{align*}
$$

Here the double brackets emphasize that the argument of $f_{\Gamma^{\prime}}^{A-\Gamma}$ is unaffected in the taking of the $|\Gamma|$ th-order difference. The advantage of worrying about this is that when we use Lemma 4.7 in estimating $u_{2}$, all terms like $D_{j, l}\left(f_{\Gamma^{\prime}}^{A-\Gamma}\right), D_{j, l, k}\left(f_{\Gamma^{\prime}}^{A-\Gamma}\right)$ are automatically spiflicated.

The next step is to use

$$
\begin{align*}
\left|\zeta_{j}^{\phi^{\prime}} f-\zeta_{j}^{\phi} f\right|_{N} & =\sum_{\Lambda \in V_{N}} D_{\Lambda}\left(\int_{0}^{1} d u \frac{d}{d u} \zeta_{j}^{\phi+u \psi} f\right) \\
& \leqslant \sum_{\Lambda \in V_{N}} \sup _{\Omega_{\Lambda}^{\prime}} \int_{0}^{1} d u\left|\left[\frac{d}{d u} \zeta_{j}^{\phi+u \psi} f\right]^{\Lambda}\right|(\cdot) \tag{4.100}
\end{align*}
$$

That is, from (4.99),

$$
\begin{equation*}
\left|\zeta_{j}^{\phi} f-\zeta_{j}^{\phi^{\prime}} f\right|_{N} \leqslant 2^{-N} \int_{0}^{1} d u \sum_{\Lambda \in V_{N}} \sup _{\Omega_{\Lambda}^{\prime}} \sum_{\Gamma \subset \Lambda} \sum_{\Gamma^{\prime} \subset \Lambda}\left|\left[\left[u_{2}^{\phi+w \psi}\left(k_{\Gamma^{*}}, f_{\Gamma^{\prime}}^{\Lambda-\Gamma}\right)\right]\right]^{\Gamma}\right| \tag{4.101}
\end{equation*}
$$

where $\psi=\phi^{\prime}-\phi$.
We specialize now to the instances $N=1,2$.
(i) $|\Lambda|=1$. For $\Lambda=\{l\}(l \neq j)$, (4.99) gives

$$
\begin{align*}
2\left|\left[\frac{d}{d u} \zeta_{j}^{\phi+u \psi} f\right]^{l}\right| & \leqslant \sum_{\Gamma^{\prime} \subset\{l\}}\left\{\left|u_{2}^{\phi+u \psi}\left(f_{\Gamma^{\prime}}^{l}, k_{\Gamma^{\prime}}\right)\right|+\left|\left[\left[u_{2}^{\phi+u t}\left(f_{\Gamma^{\prime}}^{\oslash}, k_{\Gamma^{\prime}}\right)\right]\right]^{\prime}\right|\right\} \\
& \leqslant \sum_{\Gamma^{\prime} \subset\{l\}}\left[D_{l}(f) D_{j}(k)+D_{j}(f)\left(D_{j, l}(k)+D_{j}(k) D_{j, l}(g)\right)\right] \tag{4.102}
\end{align*}
$$

where we have used (4.51) and (4.54) and the arguments leading to them (with $D_{j, l}(f)$ being set equal to zero.) Here $g=k_{\phi+u \psi}$. Now put $\psi=\phi^{\prime}-\phi$, $H=H_{\phi}, H^{\prime}=H_{\phi^{\prime}}$. Then by (4.20)

$$
\begin{equation*}
D_{j}(k)=\left|H^{\prime}-H\right|_{1}, \quad \sum_{l} D_{j, l}(k)=\left|H-H^{\prime}\right|_{2} \tag{4.103}
\end{equation*}
$$

and

$$
\sum_{l} D_{j, l}(g) \leqslant u\left|H^{\prime}\right|_{2}+(1-u)|H|_{2}
$$

since $0 \leqslant u \leqslant 1$.
Now from (4.101), (4.102), and (4.103) we get

$$
\begin{align*}
\left|\zeta_{j}^{\phi^{\prime}} f-\zeta_{j}^{\phi} f\right|_{1} \leqslant & \left|H^{\prime}-H\right|_{1}|f|_{1} \\
& +D_{j}(f)\left[\left|H-H^{\prime}\right|_{2}+\frac{1}{2}\left|H-H^{\prime}\right|_{1}\left(\left|H^{\prime}\right|_{2}+|H|_{2}\right)\right] \tag{4.104}
\end{align*}
$$

so that $\phi \rightarrow \zeta_{j}^{\phi} f: \mathscr{P}_{2} \rightarrow C^{1}$ is continuous for each $f \in C^{1}$.
(ii) $|\Lambda|=2$. For $\Lambda=\{i, l\}, j \notin \Lambda$, (4.99) gives

$$
\begin{align*}
4\left|\left[\frac{d}{d u} \zeta_{j}^{\phi+u^{4}} f\right]^{i, l}\right| \leqslant & \sum_{\Gamma^{\prime} \subset \Lambda}\left|u_{2}^{\phi+u \psi}\left(f_{\Gamma^{\prime}}^{i, l}, k_{\Gamma^{\prime}}\right)\right|+\left|\left[\left[u_{2}\left(f_{\Gamma^{\prime}}^{l}, k_{\Gamma^{\prime}}\right)\right]\right]^{i}\right| \\
& +\left|\left[\left[u_{2}\left(f_{\Gamma^{\prime}}^{i}, k_{\Gamma^{\prime}}\right)\right]\right]^{l}\right|+\left|\left[\left[u_{2}\left(f_{\Gamma^{\prime}}, k_{\Gamma^{\prime}}\right)\right]\right]^{i, l}\right| \tag{4.105}
\end{align*}
$$

Again, the sum over $\Gamma^{\prime}$ cancels the coefficient 4 on the left-hand side and summing over $\{i, l\}$ using Lemma 4.7 (and setting $D_{j, i}\left(f^{l}\right)=0$ etc. there) we have from (4.103) that

$$
\begin{align*}
\left|\frac{d}{d u} \tau_{j}^{\varphi+u \psi} f\right|_{2} \leqslant & |f|_{2}\left|H-H^{\prime}\right|_{1}+\left(\sum_{l}^{l} D_{j, l}(f)\right) \\
& \times\left[\left|H-H^{\prime}\right|_{2}+\left|H-H^{\prime}\right|_{1}\left(u\left|H^{\prime}\right|_{2}+(1-u)|H|_{2}\right)\right] \\
& +D_{j}(f)\left[\left|H-H^{\prime}\right|_{3}+\left|H-H^{\prime}\right|_{2}\left(u\left|H^{\prime}\right|_{2}+(1-u)|H|_{2}\right)\right. \\
& +\left|H-H^{\prime}\right|_{1}\left(4\left(u\left|H^{\prime}\right|_{2}+(1-u)|H|_{2}\right)^{2}\right. \\
& \left.\left.+u\left|H^{\prime}\right|_{3}+(1-u)|H|_{3}\right)\right] \tag{4.106}
\end{align*}
$$

Again, this integrates in (4.101) to show that $\phi \rightarrow \zeta_{j}^{\phi} f: \mathscr{P}_{3} \rightarrow C^{2}$ is continuous for each $f \in C^{2}$.
(b) (i) $C(\Omega)$ Existence and Continuity of Derivatives. Existence is the content of Section 4.1. Their continuity as functions from $\mathscr{P}_{1}$ into $C(\Omega)$ for $f \in C(\Omega)$ ) follows directly from their representation as Ursell functions in (4.8) and (4.7) and part (a)(iii) of this theorem.
(b) (ii) $C^{N}$ Boundedness and Continuity of the Derivatives. In this partial proof we restrict ourselves to the following cases:

$$
\begin{equation*}
\partial_{\psi} \xi_{j}^{\phi} f: \phi, \psi \in \mathscr{P}_{1}, \quad f \in C(\Omega) \tag{i}
\end{equation*}
$$

$$
\begin{equation*}
\partial_{\psi_{1}, \psi_{2}} \zeta_{j}^{\phi} f: \phi, \psi \in \mathscr{P}_{2}, \quad f \in C^{1} \tag{ii}
\end{equation*}
$$

$$
\begin{equation*}
\partial_{\psi_{1}, \psi_{2}} \zeta_{j}^{\phi} f: \phi, \psi \in \mathscr{P}_{1}, \quad f \in C(\Omega) \tag{iii}
\end{equation*}
$$

Now

$$
\begin{equation*}
\partial_{\psi} \zeta_{j}^{\Phi} f=u_{2}^{\phi}(f, k) \quad \text { and } \quad \partial_{\psi_{1} \psi_{2}} \zeta_{j}^{\phi} f=u_{3} \phi\left(f, k_{1}, k_{2}\right) \tag{4.107}
\end{equation*}
$$

Hence (4.28), (4.29), and (4.30) follow directly from Lemma 4.7: (4.57), (4.58), and (4.60), respectively, and the relative Hamiltonian formulas (4.20), (4.21). Boundedness, given the pertinent locations of $\phi, f, \psi$, etc., is assured $\left(\sum_{\neq j} D_{j, l}(f) \leqslant 2|f|_{1}\right.$, etc.).
[Actually, given the remaining estimates in Lemma 4.7, we have more:

$$
\begin{align*}
\left.\partial_{\psi_{1} \psi_{2} \psi_{3}}\right\}_{j}^{\phi} f \in C(\Omega) & \text { for } \phi, \psi_{1}, \psi_{2}, \psi_{3} \in \mathscr{P}_{1} \text { and } f \in C(\Omega) \\
\left.\partial_{\psi_{1} \psi_{2}}\right\}_{j}^{\phi} f \in C^{1} & \text { for } \phi, \psi_{1}, \psi_{2} \in \mathscr{P}_{2} \text { and } f \in C^{1}  \tag{4.108}\\
\partial_{\psi} \zeta_{j}^{\phi} f \in C^{2} & \text { for } \phi, \psi \in \mathscr{P}_{3} \text { and } f \in C^{2}
\end{align*}
$$

Indeed the number of derivatives does not determine the requirements on $f$ and the interactions. This is borne out in the general case by b(ii) of Theorem 4.4. By contrast, the number of derivatives of $T_{\phi}$ will determine these requirements.]

We turn now to continuity in $\phi$ of the derivatives. Continuity from $\mathscr{P}_{1}$ to $C(\Omega)$ needs no further proof, since Ursell functions are automatically $C(\Omega)$ continuous.

Now, we saw in Section 2.5 that for $\psi \in \mathscr{P}_{N+1}, k_{\psi} \in C^{N}$. Thus by the representation of derivatives of $\zeta_{j}^{\dagger} f$ as Ursell functions as in (4.7), continuity from $P_{N+1}$ to $C^{N}$ follows from part (a)(iii) of this theorem.

This concludes the partial proof.

### 4.10. On the General Estimates and Completion of the Proofs of Proposition 4.3 and Theorem 4.4

Let us first review the extent to which we have established Proposition 4.3 and then state what we need in order to complete its proof.
(i) Proof of Proposition 4.3. The basic inequality required is (4.86). Suppose we can find some estimate

$$
\begin{equation*}
|u f(h, k)|_{n} \leqslant \eta\left(\phi, \phi^{\prime}, u\right) \tag{4.109}
\end{equation*}
$$

independent of $j \in L, h \in C\left(X_{j}\right),|h|_{\infty}=1$ and such that $\eta\left(\phi, \phi^{\prime}, u\right)$ is a linear combination of $\left|H_{\phi}-H_{\phi^{\prime}}\right|_{m}, 1 \leqslant m \leqslant n+1$, with coefficients possibly involving $\left|H_{\phi}\right|_{m},\left|H_{\phi}\right|_{m}, 1 \leqslant m \leqslant n+1$ and polynomials in $u$. Then we will have established Proposition 4.3.

But this is quite straightforward given the formalism developed in

Section 4.6. Recalling (4.43), for $\Lambda \in V_{n}$ and $\left(s, s^{\prime}\right) \in \Omega_{\Lambda}^{\prime}$, we have

$$
\begin{equation*}
F(v)=u_{2}^{f_{0}}\left(h, k_{v}\right), \quad v=\left\{v_{a}\right\}_{a \in \Lambda} \tag{4.110}
\end{equation*}
$$

where

$$
\begin{align*}
f_{v} & =\sum_{\Gamma \subset \Lambda} K(\Lambda, \Gamma) f_{\Gamma}  \tag{4.111}\\
f_{\Gamma}(x) & =f\left(x_{v} \hat{s}_{\Gamma}\right)
\end{align*}
$$

and similarly for $k_{v}$. Note that $h_{v}=h$, as $h$ does not depend upon spins outside $j$. For $\Gamma \subset \Lambda$, let $Q_{\Gamma}$ run over (unordered) partitions of $\Gamma$. Then we claim that

$$
\begin{equation*}
\partial_{\Lambda} F(v)=u_{2}^{f_{0}}\left(h, \partial_{\Lambda} k_{v}\right)+\sum_{\substack{\Gamma \subset \Lambda \\ \Gamma \neq \emptyset}} \sum_{Q_{\Gamma}} u_{2}^{f_{v}}+\left|Q_{\Gamma}\right|\left(h, \partial_{\Lambda-\Gamma} k_{v},\left\{\partial_{P} f_{v}\right\}_{P \in Q_{\Gamma}}\right) \tag{4.112}
\end{equation*}
$$

This may be proved by induction, by first replacing $\Lambda$ above with $\Upsilon \subset \Lambda$ ( $v=\left\{v_{a}\right\}_{a \in \Lambda}$ ) and using (4.10) [recall (4.47) and (4.48)].

Now we may generalize (4.76) above for the derivatives of $v \rightarrow k_{v}$ by defining, for $\Gamma$ and $\Gamma^{\prime}$ disjoint subsets of $\Lambda$,

$$
\begin{equation*}
k_{\Gamma^{\prime}}^{\Gamma}=k^{\Gamma}\left(x_{v} \hat{s}_{\Gamma^{\prime}}, x_{v} \hat{s}_{\Gamma^{\prime} \cup \Gamma}\right), \quad \Gamma_{\cap} \Gamma^{\prime}=\emptyset \tag{4.113}
\end{equation*}
$$

Then we may write any derivatives as

$$
\begin{equation*}
\partial_{\Gamma} k_{v}=\sum_{\Gamma^{\prime} \subset \Lambda-\Gamma} K\left(\Lambda-\Gamma, \Gamma^{\prime}\right) g_{\Gamma^{\prime}}^{\Gamma}, \quad \Gamma \subset \Lambda \tag{4.114}
\end{equation*}
$$

This may be proved (Ref. 23) by induction on $\Gamma$, using (4.40) and Proposition $2.2(\mathrm{c})$. Thus we have, returning to (4.112), that $\partial_{\Lambda} k_{v}=k^{\Lambda}$, whereas,

$$
\begin{equation*}
\partial_{\Lambda-\Gamma} k_{v}=\sum_{\Gamma_{1} \subset \Gamma} K\left(\Gamma, \Gamma_{1}\right) k_{\Gamma_{1}}^{\Lambda-\Gamma} \tag{4.115}
\end{equation*}
$$

and

$$
\begin{equation*}
\partial_{P} f_{v}=\sum_{\Gamma_{2} \subset \Lambda-P} K\left(\Lambda-P, \Gamma_{2}\right) f_{\Gamma_{2}}^{P} \tag{4.116}
\end{equation*}
$$

Applying these to (4.112) we have

$$
\begin{align*}
\partial_{\Lambda} F(v)= & u_{2}^{f_{v}}\left(h, k^{\Lambda}\right) \\
& +\sum_{\substack{\Gamma \subset \Lambda \\
\Gamma \neq \emptyset}} \sum_{Q_{\Gamma}}\left[\sum_{\Gamma_{1} \subset \Gamma} K\left(\Gamma, \Gamma_{1}\right)\right]\left[\prod_{P \in Q_{\Gamma}} \sum_{\Gamma_{2} \subset \Lambda-P} K\left(\Lambda-P, \Gamma_{2}\right)\right] \\
& \times u_{2+\mid Q_{\Gamma}( }^{f_{0}}\left(h, k_{\Gamma_{1}}^{\Lambda-\Gamma},\left\{f_{\Gamma_{2}}^{P}\right\}_{P \in Q_{\mathrm{R}}}\right) \tag{4.117}
\end{align*}
$$

We may now estimate $\partial_{\Lambda} F(v)$ by employing (4.32), which says here that $\left(D_{j}(h) \leqslant 2|h|_{\infty} \leqslant 2\right)$

$$
\begin{equation*}
\left|u_{2+\left|Q_{\Gamma}\right|}^{f_{p}}\left(h, k_{\Gamma_{1}}^{\Lambda-\Gamma},\left\{f_{\Gamma_{2}}^{P}\right\}_{P \in Q_{r}}\right)\right| \leqslant 2 t_{2+\left|Q_{r}\right|} D_{j \cup(\Lambda-\Gamma)}(k) \prod_{P \in Q_{\Gamma}} D_{j \cup P}(f) \tag{4.118}
\end{equation*}
$$

i.e., independently of $\Gamma_{1}$ and $\Gamma_{2}$. Since each of the square-bracketed terms in (4.117) involving $K(\cdot, \cdot)$ is equal to unity as in (4.39), we have that

$$
\begin{align*}
D_{\Lambda}\left(u_{2}(h, k)\right) \leqslant & D_{j \cup \Lambda}(k)+2 \sum_{\substack{\Gamma \subset \Lambda \\
\Gamma \neq \emptyset}} \sum_{Q_{\Gamma}} t_{2+\left|Q_{\Gamma}\right|} D_{j \cup(\Lambda-\Gamma)}(k) \prod_{P \in Q_{\Gamma}} D_{j_{\cup} P}(f) \\
\leqslant & \lambda^{\phi^{\prime}-\phi}(j, \Lambda) \\
& +2 \sum_{\substack{\Gamma \in \Lambda \\
\Gamma \neq \emptyset}} \lambda^{\phi^{\prime}-\phi}(j, \Lambda-\Gamma) \sum_{Q_{\Gamma}} t_{2+\left|Q_{r}\right|} \prod_{P \in Q_{\Gamma}} \lambda^{u \phi^{\prime}+(1-u) \phi}(j, P) \tag{4.119}
\end{align*}
$$

where we have used (4.45), (4.75), and (4.20). Of course, if $j \in \Lambda$ then $D_{\Lambda}\left(u_{2}(h, k)\right)=0$. Now we wish to sum over $\Lambda \in V_{n}, j \notin \Lambda$ to get an estimate as in (4.109). This is worked out in Ref. 25, pp. 106 and 107; here we present the result. A partition of the number $N$ of length $p$ is a collection $\mathscr{T}_{p}^{(N)}=\left\{\xi_{1}, \ldots, \xi_{p}\right\}$ of strictly positive integers such that $N=\sum_{i=1}^{p} \xi_{i}$. We have then that (4.119) sums to

$$
\begin{align*}
\left|u_{2}(h, k)\right|_{n} \leqslant\left|H_{\varphi}-H_{\varphi^{\prime}}\right|_{n+1} & \\
+2 \sum_{m=1}^{n}\left|H_{\varphi}-H_{\varphi^{\prime}}\right|_{m}[ & \sum_{p=1}^{n-m+1} t_{2+p} \sum_{\mathscr{F}_{p}^{(n-m+1)}} \\
& \times \prod_{\xi \in \mathscr{T}_{p}^{(n-m+1)}} \mid H_{\left.n \varphi+\left.(1-u) \varphi^{\prime}\right|_{\xi+1}\right]} \tag{4.120}
\end{align*}
$$

Applying this to (4.86), we have proved Proposition 4.3.
(ii) Proving Theorem 4.4. What remains to be done in the proof of the Theorem? In part (a), we need to prove continuity of $\varphi \rightarrow \zeta_{j}^{\varphi}: \mathscr{F}_{N+1}$ $\rightarrow C^{N}$. In part (b), we have to establish (ii), which is a question of proving (4.27). For once we have that estimate, the $n$th derivative is in $C^{N}$ for $\varphi, \psi_{i} \in \mathscr{P}_{N+1}$. The continuity result of part (a) then serves to complete the proof.

It is clear from Section 4.9 that what we need, in order to prove continuity and boundedness as above, is an estimate generalizing those of Lemma 4.7 and (4.120). Indeed, with the $n$th derivative of $\zeta_{j}$ replaced by the $(n+1)$ th Ursell function, $(4.27)$ is one such estimate and may be found by a simple though tedious extension of the arguments in part (i) of this subsection (see Ref. 23, pp. 107-114).

## 5. CONTINUOUS DIFFERENTIABILITY OF THE GIBBS STATE

In the following $\mathscr{T}_{N}$ is the $N$ th Dobrushin uniqueness region defined in Section 3.1, the spaces $C^{N}$ are defined in Section 2.5 and the $\mathscr{P}_{N}$ in Section 1. Note the relationship (4.19) between the $n$th relative Hamiltonian norm and the $\mathscr{P}_{n}$ norm.

### 5.1. Theorem

Let $\phi \in \mathscr{D}_{N}$ and $\sigma_{\phi}(\cdot)$ be the unique Gibbs state corresponding to $\phi$. For each $f \in C^{N}$, the function $\phi \rightarrow \sigma_{\phi}(f): \mathscr{D}_{N} \rightarrow R^{1}$ is $N$ times continuously Gateaux differentiable in $\mathscr{P}_{N+1}$ directions. That is, for each $n$ with $1 \leqslant n \leqslant N$, and for each collection $\left\{\psi_{1}\right\}_{i=1}^{n}, \psi_{i} \in \mathscr{P}_{N+1}, 1 \leqslant i \leqslant n$,

$$
\begin{equation*}
\left(\partial_{\psi_{1}, \ldots, \psi_{n}^{\sigma}}\right)_{\phi}(f)=\left.\frac{\partial^{n}}{\partial u_{1} \ldots \partial u_{n}} \sigma_{\phi+} \sum_{i=1}^{n} u_{i} \psi_{i}(f)\right|_{u_{1}=\cdots=u_{m}}=0 \tag{5.1}
\end{equation*}
$$

exists and is continuous on $\mathscr{D}_{N}$.
Moreover, under these conditions, the expression (5.1) is bounded in absolute value by a polynomial in the variables

$$
|f|_{M}, \alpha_{M}(\phi),\left|H_{\psi_{i}}\right|_{M} \text { and }\left|H_{\phi}\right|_{M}, \quad 1 \leqslant M \leqslant N
$$

and

$$
\frac{1}{1-\alpha_{1}(\phi)},\left|H_{\psi_{i}}\right|_{N+1}, \text { and }\left|H_{\phi}\right|_{N+1}
$$

where the $H$ and $|H|_{M}$ are as in (4.10) and (4.12).
The derivative is given by the convergent sum

$$
\begin{align*}
\left(\partial_{\psi_{1}, \ldots, \psi_{n}} \sigma\right)_{\phi}(f) & \equiv \partial_{\left\{\psi_{i}\right\}_{1}^{n} \sigma_{\phi}}(f) \\
& =\sum_{Q_{n}}^{\prime} \sigma_{\phi}\left(\left\{\prod_{P \in Q_{n}}^{\prime}\left(\partial_{P} T_{\phi}\left(I-T_{\phi}\right)^{-1}\right)\right\}[f]\right) \tag{5.2}
\end{align*}
$$

where: the primed sum is over ordered partitions of the set $\{1,2, \ldots, n\}$,

$$
\begin{equation*}
\partial_{P} T_{\phi} g=\partial_{\left\{\psi_{i}\right\}_{\in P}} T_{\phi} g \tag{5.3}
\end{equation*}
$$

(whose existence and continuity is the content of Lemma 5.4), $[f]$ is the equivalence class modulo constants of $f$ in $C^{N},\left(I-T_{\phi}\right)^{-1}$ is the inverse of $I-T_{\phi}$ acting on $\tilde{C}^{N}$ and is given by

$$
\begin{equation*}
\left(I-T_{\varphi}\right)^{-1}[f]=\sum_{k=0}^{\infty}\left[T_{\phi}^{k} f\right] \tag{5.4}
\end{equation*}
$$

and finally, where the primed product represents an ordered product: if $Q_{n}=\left(P_{1}, \ldots, P_{m}\right)$ is an ordered partition, then

$$
\begin{aligned}
& \prod_{P \in Q_{n}}^{\prime}\left(\partial_{P} T_{\phi}\left(I-T_{\phi}\right)^{-1}\right) \\
& \quad=\partial_{P_{1}} T_{\phi}\left(I-T_{\phi}\right)^{-1} \partial_{P_{2}} T_{\phi}\left(I-T_{\phi}\right)^{-1} \cdots \partial_{P_{m}} T_{\phi}\left(I-T_{\phi}\right)^{-1}
\end{aligned}
$$

### 5.2. Bounds on the First and Second Derivatives

In the cases $N=1,2$, the expression (5.2) becomes

$$
\begin{align*}
\partial_{\psi} \sigma_{\phi}(f)= & \sigma_{\phi}\left(\partial_{\psi} T_{\phi} \cdot\left(I-T_{\phi}\right)^{-1}[f]\right)=\sum_{k=0}^{\infty} \sigma_{\phi}\left(\partial_{\psi} T_{\phi} \cdot T_{\phi}^{k} f\right)  \tag{5.5}\\
\partial_{\psi_{1} \psi_{2}} \sigma_{\phi}(f)= & \sigma_{\phi}\left(\partial_{\psi_{1}} T_{\phi} \cdot\left(I-T_{\phi}\right)^{-1} \cdot \partial_{\psi_{2}} T_{\phi} \cdot\left(I-T_{\phi}\right)^{-1}[f]\right) \\
& +\sigma_{\phi}\left(\partial_{\psi_{2}} T_{\phi} \cdot\left(I-T_{\phi}\right)^{-1} \cdot \partial_{\psi_{1}} T_{\phi}\left(I-T_{\phi}\right)^{-1}[f]\right) \\
& +\sigma_{\phi}\left(\partial_{\psi_{1} \psi_{2}} T_{\phi}\left(I-T_{\phi}\right)^{-1}[f]\right) \\
= & \sum_{l=0}^{\infty} \sum_{k=0}^{\infty}\left\{\sigma_{\phi}\left(\partial_{\psi_{1}} T_{\phi} \cdot T_{\phi}^{k} \cdot \partial_{\psi_{2}} T_{\phi} \cdot T_{\phi}^{l} f\right)\right. \\
& \left.+\sigma_{\phi}\left(\partial_{\psi_{2}} T_{\phi} \cdot T_{\phi}^{k} \cdot \partial_{\psi_{2}} T_{\phi} \cdot T_{\phi}^{l} f\right)\right\}+\sum_{k=0}^{\infty} \sigma_{\phi}\left(\partial_{\psi_{1} \psi_{2}} T_{\phi} \cdot T_{\phi}^{k} f\right) \tag{5.6}
\end{align*}
$$

The second equality in each case will be seen to be true in the proof of Theorem 5.1. The series in (5.5) was provided by L. Gross, ${ }^{(3)}$ who also showed that

$$
\begin{equation*}
\left|\partial_{\psi} \sigma_{\phi}(f)\right| \leqslant \frac{\|\psi\|_{1}|f|_{1}}{\left[1-\alpha_{1}(\phi)\right]^{2}} \tag{5.7}
\end{equation*}
$$

Here we shall also explicitly demonstrate that, with $H^{i}=H_{\psi_{i}}, i=1,2$, and $\alpha_{1}=\alpha_{1}(\phi), \alpha_{2}=\alpha_{2}(\phi)$,

$$
\begin{aligned}
& \left|\partial_{\psi_{1} \psi_{2}} \sigma_{\phi}(f)\right| \\
& \leqslant \\
& \leqslant
\end{aligned} \begin{aligned}
\leqslant & \frac{1}{2\left(1-\alpha_{1}\right)^{2}}\left|H^{1}\right|_{1}\left|H^{2}\right|_{1}|f|_{1} \\
& +\frac{\left\|\psi_{1}\right\|_{1}}{\left(1-\alpha_{1}\right)^{2}}\left\{\frac{1}{\left(1-\alpha_{1}\right)}\left(\left|H^{2}\right|_{2}+\left|H^{2}\right|_{1}\left|H_{\phi}\right|_{2}\right)|f|_{1}\right.
\end{aligned} \quad \begin{aligned}
& +\frac{1}{1-\alpha_{1}}\left|H^{2}\right|_{1}\left[2|f|_{2}+\frac{2 \alpha_{2}}{\left(1-\alpha_{1}\right)^{2}}|f|_{1}\right. \\
& +\frac{\left.\left.\| \alpha_{2}\left(1+\frac{2}{1-\alpha_{1}}\right)|f|_{1}\right]+2\left\|\psi_{2}\right\|_{1}|f|_{1}\right\}}{\left(1-\alpha_{1}\right)^{4}}\left\{\left(\left|H^{2}\right|_{2}+\left|H^{2}\right|_{1}\left|H_{\phi}\right|_{2}\right)|f|_{1}+\left|H^{2}\right|_{1}\right. \\
& \left.\left.\times\left[\alpha_{2}\left(1+\frac{2}{1-\alpha_{1}}\right)|f|_{1}+2|f|_{2}+\frac{\alpha_{2}}{\left(1-\alpha_{1}\right)^{2}}|f|_{1}\right]\right\}\right)
\end{aligned}
$$

$$
+\left\{\text { same expression with } \psi_{1} \leftrightarrow \psi_{2} \text { and } H^{1} \leftrightarrow H^{2}\right\}
$$

$$
\leqslant\left(\frac{2}{\left(1-\alpha_{1}\right)^{2}}\left\|\psi_{1}\right\|_{1}\left\|\psi_{2}\right\|_{1}|f|_{1}+\frac{\left\|\psi_{1}\right\|_{1}}{\left(1-\alpha_{1}\right)^{2}}\right.
$$

$$
\times\left[\frac{4}{1-\alpha_{1}}\left(\left\|\psi_{2}\right\|_{2}+2\left\|\psi_{2}\right\|_{1}\|\phi\|_{2}\right)|f|_{1}+\frac{2}{1-\alpha_{1}}\left\|\psi_{2}\right\|_{1}\left(2|f|_{2}\right.\right.
$$

$$
\left.+\frac{2 \alpha_{2}}{\left(1-\alpha_{1}\right)^{2}}|f|_{1}+\alpha_{2}\left(1+\frac{2}{1-\alpha_{1}}\right)|f|_{1}+2\left\|\psi_{2}\right\|_{1}|f|_{1}\right]
$$

$$
+\frac{\left\|\psi_{1}\right\|_{1}}{\left(1-\alpha_{1}\right)^{4}}\left\{4\left(\left\|\psi_{2}\right\|_{2}+2\left\|\psi_{2}\right\|_{1}\|\phi\|_{2}\right)|f|_{1}\right.
$$

$$
+2\left\|\psi_{2}\right\|_{1}\left[\alpha_{2}\left(1+\frac{2}{1-\alpha_{1}}\right)|f|_{1}+2|f|_{2}\right.
$$

$$
\left.\left.\left.+\frac{\alpha_{2}}{\left(1-\alpha_{1}\right)^{2}}|f|_{1}\right]\right\}\right)
$$

$$
\begin{equation*}
+\left\{\text { same expression with } \psi_{1} \leftrightarrow \psi_{2}\right\} \tag{5.8}
\end{equation*}
$$

(where we have used the facts that $\left|H_{\psi}\right|_{1} \leqslant 2\|\psi\|_{1}$ and $\left|H_{\psi}\right|_{2} \leqslant 4\|\psi\|_{2}$ [see (4.19)]). Indeed, the estimates of the following lemmas along with the series expansions for the deviatives provide us with a systematic procedure for estimating the size of any derivative of the Gibbs state. However, a notation appropriate to an arbitrary number of derivatives awaits full development.

### 5.3. Lemma: The Boundedness and Continuity of $T_{\phi}$

For each $k \in[1, \infty)$ and $p \in[k, \infty)$, the operator $T_{\phi, k, p}$ is a contraction on $C(\Omega)$ for $\phi \in \mathscr{P}_{1}$. Also, $\phi \rightarrow T_{\phi, k, p} f$ is continuous for each $f \in C(\Omega)$.

Let $N=1,2, \ldots$. Then for $\phi \in \mathscr{D}_{N}, T_{\phi, k, p}$ is a bounded linear operator on $C^{N}$. Moreover, for each $f \in C^{N}$, the function $\phi \rightarrow T_{\phi, k, p} f: \mathscr{D}_{N} \rightarrow C^{N}$ is continuous.
(See Theorem 3.2 for a bound on $\left|T_{\phi, k, p} f\right|_{N}$ and Remark 3.3(c) for the instances $N=1,2$, and 3.)

Proof. The contractivity on $C(\Omega)$ was shown in Section 1.2. For $p<\infty, \phi \rightarrow T_{\phi, k_{p}} f: \mathscr{P}_{1} \rightarrow C(\Omega)$ is continuous since $T_{\phi, k, p}$ is a finite product of $\phi$-continuous operators (Section 4.1). But $T_{\phi,, k p} f$ converges uniformly (in $\phi)$ to $T_{\phi, k, \infty} f$, in the space $C(\Omega)$. Thus continuity is assured for each $p \leqslant \infty$.

Let now $N \geqslant 1$. By Theorem 3.2, $T_{\phi, k, p}$ is a bounded linear operator on $C^{N}$. If $p<\infty$, Theorem 4.4(a) assures us that $\zeta_{p}^{\phi} f \in C^{N}$ for $f \in C^{N}$ and $\phi \in \mathscr{D}_{N} \subset \mathscr{P}_{N+1}$ and moreover that $\phi \rightarrow \zeta_{p}^{\phi} f: \mathscr{D}_{N} \rightarrow C^{N}$ is continuous. Thus the same holds for $\zeta_{p-1}^{\phi}\left(\zeta_{p}^{\phi} f\right)=T_{\phi, p-1, p} f$. In other words, $T_{\phi, k, p} f$ is continuous into $C^{N}$ whenever $p<\infty$.

If $g$ is a continuous cylinder function, there is some $q<\infty$ such that

$$
T_{\phi, k, \infty} g= \begin{cases}T_{\phi, k, q} g & \text { if } \quad k \leqslant q  \tag{5.9}\\ g & \text { if } \quad k>q\end{cases}
$$

Hence in this case $T_{\phi, k, p} g$ is continuous, for all $p \leqslant \infty$, from $\mathscr{D}_{N}$ into $C^{N}$. Let $\left\{g_{n}\right\}$ be a sequence of cylinder functions tending to $f$ in $C^{N}$, i.e., $\left|f-g_{n}\right|_{M} \rightarrow 0$ for $1 \leqslant M \leqslant N$. Put

$$
\begin{equation*}
B_{r}^{N}=\left\{\phi \in \mathscr{P}_{N+1}: \alpha_{1}(\phi) \leqslant r \text { and } \alpha_{M}(\phi) \leqslant \frac{1}{1-r}, 1 \leqslant M \leqslant N\right\} \tag{5.10}
\end{equation*}
$$

Then $\mathscr{D}_{N}=\bigcup_{r<1} B_{r}^{N}$. We see from (3.2) and its adjuncts (3.3), (3.4), and (3.6) that the bound given in the right-hand side of (3.2) is uniform in $\phi$ for $\phi \in B_{r}^{N}, r<1$. Moreover, it involves only those $|f|_{M}$ for which $1 \leqslant M$ $\leqslant N$. Set $p=\infty$ so that $E^{p} \equiv 0$. Then it is clear that $\left|T_{\phi, k, \infty} f-T_{\phi, k, \infty} g_{n}\right|_{M}$ $\rightarrow 0$ for each $M \leqslant N$, and uniformly in $\phi \in B_{r}^{N}$. Thus $\phi \rightarrow T_{\phi, k, \infty} f: B_{r}^{N}$ $\rightarrow C^{N}$ is continuous. Finally, let $r \uparrow 1$.

### 5.4. Lemma: Existence, Boundedness, and Continuity of Derivatives of $T_{\phi}$

We will sometimes suppress the symbol $\phi$ in the equations that follow. Also, write $T=T_{1, \infty}, T_{k}=T_{k, \infty}$.
(a) If $n$ is a natural number, $\phi \in \mathscr{D}_{n}, \psi_{i} \in \mathscr{P}_{n+1}(1 \leqslant i \leqslant n)$ and $f \in C^{n}$, the function

$$
\begin{equation*}
\left(u_{1}, \ldots, u_{n}\right) \rightarrow T_{\phi+\sum_{i} u_{i} \psi_{i}} f: R^{n} \rightarrow C(\Omega) \tag{5.11}
\end{equation*}
$$

possesses the $n$th mixed derivative

$$
\begin{equation*}
\left(\partial_{\psi_{1}, \ldots, \psi_{n}} T\right)_{\phi} f=\left.\frac{\partial^{n}}{\partial u_{1} \ldots \partial u_{n}} T_{\phi+\sum_{i} u_{i} \psi_{i}} f\right|_{u_{1}=\cdots=u_{n}=0} \tag{5.12}
\end{equation*}
$$

Moreover, this derivative is, for fixed $f$ and $\left\{\psi_{i}\right\}$, continuous as a function of $\phi$ from $\mathscr{D}_{n}$ into $C^{n}$.

In fact, we may describe the derivative by a $C(\Omega)$ convergent sum as follows:

$$
\begin{align*}
\partial_{\psi} T f= & \sum_{j=1}^{\infty} T_{1, j-1} \cdot\left(\partial_{\psi} \zeta_{j}\right)\left(T_{j+1} f\right)  \tag{5.13}\\
\partial_{\psi_{1}, \psi_{2}} T f= & \sum_{j=1}^{\infty} T_{1, j-1} \cdot\left(\partial_{\psi_{1}, \psi_{2}} \zeta_{j}\right)\left(T_{j+1} f\right) \\
& +\sum_{j=1}^{\infty} \sum_{k>j}\left\{T_{1, j-1} \cdot\left(\partial_{\psi_{1}} \zeta_{j}\right)\left[T_{j+1, k-1}\left(\partial_{\psi_{2}} \zeta_{k}\right)\left(T_{k+1} f\right)\right]\right. \\
& \left.\quad+T_{1, j-1}\left(\partial_{\psi_{2}} \zeta_{j}\right)\left[T_{j+1, k-1}\left(\partial_{\psi_{1}} \zeta_{k}\right)\left(T_{k+1} f\right)\right]\right\} \tag{5.14}
\end{align*}
$$

where, as usual, $T_{l, l-1} \equiv I$. For the general case, let $Q=\left\{P_{1}, \ldots, P_{s}\right\}$ be some ordered partition of $\{1,2, \ldots, n\}$. Define

$$
\begin{gather*}
\zeta_{j}^{P} f=\partial_{\left\{\psi_{i}\right\}_{i E}} \zeta_{j}^{\phi} f, \quad P \subset\{1, \ldots, n\}  \tag{5.15}\\
T^{Q} f= \\
\sum_{j_{s}=s}^{\infty} \sum_{j_{s}-1<j_{s}}^{\infty} \cdots \sum_{j_{1}<j_{2}} T_{1, j_{1}-1} \cdot \zeta_{j_{1}}^{p_{1}} T_{j_{1}+1, j_{2}-1}  \tag{5.16}\\
\cdot \zeta_{j_{2}}^{p_{2}} \cdots T_{j_{s-1}+1 j_{s}-1} \cdot \zeta_{j_{s}}^{p_{s}} T_{j_{s}+1} f
\end{gather*}
$$

Then we have that

$$
\begin{equation*}
\partial_{\psi_{1}, \ldots, \psi_{n}} T_{\phi} f=\sum_{Q_{n}}^{\prime} T^{Q_{n}} f \tag{5.17}
\end{equation*}
$$

where the primed sum is over all ordered partitions of $\{1, \ldots, n\}$.
(b) The derivatives in (5.12) also satisfy the following: if $N$ is nonnegative, $\phi \in \mathscr{D}_{N+n}, \psi_{1} \in \mathscr{P}_{N+n+1}$ and $f \in C^{N+n}, \partial_{\psi_{1}, \ldots, \psi_{n}} T_{\phi} f$ lies in $C^{N}$ and, for fixed $f$ and $\left\{\psi_{i}\right\}$, is continuous as a function of $\phi$ from $\mathscr{D}_{N+n}$ into $C^{N}$.
(c) The $C^{N}$ norm of the derivative is a polynomial in $|f|_{M}(1 \leqslant M$ $\leqslant N+n)$, in $\left|H_{\psi_{i}}\right|_{M}(1 \leqslant M \leqslant N+n+1)$ and in the variables $1 /[1-$ $\alpha_{1}(\phi)$ ], $\alpha_{M}(\phi)(1 \leqslant M \leqslant N+n)$. [Here $C^{0}=C(\Omega)$.]

We present the estimates needed for the second derivative of the Gibbs state:

$$
\begin{align*}
\left|\partial_{\psi} T_{\phi} f\right|_{\infty} \leqslant & \frac{\|\psi\|_{1}|f|_{1}}{1-\alpha_{1}(\phi)}  \tag{5.18}\\
\left|\partial_{\psi} T_{\phi} f\right|_{1} \leqslant & \frac{1}{1-\alpha_{1}(\phi)}\left\{|f|_{1}\left(\left|H_{\psi}\right|_{2}+\left|H_{\psi}\right|_{1}\left|H_{\phi}\right|_{2}\right)\right. \\
& \left.+\left|H_{\psi}\right|_{1}\left[2|f|_{2}+\alpha_{2}\left(1+\frac{2}{1-\alpha_{1}}\right)|f|_{1}\right]\right\}  \tag{5.19}\\
\left|\partial_{\psi_{1}, \psi_{2}} T_{\phi} f\right|_{\infty} \leqslant & \left|H^{1}\right|_{1}\left|H^{2}\right|_{1}|f|_{1}\left[1-\alpha_{1}(\phi)\right]^{-1}+\left[1-\alpha_{1}(\phi)\right]^{-1} \\
& \left\{\left\|\psi_{1}\right\|_{1}\left(\left|H^{2}\right|_{2}+\left|H^{2}\right|_{1}\left|H_{\phi}\right|_{2}\right)|f|_{1}\left(1-\alpha_{1}\right)^{-1}\right. \\
& +\left(1-\alpha_{1}\right)^{-1}\left\|\psi_{1}\right\|_{1}\left|H^{2}\right|_{1}\left[2|f|_{2}+\alpha_{2}\left(1+\frac{2}{1-\alpha_{1}(\phi)}\right)|f|_{1}\right] \\
& +\left.2\left\|\psi_{1}\right\|\right|_{1} \|\left.\psi_{2}\right|_{1}|f|_{1} \\
& \left.+ \text { the same terms with } \psi_{1} \text { and } \psi_{2} \text { interchanged }\right\} \tag{5.20}
\end{align*}
$$

Proof. The organization of this proof is as follows:
(i) Let $N$ be a nonnegative integer. We show that the sum of the right-hand side of (5.17) lies in $C^{N}$ when $\phi \in \mathscr{D}_{N+n}, \psi_{i} \in \mathscr{P}_{N+1+n}$ and $f \in C^{N+n}$. Moreover, its $C^{N}$ norm is bounded as in part (c) of the lemma. We also indicate the evaluation of the bounds in the right-hand side of (5.18)-(5.20).
(ii) Next we informally derive the formulas (5.16) and (5.17) and then prove part (a) for the first derivative, i.e., $n=1$.
(iii) We prove the whole of part (a), including the continuity in $\phi$, for all $n$. The $\phi$ continuity of part (b) will then follow directly from the discussion in (i) and the lemma will have been proved.
(i) Let $N \geqslant 0$ and recall (3.2) of Theorem 3.2. This contains the annoying term $E^{p}(f)$, which we get rid of by noting that $\sum_{p} E_{n}^{p}(f)=n(1-$ $\left.\alpha_{1}\right)|f|_{n}=\left[\left(1-\alpha_{1}\right) J|f|\right]_{n}$, so that we may replace $J|f|+E^{p}(f)$ in (3.2) by $\alpha_{1} J|f|$. Collecting the estimates in (3.2) and (3.7) for $k \leqslant p$ we see that we
have

$$
\begin{equation*}
\left|T_{k, p} f\right|_{N} \leqslant|f|_{N}+(K|f|)_{N}, \quad p \geqslant k \tag{5.21}
\end{equation*}
$$

where $K$ is zero on or above its diagonal and whose entries are polynomials in $\alpha_{1}, \ldots, \alpha_{N}$ and $1 /\left(1-\alpha_{1}\right)$.

Now consider $T^{Q}$ as in (5.16). By expressing the bounds on $T_{k, p}$ as in (5.21), we place the burden of summability of $T^{Q} f$ onto the $\zeta_{j_{i}}^{P_{t}}$. But they rise to the occasion, thanks to ( 4.27 n ) of Theorem 4.4.

Assume the hypotheses of part (b) of this lemma. Then it follows that the summand in (5.16) lies in $C^{N}$. For, recalling (4.27n), we have (in matrix terminology) that

$$
\begin{equation*}
\left|\xi_{j}^{P} f\right|_{M} \leqslant\left(C^{P} L^{(j)}(f)\right)_{M} \tag{5.22}
\end{equation*}
$$

where

$$
\begin{equation*}
\left(L^{(j)}(f)\right)_{M}=\sum_{\substack{\Lambda \in V_{m-1} \\ j \notin \Lambda}} D_{j \cup \Lambda}(f) \tag{5.23}
\end{equation*}
$$

and $C_{M, m}^{P}$ is a polynomial in $\left|H_{\psi_{i}}\right|_{l},\left|H_{\varphi}\right|_{l}, 1 \leqslant l \leqslant M+1, i \in P$. Now note that we may cast (3.30) of Lemma 3.10 in the form

$$
\begin{equation*}
F_{j, p ; m}(g) \leqslant\left[\left(\alpha_{1} J+K_{1}\right)|g|\right]_{m} \tag{5.24}
\end{equation*}
$$

where $K_{1}$ is a matrix with zeroes on and above its diagonal. If we let

$$
\begin{equation*}
g=\text { expression to the right of } \zeta_{j_{1}}^{P_{1}} \text { in (5.16) } \tag{5.25}
\end{equation*}
$$

then we have

$$
\begin{align*}
\sum_{j_{1} \leqslant j_{2}} \mid \text { summand of RHS }\left.(5.16)\right|_{N} & \leqslant \sum_{j_{1} \leqslant j_{2}}\left[(I+K)\left|\xi_{j_{1}}^{P_{1}} g\right|\right]_{N} \\
& \leqslant \sum_{j_{1} \leqslant j_{2}}\left[(I+K) C^{P_{1}} L^{\left(j_{1}\right)}(g)\right]_{N} \\
& \leqslant\left[(I+K) C^{P_{1} F_{j_{1}, j_{2}} ;} \cdot(g)\right]_{N} \\
& \leqslant\left[(I+K) C^{P_{1}}\left(\alpha_{1} J+K_{1}\right)|g|\right]_{N} \tag{5.26}
\end{align*}
$$

Iterating this procedure and noting that $\sum_{i}\left|P_{i}\right|=n$, it is clear that we have, under the hypotheses of part (b) of the current lemma, that the series for $T_{f} \ell_{f}$ is absolutely summable in the $N$ th seminorm. Thus the right-hand side of (5.16) is in $C^{N}$ itself.

We omit here the evaluation of the estimates (5.18)-(5.20) [the computation of (5.20) was simplified by setting $D_{k}(\cdot) \leqslant 2|\cdot|_{\infty}$ at a convenient point].
(ii) Next we show that the sum (5.17) actually represents the derivative. We do this by induction on the number of derivatives. That the
right-hand side of (5.17) is informally the derivative with respect to $\psi_{n}$ of the (informal) derivative $\partial_{\psi_{1}, \ldots, \psi_{n-1}} T_{\phi} f$ is simply a question of counting ordered partitions of $[1, n]$ in terms of those of $[1, n-1]$, as in Section 4.

Following Gross ${ }^{(3)}$ let us show that (5.13) holds true, i.e., that the first $C(\Omega)$ derivative exists (for $\phi \in \mathscr{D}_{1}, \psi \in \mathscr{P}_{2}$ and $f \in C^{1}$ ). We use a standard theorem on interchanging limits and differentiation. Let $g$ be a cylinder function. Set $\Lambda_{\phi}(f)=\operatorname{RHS}$ (5.13). It is clear that $\Lambda_{\phi}(g)$ is a finite sum and is the derivative of $T_{\phi} g$ (which is a finite product of operators acting on $g$ ) by the product rule and the differentiability of the $\zeta$ 's as in Section 4.1. Moreover, by Theorem 4.4, $\phi \rightarrow A_{\phi}(g)$ is continuous from $\mathscr{D}_{1}$ into $C(\Omega)$.

Now suppose $g_{k}$ are cylinder functions converging to $f$ in $C(\Omega)$ and $C^{1}$ norms. Fix $\phi$ and $r$ such that $\alpha_{1}(\phi)<r<1$. Recall that definition (5.10) of $B_{r}^{1} \cdot B_{r}^{1}$ is open by the continuity of $\alpha_{1}$ so that there exists a $\delta>0$ such that $\phi+v \psi \in B_{r}{ }^{1}$ whenever $|v| \leqslant \delta$ and such that $A_{\phi+v \psi} g_{k}$ converge to $A_{\phi+v u} f$ in $C(\Omega)$ norm, uniformly in $v \in[-\delta, \delta]$. This last fact follows from the estimate (5.18).

Thus $A_{\phi} f$ is indeed the derivative of $T_{\phi} f$. Moreover, $\phi \rightarrow \partial_{\psi} T_{\phi} f$ is continuous on $\mathscr{D}_{1}$. To see this, note that by the bound on $\left|A_{\phi} g\right|_{\infty}$ (in this case, $\left.\left[1-\alpha_{1}(\phi)\right]^{-1}|g|_{1}\|\psi\|_{1}\right),\left|A_{\phi} g_{n}-A_{\phi} f\right|_{\infty}$ converges to zero uniformly in $\phi$ on $B_{r}^{1}, 0<r<1$. Since the $A_{\phi} g_{n}$ are continuous on $B_{r}^{1}$, so is $A_{\phi} f$.
(iii) Now let $n$ be a natural number, $f \in C^{n}, \phi \in \mathscr{D}_{n}, \psi_{i} \in \mathscr{P}_{n+1}$ for $1 \leqslant i \leqslant n$. Make the induction hypothesis that for some $m \leqslant n$, $\partial_{\psi_{1}, \ldots, \psi_{m-1}} T_{\phi}$ fexists, is bounded and continuous, and satisfies (5.17) (with $n \rightarrow m$ there). Let $A_{\phi}^{(n)} f=\operatorname{RHS}$ (5.17) and let $\left\{g_{k}\right\}$ be a sequence of cylinder functions tending to $f$ in $C(\Omega)$ and $C^{n}$ (and therefore in $C^{m}$ ). Then $A_{\phi}^{(m-1)} g_{k}$ is a finite sum for each $k$. By Theorem 4.4 we have existence and $\phi$ continuity of the derivatives with respect to $\psi_{m}$ of $\zeta_{j}^{P g}$, and continuity of $T_{\phi, k, p} g$ (again, note that continuity in $\mathscr{P}_{1}$ implies continuity in $\mathscr{P}_{m+1}$ ). By the finiteness of the sums involves, $A_{\phi}^{(m)} g_{k}=\partial_{\psi_{m}} A_{\phi} g_{k}$. Again, $A_{\phi}^{(m-1)} g_{k}$ $\rightarrow A_{\phi}^{(m-1)} f$ in $C(\Omega)$, uniformly in $\phi \in B_{r}^{n}$ for each $r$ satisfying $\alpha_{1}(\phi)<r<1$, $\alpha_{2}(\phi), \ldots, \alpha_{n}(\phi)<1 /(1-r)$ and such that $A_{\phi+\tau \psi_{m}}^{(m)} g_{k} \rightarrow A_{\phi+u \psi_{m}}^{(m)} f$ in $C(\Omega)$, uniformly in $v$ (for suitably restricted $v$ ). Both of these facts follow from the estimations in (i) above [as expressed in part (c) of the lemma]. Thus we conclude that $A_{\varphi}^{(m)} f$ is the $m$ th derivative. Moreover, as in (i) above, $\left|A_{\phi}^{(m)}\left(g_{k}-f\right)\right|_{\infty}$ converges to zero uniformly in $\phi$ for $\phi \in B_{r}^{N}$ and any $r \in(0,1)$, so that continuity in $\phi$ of the derivatives is assured. By the results of (ii) above, induction is complete and we have proved part (a) and once we have established the remaining portion of part (b) we will have proved the lemma.

What remains is to show that the $C(\Omega)$ derivatives are continuous from $\mathscr{D}_{N+n}$ into $C^{N}$. Using cylinder functions as in the above arguments, for example, the estimates in part (c) [already derived in (i) above] justify this conclusion.

### 5.5. Derivatives of $T_{\phi}$ as Operators on $C^{N}$

Let $\pi$ be the canonical map taking $C^{N}$ to $\tilde{C}^{N}=C^{N} /$ constants. $\tilde{C}^{N}$ is a Banach space in the norm $\sum_{M=1}^{N}|\cdot|_{M}$. An operator $H$ on $C^{N}$ which annihilates constants is then uniquely identified with an operator $\tilde{H}$ on $\tilde{C}^{N}$ through $\tilde{H} \cdot \pi=\pi \cdot H$. We will drop the tilde in what follows. In particular, if $H:{\underset{\sim}{C}}^{N} \rightarrow C(\Omega)$ annihilates constants, we can think of it as an operator from $\tilde{C}^{N}$ to $C(\Omega)$ through $(H[f])(s)=H f(s)$.

Since $\tilde{C}^{N}$ is a Banach space we can define the notion of Gateaux derivatives of functions into $\tilde{C}^{N}$ and the question arises as to whether $\partial_{\psi} T_{\phi}(f)$, which annihilates constants, is in the $\tilde{C}^{N}$ sense the derivative of some curve in $\tilde{C}^{N}$. The obvious candidate for its antiderivative is $u$ $\rightarrow\left(T_{\phi+w \psi}-T_{\phi}\right)[f]$. The question becomes: is

$$
\begin{equation*}
\lim _{u \rightarrow 0} \sum_{M=1}^{N}\left|\frac{1}{u}\left(T_{\phi+u \psi} f-T_{\phi} f\right)-\partial_{\psi} T_{\phi} f\right|_{M}=0 \tag{5.27}
\end{equation*}
$$

for each $f \in C^{N}$, if $\partial_{\psi} T_{\phi} f$ is the already defined $C(\Omega)$ derivative? The answer is yes and may be seen as follows:

Suppose $\phi \in \mathscr{D}_{N+1}, \psi \in \mathscr{P}_{N+2}$ and $f \in C^{N+1}$. Then for $M \leqslant N$,

$$
\begin{align*}
\left|\frac{1}{u}\left(T_{\phi+u \psi} f-T_{\phi} f\right)-\partial_{\psi} T_{\phi} f\right|_{M} & \left.=\left\lvert\, \frac{1}{u} \int_{0}^{u} d v \partial_{\psi} T_{\phi+v \psi} f-\partial_{\psi} T_{\phi} f\right.\right)\left.\right|_{M} \\
& \leqslant \frac{1}{|u|} \int_{0}^{u} d v\left|\partial_{\psi} T_{\phi+v \psi} f-\partial_{\psi} T_{\phi} f\right|_{M} \tag{5.28}
\end{align*}
$$

The first step uses the fundamental theorem of the calculus and the second uses Minkowski's inequality: the integrand is integrable by continuity as in Lemma 5.4(b). But by this continuity, we have that the limit as $u \rightarrow 0$ is zero (use the other part of the fundamental theorem).

A similar result holds for the derivatives of $\zeta_{j}^{\phi} f$ and we see that all the results on existence, boundedness, and continuity of derivatives continue to hold in the setting of $\tilde{C}^{N}$.

### 5.6. Lemma. Existence and Continuity of $\left(I-T_{\phi}\right)^{-1}$, and Its Derivatives, on $C^{N}$

(a) If $\phi \in \mathscr{D}_{N}$, the operator $I-T_{\phi}$ on $\tilde{C}^{N}$ has a bounded inverse, $S_{\phi}=\left(I-T_{\phi}\right)^{-1}$. For each fixed $F \in \tilde{C}^{N}, \phi \rightarrow S_{\phi} F: \mathscr{D}_{N} \rightarrow \tilde{C}^{N}$ is continuous. We have in particular the bounds

$$
\begin{align*}
& \left|S_{\phi}[f]\right|_{1} \leqslant \frac{|f|_{1}}{1-\alpha_{1}(\phi)}  \tag{5.29}\\
& \left|S_{\phi}[f]\right|_{2} \leqslant \frac{|f|_{2}}{1-\alpha_{1}(\phi)}+\alpha_{2}(\phi) \frac{|f|_{1}}{\left[1-\alpha_{1}(\phi)\right]^{3}} \tag{5.30}
\end{align*}
$$

(b) If $\phi \in \mathscr{D}_{N+1}, \psi \in \mathscr{P}_{N+2}$ and $F \in \tilde{C}^{N+1}$, the function $u \rightarrow$ $S_{\varphi+u \psi} F: R^{1} \rightarrow \tilde{C}^{N}$ is differentiable at $u=0$, with derivative

$$
\begin{equation*}
\left(\partial_{\psi} S\right)_{\phi} F=S_{\phi} \cdot\left(\partial_{\psi} T\right)_{\phi} \cdot S_{\phi} F \tag{5.31}
\end{equation*}
$$

where $\partial_{\psi} T_{\phi}$ is interpreted as an operator on $\tilde{C}^{N+1}$. [By part (a), $\phi$ $\rightarrow \partial_{\psi} S_{\phi} F: \mathscr{\mathscr { D }}_{N+1} \rightarrow \tilde{C}^{N}$ is continuous.]

Proof. (a) Consider first the sum $\sum_{k=0}^{\infty}\left|T^{k} f\right|_{N}$. By (3.5) we have

$$
\begin{equation*}
|T f| \leqslant\left(\alpha_{1} I+\bar{K}\right)|f|, \quad f \in C^{N}, \quad \phi \in D_{N} \tag{5.32}
\end{equation*}
$$

where the $N \times N$ matrix $\bar{K}$ is zero on and above its diagonal. It follows that

$$
\begin{align*}
\sum_{k=0}^{\infty}\left|T^{k} f\right|_{N} & \leqslant \frac{1}{1-\alpha_{1}}\left[\exp \left(\frac{1}{1-\alpha_{1}} \bar{K}\right)|f|\right]_{N} \\
& =\frac{1}{1-\alpha} \sum_{m=0}^{N-1} \frac{1}{\left(1-\alpha_{1}\right)^{m}}\left[\bar{K}^{m}|f|\right]_{N} \tag{5.33}
\end{align*}
$$

Since the entries of $K$ are polynomials in $\left(1-\alpha_{1}\right)^{-1}, \alpha_{2}, \ldots, \alpha_{N}$, the sum converges uniformly in $\phi \in B_{r}^{N}, 0<r<1$, so that it is continuous in $\phi$ on $\mathscr{D}_{N}$.

Thus we may define $S_{\phi}=\left(I-T_{\phi}\right)^{-1}$ by

$$
\begin{equation*}
S_{\phi}[f]=\sum_{k=0}^{\infty} \pi\left(T_{\phi}^{k} f\right), \quad \phi \in \mathscr{D}_{N}, \quad f \in C^{N} \tag{5.34}
\end{equation*}
$$

as a linear, bounded, and continuous operator on $\tilde{C}^{N}$.
When $N=1, K=0$ so that we have (5.29). When $N=2$,

$$
K=\left(\begin{array}{cc}
0 & 0  \tag{5.35}\\
\frac{\alpha_{2}}{1-\alpha_{1}} & 0
\end{array}\right)
$$

so that we have (5.30).
(b) Here we take direct advantage of the fact that the alleged derivatives in the right-hand side of (5.31) is already well defined and continuous. Let $f \in F$ so that $f \in C^{N+1}$ and put

$$
\begin{equation*}
s_{n}(\phi)=\sum_{k=0}^{n} \pi\left(T_{\phi}^{k} f\right) \tag{5.36}
\end{equation*}
$$

Then by part (a), $\tilde{C}^{N}-\lim _{n \rightarrow \infty} s_{n}(\phi)=S_{\phi} F$. It suffices to show that (i) the $\tilde{C}^{M}$ derivatives $(1 \leqslant M \leqslant N) s_{n}^{\prime}(\phi)=\left.(d / d u) s_{n}(\phi+u \psi)\right|_{n=0}$ exist and are continuous from $\mathscr{D}_{N+1}$ to $\tilde{C}^{N}$; (ii) $s_{n}^{\prime}(\phi)$ converge to $S_{\phi} \cdot \partial_{\psi} T_{\phi} \cdot S_{\phi} F$ on $\mathscr{D}_{N+1}$ and for each $r$ in $(0,1),\left\{s_{n}^{\prime}(\phi)\right\}_{n, \phi}$ is uniformly bounded for $1 \leqslant n \leqslant \infty$ and $\phi \in B_{r}^{N}$. For then, since $v \rightarrow S_{\phi+v \psi} \cdot \partial_{\psi} T_{\phi+o \psi} \cdot S_{\phi+v \psi} F: R^{1}$ $\rightarrow \tilde{C}^{N}$ is continuous (for small $v$ ) by part (a) of this lemma and Lemma 5.4,
we have

$$
\begin{align*}
S_{\phi+u \psi} F-S_{\phi} F & =\lim _{n \rightarrow \infty}\left[s_{n}(\phi+u \psi)-s_{n}(\phi)\right] \\
& =\lim _{n \rightarrow \infty} \int_{0}^{u} d v s_{n}^{\prime}(\phi+v \psi) \\
& =\int_{0}^{u} d v S_{\phi+v \psi} \cdot \partial_{\psi} T_{\phi+v \psi} \cdot S_{\phi+u \psi} F \tag{5.37}
\end{align*}
$$

The second equality follows from the fundamental theorem and (i) above and third, by means of Lebesgue's dominated convergence theorem, from (ii). Finally, the continuity of the last integrand above and another application the fundamental theorem yield the result (5.31).
(i) We have, from (5.36),

$$
\begin{equation*}
\frac{S_{n}(\phi+u \psi)-s_{n}(\phi)}{u}=\sum_{k=1}^{n} \pi\left[\sum_{j=0}^{k-1} T_{\phi+u \psi}^{k-j-1}\left(\frac{T_{\phi+u \psi}-T_{\phi}}{u}\right) T_{\phi}^{j} f\right] \tag{5.38}
\end{equation*}
$$

For each summand, consider

$$
\begin{align*}
&\left|\frac{1}{u} T_{\phi+u \psi}^{k-j-1}\left(T_{\phi+u \psi}-T_{\phi}\right) T_{\phi}^{j} f-T_{\phi}^{k-j-1} \partial_{\psi} T_{\phi} \cdot T_{\phi}^{j} f\right|_{N} \\
& \leqslant\left|T_{\phi+u \psi}^{k-j-1}\left[\frac{1}{u}\left(T_{\phi+u \psi}-T_{\phi}\right)-\partial_{\psi} T_{\phi}\right] T_{\phi}^{j} f\right|_{N} \\
&+\left|\left(T_{\phi+u \psi}^{k-j-1}-T_{\phi}^{k-j-1}\right) \partial_{\psi} T_{\phi} \cdot T_{\phi}^{j} f\right|_{N} \tag{5.39}
\end{align*}
$$

and consider its limit as $u$ tends to zero. Now, in the last term, $\partial_{\psi} T_{\phi} \cdot T_{\phi}^{j} f$ $\in C^{N}$ (Lemmas 5.3 and 5.4). Moreover, $T_{\phi}$ (and $T_{\phi}^{k-j-1}$ ) is, as an operator on $C^{N}$, strongly continuous for $\phi \in \mathscr{D}_{N}$ (Lemma 5.3). Since the injection $\mathscr{D}_{N+1} \rightarrow \mathscr{D}_{N}$ is itself continuous, $T_{\phi}$ strongly continuous on $\mathscr{D}_{N+1}$, so that the last term tends to zero.

Let $r<1, \phi \in B_{r}^{N}$ and $g=T_{\phi}^{j} f$. Then $g \in C^{N+1}$ and the second last term of (5.39) is majorized by

$$
\begin{equation*}
[C(r)] \sum_{M=1}^{N}\left|\frac{1}{u}\left(T_{\phi+u \psi} g-T_{\phi} g\right)-\partial_{\psi} T_{\phi} g\right|_{M} \tag{5.40}
\end{equation*}
$$

where $C(r)<\infty$ is independent of $u$ (by the bounds on $T_{\phi}$, Lemma 5.3). By the remarks of the last section (5.5), this goes to zero with $u$ and we have that for each $n$,

$$
\begin{equation*}
s_{n}^{\prime}(\phi)=\sum_{k=1}^{n} \pi\left(\sum_{j=0}^{k-1} T_{\phi}^{k-j-1} \cdot \partial_{\psi} T_{\phi} \cdot T_{\phi}^{j} f\right) \tag{5.41}
\end{equation*}
$$

exists and is continuous from $\mathscr{D}_{N+1}$ to $\tilde{C}^{N}$. The existence and continuity of these derivatives for the $M$ th norms, $1 \leqslant M \leqslant N$, follows in the same manner.
(ii) We have from (5.41) that

$$
\begin{equation*}
\left|s_{n}^{\prime}(\phi)\right|_{N} \leqslant \sum_{j=0}^{\infty} \sum_{m=0}^{\infty}\left|\pi\left(T_{\phi}^{m} \cdot \partial_{\psi} T_{\phi} \cdot T_{\phi}^{j} f\right)\right|_{N} \tag{5.42}
\end{equation*}
$$

By (5.33) and Lemma 5.4 it is clear that $\left|s_{n}^{\prime}(\phi)\right|_{N}$ is uniformly bounded for all $n$ and all $\phi \in B_{r}^{N}$, for each $r<1$. The same is true for $\left|s_{n}^{\prime}(\phi)\right|_{M}$, $1 \leqslant M \leqslant N$. Finally, it is clear that $s_{n}^{\prime}(\phi)$ converge to $S_{\phi} \cdot \partial_{\psi} T_{\phi} \cdot S_{\phi}[f]$ in $\tilde{C}^{N}$ and we are done.

### 5.7. Proof of Theorem 5.1

We will use induction on the number of derivatives. We follow Ref. 3 in establishing the theorem for the first derivative. Let $f \in C^{1}, \phi \in \mathscr{D}_{1}$ and $\psi \in \mathscr{P}_{2}$. Vasershtein's formula says that

$$
\begin{equation*}
\sigma_{\phi}(f)=C^{0}-\lim _{n \rightarrow \infty} T_{\phi}^{n} f \tag{5.43}
\end{equation*}
$$

where $C^{0}=C(\Omega)$. By arguments similar to those used in proving Lemma $5.6(\mathrm{~b})$, it is clear that

$$
\begin{equation*}
\left(\partial_{\psi} T^{n}\right)_{\phi} f=\sum_{j=0}^{n-1} T_{\phi}^{n-j-1} \cdot \partial_{\psi} T_{\phi} \cdot T_{\phi}^{j} f \tag{5.44}
\end{equation*}
$$

where now the derivatives are taken in the $C^{0}$ sense. Also, this derivative is continuous in $\phi$ for $\phi$ in $\mathscr{D}_{1}$. Now $\left|T_{\phi} g\right|_{\infty} \leqslant|g|_{\infty}$ and $\left|T_{\phi} f\right|_{1} \leqslant \alpha_{1}(\phi)|g|_{1}$ for $\phi \in \mathscr{D}_{1}$, so that, using (5.18),

$$
\begin{equation*}
\left|\left(\partial_{\psi} T^{n}\right)_{\phi} f\right|_{\infty} \leqslant \sum_{j=0}^{\infty} \frac{\|\psi\|_{1}\left|T^{j} f\right|_{1}}{1-\alpha_{1}(\phi)} \leqslant \frac{\|\psi\|_{1}|f|_{1}}{\left[1-\alpha_{1}(\phi)\right]^{2}} \tag{5.45}
\end{equation*}
$$

Thus the series in (5.44) is absolutely convergent. Put

$$
C_{n, j}= \begin{cases}T_{\phi}^{n-j-1} \partial_{\psi} T_{\phi} T_{\phi}^{j} f, & 0 \leqslant j \leqslant n-1  \tag{5.46}\\ 0, & j \geqslant n\end{cases}
$$

Then $\left(\partial_{\psi} T^{n}\right)_{\phi} f=\sum_{j=0}^{\infty} C_{n, j}$. Since this series is absolutely convergent, uniformly in $n$, and since by (5.43), $\lim _{n \rightarrow \infty} C_{n, j}=\sigma_{\phi}\left(\partial_{\psi} T_{\phi} T_{\phi}^{j} f\right)$, we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left(\partial_{\psi} T^{n}\right)_{\phi} f=\sum_{j=0}^{\infty} \sigma_{\phi}\left(\partial_{\psi} T_{\phi} T_{\phi}^{j} f\right)=\sigma_{\phi}\left(\partial_{\psi} T_{\phi} S_{\phi}[f]\right) \tag{5.47}
\end{equation*}
$$

where we have used the convergence of $\sum T^{j}$ and the boundedness and linearity of $\sigma_{\phi} \cdot \partial_{\psi} T_{\phi}$ on $\tilde{C}^{1}$.

Now $\phi \rightarrow \partial_{\psi} T_{\phi} \cdot S_{\phi}[f]: \mathscr{D}_{1} \rightarrow C^{0}$ is continuous. But so is $\phi \rightarrow \sigma_{\phi}(g)$ : $\mathscr{D}_{1} \rightarrow R^{1}$ for each $g \in C(\Omega)$. We may see this from Vasershtein's proof of Dobrushin's uniqueness theorem (Ref. 23, Section 3.12), from which we
may extract the fact that for $g \in C^{1}$,

$$
\begin{equation*}
\left|T_{\phi}^{n} g-\sigma_{\phi}(g)\right|_{\infty} \leqslant \sup \left(T_{\phi}^{n} g\right)-\inf \left(T_{\phi}^{n} g\right) \leqslant\left|T_{\phi}^{n} g\right|_{1} \leqslant \alpha_{1}^{n}(\phi)|g|_{1} \tag{5.48}
\end{equation*}
$$

so that the convergence of $T_{\phi}^{n} g$ to $\sigma_{\phi}(g)$ is uniform on each $B_{r}^{1}$. Thus $\phi \rightarrow \sigma_{\phi}(g)$ is continuous on $\mathscr{D}_{1}$ for $g$ in the $C(\Omega)$-dense set $C^{1}$ and hence it is continuous for all $g$ in $C(\Omega)$.

But this means that $\phi \rightarrow \sigma_{\phi}\left(\partial_{\psi} T_{\phi} \cdot S_{\phi}[f]\right)$ is continuous from $\mathscr{D}_{1}$ into the reals. We may now use the fundamental theorem of the calculus and the dominated convergence theorem to see that, for $u$ small enough,

$$
\begin{align*}
\sigma_{\phi+u \psi}(f)-\sigma_{\phi}(f) & =\lim _{n \rightarrow \infty} \int_{0}^{u} d v\left(\partial_{\psi} T^{n}\right)_{\phi+\imath \psi}(f) \\
& =\int_{0}^{u} d v \sigma_{\phi+v \psi}\left(\partial_{\psi} T_{\phi+v \psi} \cdot S_{\phi+v \psi}[f]\right) \tag{5.49}
\end{align*}
$$

By the continuity of the integrand, we have again from the fundamental theorem that $\sigma_{\dot{\phi}}(f)$ is indeed differentiable, with the expected derivative. Note that (5.5) is fully justified.

Now proceed with the induction hypothesis that the theorem is true for some $N$. Let $\phi \in \mathscr{D}_{N+1}, \psi \in \mathscr{P}_{N+2}$ and $f \in C^{N+1}$. By hypothesis, the $N$ th derivative in directions $\psi_{1}, \ldots, \psi_{N}$ exists, is continuous, and is given by (5.2) with $n=N$ (we consider the $\psi_{i}$ to lie in $\mathscr{P}_{N+2}$ ). (5.2) is of the form

$$
\begin{equation*}
\partial_{\left[\psi \mid l N_{i}^{\prime}, \phi\right.}(f)=\sum_{Q_{N}}^{\prime} \sigma_{\phi}\left(f_{Q_{N}}\right) \tag{5.50}
\end{equation*}
$$

where, with $Q$ an ordered partition of $\{1, \ldots, N\}$,

$$
\begin{align*}
& f_{Q}(\phi)=T_{1}^{\prime}(\phi) T_{2}^{\prime}(\phi) \cdots T_{m}^{\prime}(\phi)[f], \quad m=|Q|  \tag{5.51}\\
& T_{i}^{\prime}(\phi) G=\left(\partial_{\left.\left\{\psi_{i}\right\}_{\in \in R_{i}} T\right)_{\phi}} \cdot S_{\phi} G \quad\left(G \text { in some } \tilde{C}^{n}\right)\right. \tag{5.52}
\end{align*}
$$

Thus we have that

$$
\begin{align*}
& \frac{1}{u}\left[f_{Q}(\phi+u \psi)-f_{Q}(\phi)\right] \\
& \quad=\frac{1}{u} \sum_{i=1}^{m} T_{1}^{\prime}(\phi+u \psi) \cdots T_{i-1}^{\prime}(\phi+u \psi)\left[T_{i}^{\prime}(\phi+u \psi)-T_{i}^{\prime}(\phi)\right] \\
& \quad \times T_{i+1}^{\prime}(\phi) \cdots T_{m}^{\prime}(\phi)[f] \tag{5.53}
\end{align*}
$$

(with suitable adjustments for $i=1, m$ ).
From Lemmas 5.4 and 5.6 and Remark 5.5 we have that

$$
\begin{equation*}
T_{l}^{\prime}(\phi): \tilde{C}^{N+1-\sum_{j=1+1}^{m}\left|P_{j}\right|} \rightarrow \tilde{C}^{N+1-\sum_{j=-}^{m}\left|P_{j}\right|} \tag{5.54}
\end{equation*}
$$

boundedly, $i+1 \leqslant l \leqslant m$;

$$
\begin{equation*}
\frac{1}{u}\left[T_{i}^{\prime}(\phi+u \psi)-T_{i}^{\prime}(\phi)\right] T_{i+1}^{\prime}(\phi) \cdots T_{m}^{\prime}(\phi)[f] \tag{5.55}
\end{equation*}
$$

has the limit

$$
\begin{align*}
\left(\partial_{\psi} T_{i}^{\prime}\right)(\phi) \cdot T_{i+1}^{\prime}(\phi) & \cdots T_{m}^{\prime}(\phi)[f] \quad \text { on } \tilde{C}^{N-\sum_{j-1}^{m}\left|P_{j}\right|} \\
T_{l}^{\prime}(\phi+u \psi) & : \tilde{C}^{N-\sum_{l+1}^{m}\left|P_{j}\right|} \rightarrow \tilde{C}^{N-\sum_{l}^{m}\left|P_{i}\right|} \tag{5.56}
\end{align*}
$$

boundedly and is continuous at $u=0$. Hence we may let $u \rightarrow 0$ in (5.53) to obtain the result that the $C(\Omega)$ derivative of $f_{Q}$ exists and is given by

$$
\begin{equation*}
\partial_{\psi} f_{Q}(\phi)=\sum_{i=1}^{m} T_{1}^{\prime}(\phi) \cdots T_{i-1}^{\prime}(\phi) \cdot\left(\partial_{\psi} T_{i}^{\prime}\right)(\phi) T_{i+1}^{\prime}(\phi) \cdots T_{m}^{\prime}(\phi)[f] \tag{5.57}
\end{equation*}
$$

Also, note that, by similar arguments

$$
\begin{equation*}
\partial_{\psi} T_{i}^{\prime}(\phi) G=\partial_{\left(\left\{\psi_{j}\right\}_{j \in p}\right) \cup\{\psi\}} T_{\phi} \cdot S_{\phi} G+\partial_{\left\{\psi_{j}\right\}_{j \in P}} T_{\phi} \cdot S_{\phi} \cdot \partial_{\psi} T_{\phi} \cdot S_{\phi} G \tag{5.58}
\end{equation*}
$$

from (5.31). Now

$$
\begin{align*}
\sigma_{\phi+u \psi}\left[f_{Q}(\phi-u \psi)\right]-\sigma_{\phi}\left[f_{Q}(\phi)\right]= & \left\{\sigma_{\phi+u \psi}\left[f_{Q}(\phi)\right]-\sigma_{\phi}[Q(\phi)]\right\} \\
& +\sigma_{\phi+u \psi}\left[f_{Q}(\phi+u \psi)-f_{Q}(\phi)\right] \tag{5.59}
\end{align*}
$$

In the last term, $\sigma_{\phi+u \psi}(\cdot)$ is continuous in $u$ [since $\phi \rightarrow \sigma_{\phi}(g)$ is continuous on $\mathscr{D}_{1}$ for each $g \in C(\Omega)$, it is also so on $\mathscr{D}_{N+1}$ ]. Hence we conclude, using (5.50), (5.57), and (5.58) that the $(N+1)$ th derivative exists and equals the right-hand side of (5.2) with $n=N+1, \psi=\psi_{N+1}$. Continuity in $\phi$ follows from that of the various constituents, and our induction is complete. The boundedness remarks in the second paragraph of Section 5.1 follow from Lemmas 5.4 and 5.6 and the proof of the theorem is complete.

The bound (5.8) is obtained by applying (5.18), (5.19), (5.20), (5.29), and (5.30) to (5.6).

### 5.8. Corollary: Differentiability of the Pressure

Let $L=Z^{\nu}$. If $N \geqslant 2$, the pressure is $N$ times continuously Gateaux differentiable in $\hat{\mathscr{P}}_{N}$ directions on $\hat{\mathscr{D}}_{N-1}$ (the caret denoting translational invariance). The $N$ th derivative at $\phi \in \hat{\mathscr{D}}_{N-1}$ in the $\hat{\mathscr{P}}_{N}$ directions $\psi_{1}$, $\ldots, \psi_{N}$ is bounded in absolute value by a polynomial in

$$
\begin{aligned}
& \frac{1}{1-\alpha_{1}(\phi)}, \alpha_{M}(\phi)(1 \leqslant M \leqslant N-1) ; \quad\left\|\psi_{N}\right\|_{M}(1 \leqslant M \leqslant N-1) \\
& \left|H_{\phi}\right|_{M}(1 \leqslant M \leqslant N) ; \quad \text { and } \quad\left|H_{\psi_{i}}\right|_{M}(1 \leqslant M \leqslant N, 1 \leqslant i \leqslant N-1)
\end{aligned}
$$

The $N$ th derivative of the pressure may be expressed as the series (5.2) with
$n=N-1$ and $f=A_{\psi_{N}}$ there, where, with 0 the origin of $L$,

$$
\begin{equation*}
A_{\psi}=-\sum_{\substack{\Lambda \subset L \\ 0 \in \Lambda}}|\Lambda|^{-1} \psi(\cdot \mid \Lambda) \tag{5.60}
\end{equation*}
$$

Proof. We mentioned in Section 1.1 that on $\hat{\mathscr{D}}_{1}$ the pressure $P$ is continuously Gateaux differentiable in $\hat{\mathscr{F}}_{2}$ directions $\psi$, with

$$
\begin{equation*}
\partial_{\psi} P(\phi)=\sigma_{\phi}\left(A_{\psi}\right) \tag{5.61}
\end{equation*}
$$

The corollary follows from Theorem 5.1 upon observing that, as in Section 2.5, $A_{\psi} \in C^{M}$ for $\psi \in P_{M}$.

We have, for the first derivative, from (5.61) that

$$
\begin{equation*}
\left|\partial_{\psi} P(\phi)\right| \leqslant\|\psi\|_{1} \tag{5.62}
\end{equation*}
$$

The second and third derivatives may also be estimated by means of (5.7), (5.8), (5.61), and (2.21). For $N=2$, for example, we have Gross' result that

$$
\begin{equation*}
\left|\partial_{\psi, \psi_{1}} P(\phi)\right| \leqslant \frac{2\|\psi\|_{1}\|\psi\|_{1}}{\left(1-\alpha_{1}(\phi)\right)^{2}} \tag{5.63}
\end{equation*}
$$

For $N=3$ we may use (5.8): here $\left|A_{\psi}\right|_{2} \leqslant 2\|\psi\|_{2}$.

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